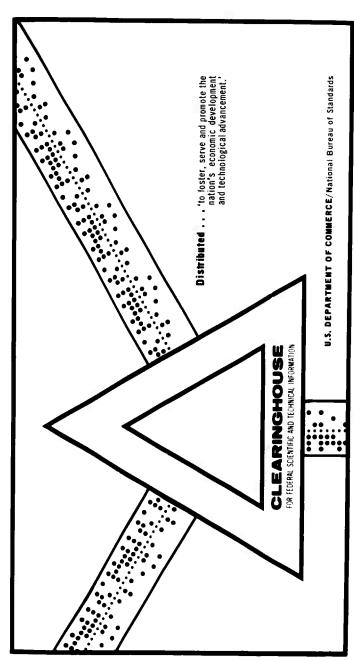
PROPELLER-SHAFT THRUST BEARING ANALYSIS-PHASE

B. Sternlicht, et al

General Electric Company Schenectady, New York

May 1959



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by

B. Sternlicht

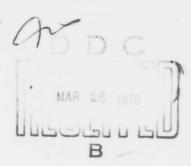
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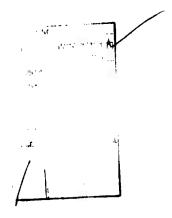
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IMPORMATION PREPARED FOR Medium Steam Turbine Generator and Gear Department	
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2	25 x 12-1/2	120 and 240				Per Fig. 4
3	31 x 15-1/2	180 and 320				Per Fig. 4
4	37 x 18-1/2	180 and 320				Per Fig. 4
5	39 x 19-1/2	150 and 200				Per Fig. 4
6	41 x 20-1/2	100 and 200				Per Fig. 4
7	45 x 22-1/2	100 and 170			50	Per Fig. 4
8	50 x 25	100 and 170				Per Fig. 4
9	26 x 17-1/2	160	8	0.113		Per Fig. 47
10	31 x 16-1/2	320	8	0. 142	51.7	Per Fig. 4
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BACKGROUND AND SCOPE

In 1958 the General Engineering Laboratory made a study of propeller shaft thrust bearing operation and reported its findings in Reference 1. Following this study a comprehensive analytical and experimental program was undertaken, for the purpose of extending present understanding of these bearings and in order to provide a body of design information for use in bearing design and selection. This program, like the preceding introductory study, is being performed under a contract awarded by the Bureau of Ships to General Electric Company's Medium Steam Turbine, Generator and Gear Department.

The program is divided into three phases as follows:

- Phase I: Investigate analytically the performance of propeller shaft thrust bearings using the existing Reynolds-Energy Method of solution to provide data necessary in design and selection of these bearings.
- Phase II: Extend existing analytical techniques for propeller shaft thrust bearings by including a numerical method of solution of the Elasticity Equation. Review, and where necessary, modify the design data obtained in Phase I, so as to include the effects of pad distortion caused by pressure distribution and thermal gradients.
- Phase III: Instrument thrust bearings on two U. S. Navy ships and obtain experimental data on the performance of these bearings. This data is to be obtained in tests carried out at the time of scheduled sea trials. The thrust bearing performance measurements obtained in these sea trials is to be used for correlation with the design data obtained analytically in Phases I and II.

A fourth phase which included the building of a thrust bearing test stand was contemplated but was not included in the present program, since the findings of the program could be used to determine the features of the stand.

The following is our final report on Phase I.

I INTRODUCTION

Virtually all ships in this country, both merchant and combat, use Kingsbury type tilting pad bearings to transmit the propeller thrust to the hull of the vessel. The geometry of these bearings and the principles on which they operate are well known and are described in most texts on lubrication as well as in the catalogues of Kingsbury Machine Works.

Generally, the bearing pads are centrally pivoted, i.e., the spherical pivot back of each pad is located mid-way between the leading and the trailing edges. Central pivot location is required for reversibility, i.e., for operation under either direction of shaft rotation.

Conventional bearing calculations in which temperature variations in the oil film are neglected and in which a converging wedge is formed by the tilting of a flat pad, fail to predict the load carrying capacity of centrally pivoted bearings. The reason for this is illustrated in Figure 1 (a) which shows the hydrodynamic pressure profile that is generated between flat surfaces separated by fluid film that converges slightly in the direction of motion. Under these conditions, calculations show that the resultant of the hydrodynamic pressures lies downstream of the radial centerline of the pad. Since the reaction to these pressures must pass through the pivot, a moment exists which tends to eliminate the convergence and hence load carrying capacity. However, when the temperature variations in the oil film and the deformation of the pad under load are considered in the analysis, the somewhat paradoxical result obtained above is eliminated. Calculations then show that there is a value of pad inclination (generally other than zero) for which the resultant of the hydrodynamic pressures passes through the central pivot as shown in Figure 1 (b).

As the oil flows through the bearing gap, its temperature rises due to the shearing of the film. This rise in temperature produces a "thermal wedge" action which accounts for part of the load carrying capacity of the bearing (provided that the viscosity and mass density of the lubricant decrease with temperature rise, which is the case for all known oils). Early in the program, calculations were made to determine the magnitude of the thermal wedge effect in a centrally pivoted finite pad. A sector shaped pad of a 31" 8-shoe bearing was analyzed, first with the pivot in optimum position and then with the pivot centrally located. In both cases, the pad was assumed to remain flat and the other operating conditions were:

Speed - 320 RPM
Minimum Film Thickness - 0.001"
Oil - 2190T
Oil Temperature at Pad Inlet - 130°F

The results are shown in Figures 2 (a) and 2 (b). It is seen that the thermal wedge effect allows the flat centrally pivoted pad to carry approximately 56% of the load carried by the pad with optimum pivot. At the same time, the maximum temperature reached with the flat centrally pivoted pads is 25°F higher than that reached in the pad with optimum pivot. Experience, however, suggests that the difference in performance between central and optimum pivot locations is not so severe. It was, therefore, decided at that time that, in order to make a more realistic analysis in Phase I, it should be extended to incorporate a simplified elasticity approach which allows pad deformation to be approximated and included in the calculation. Figure 2 (c) shows the load and maximum temperature of the 31" 8-shoe centrally pivoted bearing pad under the same operating conditions but with pad deformation included. Comparison of Figures 2 (a) and 2 (c) now show that the centrally pivoted pad is capable of carrying approximately 92% of the load carried by the flat pad with optimum pivot. Its maximum temperature is 6°F higher than that of the flat pad with optimum pivot. These results are in better agreement with experimental evidence and the method of analysis which includes a simplified elasticity solution has been used in all succeeding calculations.

(To the extent that pad deformation was included in the Phase I calculations the results presented in this report have anticipated those to be obtained in Phase II. In the latter phase, the Elasticity Equation is more rigorously solved and includes, in addition, thermal deformation of the pad. However, it requires a considerably more elaborate digital computer program. It may be expected that comparison between the two sets of results will suggest modifications of the Phase I approach to yield a simple yet sufficently rigorous method of solution.)

The conflict between the isothermal, flat pad method of solution and experience with centrally pivoted pads has been realized, since the time that Albert Kingsbury accomplished his pioneering work on slider bearing performance (Ref. 2). More recently, interest in the effects of thermal wedge and of pad deformation has resulted in analytical studies of infinitely wide bearings, some of which are reported in References 3, 4 and 5. For the case of the finite bearings, the importance of including the effects of temperature variations in the oil film has been studied by one of the authors of this report and it is explained in Reference 6. To the best knowledge of the authors, the present report is the first published study of finite centrally pivoted pad bearings in which the effects of radial and tangential inclinations, temperature variations in the oil film, and pad deformation are all considered. The results obtained have shown good agreement with experience. They have indicated that pad deformations are of the order of the minimum film thicknesses and they have explained such test results as:

bearing failures caused by high pad temperatures.

- 2. occurrence of bearing failures in the vicinity of the pivot.
- 3. insensitivity of trailing edge film thicknesses at high loads.

In order to make the Phase I study as complete as possible, approximately 70% more cases were analyzed than were called for in the contract for this phase. In all, 262 operating points were calculated. At each operating point, the values of radial and tangential pad inclination which satisfied equilibrium of moments were obtained using a trial and error procedure. This procedure required an average of 5 solutions of the Reynolds and Energy Equations for each operating point, so that the total number of solutions exceeded 1300.

The studies were conducted as follows:

- 1. Eight standard bearings were analyzed which scanned the range of present day propeller shaft bearing sizes (19" O. D. to 50" O. D.) and propeller speeds (100 R. P. M. to 320 R. P. M.). Each bearing was analyzed at two speeds and with 6, 8 and 10 pad geometries. Calculations were made at three values of minimum film thicknesses, at each speed and geometry. These calculations have yielded the value and location of the minimum film thickness, the temperature and pressure distributions, the oil flow and horsepower loss as functions of bearing size, number of pads, unit load and speed. In particular, they have shown the optimum number of pads as a function of bearing size, unit load and speed.
- 2. The ahead bearing of DD933 (U. S. S. Barry) was analyzed at the full speed ahead conditions. Its astern bearing was similarly analyzed at full speed astern condition. (The U. S. S. Barry was earlier selected by the Bureau of Ships to be the first ship for sea trial thrust bearing tests under Phase III of the program. The thrust bearings of the starboard shaft of this ship were instrumented and the tests at sea have just been completed.)
- The ahead bearing of DL1 (U.S.S. Norfolk) was analyzed under full speed ahead operation. This bearing was selected for analysis because of the past history of several successive failures.
- A 31" O. D. x 15-1/2" I. D. bearing was extensively analyzed in order to investigate the effects of pad thickness and radial pivot location on bearing performance.
- 5. A 31" O. D. x 15-1/2" I. D. and the 39" O. D. x 19-1/2" I. D. bearing were further analyzed to determine the effect of pad inlet oil temperature on bearing performance. In particular the effect of pad inlet temperature on load carrying capacity and maximum temperature were investigated.

- 6. Additional bearing sizes ranging up to 100" O. D. were analyzed to investigate the relationship between bearing size, pad thickness and unit loading.
- 7. A 51-1/2" O. D. x 32" I. D. bearing with 10 and 12 shoe geometries was analyzed at 200 R. P. M. and at 400 R. P. M. These analyses were made under separate contract with General Electric Company's Medium Steam Turbine, Generator and Gear Department who authorized their inclusion in the present report. They are of interest because the upper speed is quite high and the results illustrate some of the thrust bearing operating characteristics that will be encountered as propeller speeds are raised.

II ANALYSIS AND METHOD OF CALCULATION

The important considerations in thrust bearing analysis are:

- 1. Pressure distribution and hence load carrying capacity
- 2. Temperature distribution
- 3. Location of the center of pressure
- 4. Oil flow
- 5. Horsepower loss

all as functions of the bearing geometry, film shape and speed.

In this section, the equations from which these quantities can be calculated are given. The film shape which includes the effects of pad inclinations and deformation is discussed, as are the groove mixing temperature and the viscosity-temperature relation. Before proceeding to these, however, it is necessary to point out here the principal limitations of the analysis.

- 1. The analysis applies only to steady state conditions. It does not supply any information on the transient conditions that occur during start up and shut down. It also does not apply to dynamic load conditions (such as crash ahead and crash astern) when relative axial motion between the runner and the bearing introduces squeeze film effects.
- 2. Laminar conditions prevail in the oil film. Actually the Reynolds Number in present day propeller shaft thrust bearings is small enough for this condition to be satisfied under steady state operation. This is illustrated by the following calculation for an extreme case:

D = 50" N = 320 RPM h = 0.002" \(\mu = 1 \times 10^{-6} \text{lb.-sec.}^2/\text{in.}^4 \)

= 0.803 \times 10^{-4} \text{lb.-sec.}^2/\text{in.}^4 \)

Umax = 840 \text{in./sec.}

Reynolds Number (Maximum) =
$$\frac{U_{\text{max}} h}{\mu}$$
 = 135

- 3. Oil inertia effects are negligible. At the relatively low surface speeds of propeller shaft thrust bearings, this assumption too is quite valid.
- 4. The fluid is incompressible,
- 5. Variation of the specific heat of the oil with temperature are neglected.

A. Reynolds and Energy Equations and Their Boundary Conditions

The Reynolds Equation describes the hydrodynamic pressures generated in the oil film of a bearing. These pressures separate the bearing and runner surfaces when there is a relative motion between them. For a finite pad, the Reynolds Equation in polar coordinates is (Ref. 7):

$$\frac{\partial}{\partial \mathbf{r}} \left(\frac{\mathbf{r} \mathbf{h}^3}{\mu} \frac{\partial \mathbf{p}}{\partial \mathbf{r}} \right) + \frac{\partial}{\partial \mathbf{r}} \left(\frac{\mathbf{h}^3}{\mu \mathbf{r}} \frac{\partial \mathbf{p}}{\partial \theta} \right) = 6 \omega \mathbf{r} \frac{\partial \mathbf{h}}{\partial \theta}$$
 (1)

The boundary conditions that are needed for the solution of this equation arise from the fact that the pressure falls to zero at the pad perimeter.

With the coordinate system shown in Figure 3, the boundary conditions are then:

$$p = p = p = p = 0$$
 (2)
(r, 0) (R-L, θ) (r, θ _T) (R, θ)

Because the oil film may break down in diverging regions in the bearing, it is necessary to impose an additional condition which states that the pad pressures never fall below atmospheric.

In order to include in the analysis the effects of temperature (and hence viscosity) variations in the oil film, the Energy Equation has to be solved together with the Reynolds Equation. The Energy Equation can be written (Ref. 7):

$$\frac{\mu}{h} (\omega r)^{2} + \frac{h^{3}}{12\mu} \left[\frac{\partial p}{r \partial \theta}^{2} + \left(\frac{\partial p}{\partial r} \right)^{2} \right] - C_{p} \rho g J \left[\left(\frac{r \omega h}{2} - \frac{h^{3}}{12\mu} \frac{\partial p}{r \partial \theta} \right) \frac{\partial T}{r \partial \theta} - \frac{h^{3}}{12\mu} \frac{\partial p}{\partial r} \frac{\partial T}{\partial r} \right] = 0 (3)$$

In Equation (3) it is assumed that the oil flow through the clearance space is adiabatic. All the heat generated within the fluid due to fluid shear is considered to be carried away by the mass transfer of the fluid and no heat is gained, or lost through the bearing surfaces. This is a comparatively good assumption, for the heat transfer coefficient at the fluid boundaries is very small. (Reference 8)

The boundary conditions used for the solution of Equation 3 are that

- a) the pad inlet oil is at the groove temperature and
- b) the radial temperature gradient is zero along the inner and outer circumferences to the pad because of the cooling effect of the surrounding oil.

Thus:

With the introduction of the proper film shape, the solutions of Equations (1) and (3) yield the pressure and temperature distributions on the bearing pads.

B. Load Carrying Capacity

The total reaction of each bearing pad and hence the load it carries is given by the integral of the hydrodynamic pressures over the pad area. Thus:

$$W = \int_{\mathbf{R}-\mathbf{L}}^{\mathbf{R}} \int_{0}^{\theta_{\mathrm{T}}} \mathbf{p} \mathbf{r} d\mathbf{r} d\theta$$
 (5)

C. Oil Flow

Oil is introduced into each pad through the clearance space at its leading edge, by the motion of the runner. Part of this oil leaves the clearance space in the same manner from the trailing edge. The remaining part of the oil is forced out from all edges by the pressure gradients that are built up over the bearing surface. Referring to Figure 3, the oil flow (in G. P. M.) through the four edges is:

Flow into the pad:

$$\frac{231}{60} \quad \mathbf{Q}_{1} = \left(\frac{\mathbf{Q} \cdot \mathbf{rh}}{2} \right)_{\theta=0} \quad \mathbf{dr} - \left(\frac{\mathbf{R}}{\mathbf{R}-\mathbf{I}} \left(\frac{\mathbf{h}^{3}}{\mu \cdot \mathbf{r}} - \frac{\partial \mathbf{p}}{\partial \theta} \right) \right)_{\theta=0} \quad \mathbf{dr}$$
 (6)

Flow out of the pad:

$$\frac{231}{60} \quad Q_2 = \int_0^{\theta T} \left(\frac{h^3 r}{\mu} \frac{\partial p}{\partial r} \right) d\theta$$

$$r = R - L \tag{7}$$

$$\frac{231}{60} Q_3 = \int_{\mathbf{R}-\mathbf{L}} \left(\frac{\omega_{\mathbf{rh}}}{2} \right)_{\theta = \theta_{\mathbf{T}}} d\mathbf{r} + \int_{\mathbf{R}-\mathbf{L}} \left(\frac{\mathbf{h}^3}{\mu_{\mathbf{r}}} \frac{\partial \mathbf{p}}{\partial \theta} \right)_{\theta = \theta_{\mathbf{T}}} d\mathbf{r}$$
(7)

$$\frac{231}{60} Q_4 = \int_{0}^{\theta T} \left(\frac{h^3 r}{\mu} \frac{\partial p}{\partial r} \right) \frac{\partial \theta}{\partial r} d\theta$$

It is seen that the flow through the leading and trailing edges is made of two components. The first of these is independent of the pressure gradients and it is referred to as the "Shear Flow". The second component depends on the pressure gradients and it is referred to as the "Pressure Gradient Flow".

Since there is no relative radial motion between the runner and the bearing pads, there is only "Pressure Gradient Flow" out of the inner and outer circumferential boundaries of the bearing pads.

D. Horsepower Loss

It is assumed that all of the heat generated in the oil film goes into temperature rise of the oil. Thus, the horsepower loss can be computed from the oil flow through the bearing pads and its temperature rise. Thus:

$$HP_{2} = \frac{C_{p} \cap g}{0.707} \int_{0}^{\theta_{T}} \left[\frac{h^{3}r}{\mu} \frac{\partial p}{\partial r} (T - T_{GR}) \right]_{r=R-L} d\theta$$

$$HP_{3} = \frac{C_{p} \cap g}{0.707} \left\{ \int_{R-L}^{R} \left[\frac{\omega rh}{2} (T - T_{GR}) \right]_{\theta=\theta_{T}} \frac{dr}{R-L} \int_{R-L}^{R} \frac{h^{3}}{\partial \theta} \frac{\partial p}{\partial r} (T - T_{GR}) \right\}_{\theta=\theta_{T}} dr$$

$$(8)$$

$$HP_{4} = \frac{C_{p} fg}{0.707} \int_{0}^{\theta T} \left[\frac{h^{3}r}{\mu} \frac{\partial p}{\partial r} (T - T_{GR}) \right]_{r=R} d\theta$$

if the total horsepower loss per pad is

$$HP = HP_2 + HP_3 \quad HP_4 \tag{9}$$

E. Center of Pressure

The point on the pad surface through which the resultant of the hydrodynamic pressures acts is called the center of pressure. Its coordinates are given by:

$$\mathbf{r}_{\mathbf{cp}} = \frac{\left\{ \begin{bmatrix} \mathbf{R} & \boldsymbol{\theta} \mathbf{T} \\ \mathbf{R} - \mathbf{L} & 0 \end{bmatrix} \mathbf{p} \ \mathbf{r}^{2} \cos \boldsymbol{\theta} \ d\mathbf{r} \ d\boldsymbol{\theta} \end{bmatrix}^{2} + \begin{bmatrix} \mathbf{R} & \boldsymbol{\theta} \mathbf{T} \\ \mathbf{R} - \mathbf{L} & 0 \end{bmatrix} \mathbf{p} \ \mathbf{r}^{2} \sin \boldsymbol{\theta} \ d\mathbf{r} \ d\boldsymbol{\theta} \end{bmatrix}^{2} \right\}^{1/2}}{\mathbf{W}}$$

$$\mathbf{\theta}_{\mathbf{cp}} = \frac{1}{16} \left\{ \frac{\mathbf{R}}{\mathbf{R}} - \frac{\mathbf{\theta} \mathbf{T}}{\mathbf{p}} \mathbf{p}^{2} \sin \boldsymbol{\theta} \ d\mathbf{r} \ d\boldsymbol{\theta} \right\}^{2} + \left[\frac{\mathbf{R}}{\mathbf{R}} - \mathbf{L} \cdot 0 \right]^{2} \mathbf{p}^{2} \sin \boldsymbol{\theta} \ d\mathbf{r} \ d\boldsymbol{\theta}$$

$$\left[\frac{\mathbf{R}}{\mathbf{R}} - \mathbf{L} \cdot 0 \right]^{2} \mathbf{p} \mathbf{r}^{2} \sin \boldsymbol{\theta} \ d\mathbf{r} \ d\boldsymbol{\theta}$$

$$\left[\frac{\mathbf{R}}{\mathbf{R}} - \mathbf{L} \cdot 0 \right]^{2} \mathbf{p} \mathbf{r}^{2} \cos \boldsymbol{\theta} \ d\mathbf{r} \ d\boldsymbol{\theta}$$

$$\left[\frac{\mathbf{R}}{\mathbf{R}} - \mathbf{L} \cdot 0 \right]^{2} \mathbf{p} \mathbf{r}^{2} \cos \boldsymbol{\theta} \ d\mathbf{r} \ d\boldsymbol{\theta}$$

$$\left[\frac{\mathbf{R}}{\mathbf{R}} - \mathbf{L} \cdot 0 \right]^{2} \mathbf{p} \mathbf{r}^{2} \cos \boldsymbol{\theta} \ d\mathbf{r} \ d\boldsymbol{\theta}$$

$$\left[\frac{\mathbf{R}}{\mathbf{R}} - \mathbf{L} \cdot 0 \right]^{2} \mathbf{p} \mathbf{r}^{2} \cos \boldsymbol{\theta} \ d\mathbf{r} \ d\boldsymbol{\theta}$$

F. Film Shape

Under the hydrodynamic pressures and the pivot reaction, each pad bends so that the bearing surface becomes slightly convex, as shown in Figure 1 (b). The shape that the pad assumes under load can be calculated from a solution of the Elasticity Equation and this is done in Phase II. For the present, however, it is assumed that the bearing surface becomes very slightly spherical. In accordance with plate theory, the bending deflections are taken to be proportional to load and inversely proportional to the pad thickness cubed. Since the pads are ball seated, they also tilt in both radial and tangential directions, till moment equilibrium is satisfied.

The film shape is then (see Appendix):

$$\begin{aligned} \mathbf{h} &= \mathbf{h_a} + \mathbf{m_{\theta}} \left[\mathbf{r_a} \sin \left(\theta_a - \frac{\theta_T}{2} \right) - \mathbf{r} \sin \left(\theta - \frac{\theta_T}{2} \right) \right] - \mathbf{m_r} \left[\mathbf{r_a} \cos \left(\theta_a - \frac{\theta_T}{2} \right) - \mathbf{r} \cos \left(\theta - \frac{\theta_T}{2} \right) \right] \\ &+ \frac{1}{2R_c} \left[\mathbf{r^2} - \mathbf{r_a}^2 - 2 \mathbf{r} \mathbf{r_p} \cos \left(\theta - \theta_p \right) + 2 \mathbf{r_a} \mathbf{r_p} \cos \left(\theta_a - \theta_p \right) \right] \end{aligned}$$
(11)

For cases where loads are light and the bending deflections are small, it is convenient to use as reference, the point at the inside radius and trailing edge of the pad. Equation (11) then becomes (for a centrally pivoted pad):

$$h = h_1 + m_{\theta} \left[(R-L) \sin \frac{\theta_T}{2} - r \sin (\theta - \frac{\theta_T}{2}) - m_r \left[(R-L) \cos \frac{T}{2} - r \cos (\theta - \frac{T}{2}) \right] + \frac{1}{2R_c} \left[r^2 - (R-L)^2 + 2(R-L) r_p \cos \frac{\theta_T}{2} - 2 r r_p \cos (\theta - \frac{T}{2}) \right]$$
(12)

For cases where the loads are large and the bending deflections are of the same order as the minimum film thickness, the point of minimum film thickness may fall within the pad boundary. It is then more convenient to use this point as reference. Its coordinates can be obtained by differentiating Equation (11) and setting:

$$\frac{\partial \mathbf{h}}{\partial \mathbf{r}} = 0$$
 and $\frac{\partial \mathbf{h}}{\partial \theta} = 0$

The coordinates of the point of minimum film thickness are then found to be:

$$r_{m} = R_{c} \left[m_{\theta}^{2} \cdot \left(\frac{r_{p}}{R_{c}} - m_{p} \right)^{2} \right]^{1/2}$$

$$\theta_{m} = \frac{\theta_{T}}{2} + \tan^{-1} \left(\frac{m_{\theta}}{r_{p}} - m_{p} \right)$$
(13)

Substituting Equation (13) into Equation (11), the film thickness profile becomes (for a centrally pivoted pad):

$$h = h_{\min} + \frac{R_c}{2} \left[m_{\theta}^2 + \left(\frac{r_p}{R_c} - m_r \right)^2 \right] + r \left[m_{\theta} \sin \left(\theta - \frac{\theta_T}{2} \right) + \left(\frac{r_p}{R_c} - m_r \right) \cos \left(\theta - \frac{\theta_T}{2} \right) - \frac{r}{2R_c} \right]$$
(14)

In Equations 11 through 14 above, R_c is the radius of curvature of the bent pad. In the present analysis, it is calculated from the load and pad thickness (see Appendix) using the relation:

$$\frac{1}{2R_c} = 0.75 \times 10^{-8} \frac{W}{t^3_{avg}}$$
 (15)

where W is the load per pad

tavg is the mean thickness of the pad

G. Oil Groove Temperature

The temperature at which the oil enters the clearance space between the runner and the pads has an important effect on the load carrying capacity of the bearing. It is introduced in the analysis as one of the boundary conditions of Equation (3).

In general, the temperature of the oil in the feed grooves between the pads is several degrees higher than at the housing inlet ports. This difference is largely due to the mixing in each groove with hot oil discharged from the trailing edge of the downstream pad. It is, therefore, significantly affected by such factors as:

- a) quantity of oil admitted to the housing (this is generally several times the amount that flows through the clearance spaces.)
- b) extent of the grooves
- c) pad discharge temperature

In the Phase I calculations, the pad groove temperatures are obtained from the experimental data of several investigators. The experimental points are plotted in Figure 4 and a representative curve is drawn through them. This curve shows the feed groove temperature as a function of the unit load carried by the bearing, when the oil temperature at housing inlet is 115 F.

Figure 4 is, of course, an average curve. In the experimental work on which it is based, the oil flow through the bearing housing was four to five times the clearance flow and the total area of the grooves was 15% of the effective runner area.

Different values of these quantities or the location of major heat sources or sinks near the bearing housing would be expected to affect the groove temperature.

H. Viscosity-Temperature Relation

The viscosity-temperature relation of the lubricant is required in the simultaneous solution of Equations (1) and (3). In all the Phase I calculations, the lubricant properties used were those of 2190T oil.

The absolute viscosity versus temperature plot for 2190T oil is shown in Figure 5.

I. Numerical Solution of the Reynolds and Energy Equations

A finite difference procedure was used to solve the Reynolds and Energy Equations. These, however, were first put in dimensionless form (Equations A-2 and A-5 of the Appendix) in order to facilitate comparison between geometrically similar bearings.

The finite difference form of the dimensionless Reynolds and Energy Equations are given by Equations A-4 and A-7 of the Appendix. These are two sets of algebraic equations that can be solved on a digital computer using an iterative procedure. Their solutions yield the pressure and temperature profiles over the pad surface.

Figure 6 is a typical thrust bearing sector pad, divided into a mesh of mxn sections. Referring to Equation A-4 and Figure 6, it is seen that the dimensionless pressure $p_{i,j}$ at any point is expressed in terms of the corresponding dimensionless pressures, viscosities and film thicknesses. The boundary condition states that the pressure is zero around the periphery of the sector. In order to meet this condition, the pressures at fictitious image points outside the boundary are set equal in magnitude but opposite in sign to the pressures at the corresponding points inside the boundary. By employing a process of iteration the mxn equations represented by Equation A-4 are solved on the computer and the pressures $p_{i,j}$ are determined at each mesh centerpoint. The process of iteration is continued until the difference between successive values of the sum of the pressures converges to within a prescribed error. In this analysis, the error is specified to be less than 0.1%, i.e.

Error =
$$\frac{\sum_{j=1}^{m} \sum_{i=1}^{n} \left[(\overline{p}_{i,j})_{k} - (\overline{p}_{i,j})_{k-1} \right]}{\sum_{j=1}^{m} \sum_{i=1}^{n} \left[\overline{p}_{i,j} \right]_{k}} < 0.001. \quad (16)$$

The load carrying capacity of a bearing is greatly influenced by the oil viscosity. The temperature (hence the viscosities) at each mesh point are obtained from the solution of Equation A-7. The boundary conditions for this equation are introduced by setting: a) the temperature, along the inlet edge equal to the groove temperature and b) the temperatures at fictitious image points outside the inner and outer circumferential boundaries equal in magnitude and sign to those at the corresponding points inside the boundaries.

The steps for the simultaneous solution of the Reynolds and Energy Equation are then performed in the following manner:

- The value of the film thickness at every point is determined. (1)
- Pi is assumed equal to zero and the known value of inlet temperature (2)
- (3)
- (4)
- is assigned to $T_{i,j}$ are then determined at every point from equation A-7. The values of $P_{i,j}$ are calculated from values of $T_{i,j}$.

 The values of $P_{i,j}$ are calculated from values of $T_{i,j}$.

 The values of $P_{i,j}$ are calculated from values of $P_{i,j}$ are calculated from values of $P_{i,j}$. Having the values of $N_{i,j}$, $N_{i,j}$ and $N_{i,j}$, the first approximation of the pressure field is determined from equation A-4 and improved several (5) times by iteration.
- The value of the pressure field thus obtained is used to recalculate the (6) temperature distribution from which a new set of $\overline{f}_{i,j}$ values is determined.
- A second approximation of the pressure field is now obtained. This cycle (7) of pressure and temperature iterations is continued until the error, which is the difference between successive values of the pressure field, falls within the limit prescribed in equation 16.
- The final value of the pressure field is then used to compute the final (8) value of the temperature field.
- The total pad load, oil flow, horsepower loss and the coordinates of the (9) center of pressure are calculated by means of Equations A-8, A-10, A-15 and A-16.

Trial and Error Procedure for Pivoted Pad Bearings J.

At each operating point, the pad deformation has to be related to the pad load in accordance with Equation 15. The film shape which depends on this deformation and on the inclinations of the pad has to be such that the resulting center of pressure passes through the pivot. Finally, the groove temperature used has to be related to the unit loading in accordance with Figure 4. In order to meet these requirements, the following trial and error procedure was used:

- For the bearing geometry being studied, select a value of minimum film (1)
- Estimate the corresponding unit load and hence the groove temperature (2) (T_{GR}) and the bending coefficient $(K = 1/2R_c)$.
- Select values of radial and tangential inclinations (me and my respectively). (3)
- Introduce the above as input data and obtain the corresponding computer (4) solution.
- From the computer output data determine the coordinates of the center (5) of pressure and the actual unit load (and hence the actual groove temperature and bending coefficient). Check whether these agree with the estimated ones within the following error limits:

a)
$$|(T_{GR})_{actual} - (T_{GR})_{estimatec}| \le 2^{\circ}F$$
b) $|(K)_{actual} - (K)_{estimated}| \le 2 \times 10^{-6} \text{ in.}^{-1}$
c) $|r_{cp}\% - r_{p}\%| \le 0.5\%$
d) $|\theta_{cp}\% - \theta_{p}\%| \le 0.5\%$

If any of the conditions, a through d of Equation 17, are not satisfied, steps 2 through 5 are repeated until all errors are within the specified limits.

This procedure was found to require an average of 5 trial computer solutions for each operating point obtained.

K. Estimate of Errors

A 7×7 mesh was used in the numerical solution of the Reynolds and Energy Equations. This was the finest mesh size that could be accommodated with an IBM 650 computer for the present program. Previous experience of the authors has indicated that satisfactory accuracy can be achieved with the 7×7 mesh, provided there are no sharp inflexion points in the film thickness profile. As an additional check, the calculations for one case were repeated on a larger computing machine, using a 13×13 mesh. The results agreed with those obtained using the 7×7 mesh within 1%.

The error limits defined in Equation 17 were set up in order to limit the number of iterations required for each solution. On the basis of calculations carried out with smaller allowable errors, the effects of the limits set in Equation 17 are estimated to be:

Error in calculated maximum temperature ≤ 5°F Error in calculated minimum film thickness ≤ 0.0001"

In the calculation of the hydrodynamic oil flow and the horsepower loss, additional errors are introduced in the numerical calculation of the pressure gradients at the pad edges (see equations A-13 and A-15). Particularly at high loads, where the pad bending deflections are correspondingly large, errors in the calculated values of hydrodynamic oil flow and horsepower loss may be as high as 20%.

III RESULTS

1. Eight bearings ranging in size from 19" to 50" diameter were analyzed, each at two speeds in the range 100 to 320 RPM. These were:

BEARING SIZE (O. D. " x I. D. ")	SPEEDS (RPM)		
19 x 9-1/2	160 and 310		
25 x 12-1/2	120 and 240		
31 x 15-1/2	180 and 320		
37 x 18-1/2	180 and 320		
39 x 19-1/2	150 and 200		
41 x 20-1/2	100 and 200		
45 x 22-1/2	100 and 170		
50 x 25	100 and 170		

These bearings were all geometrically similar, with the following properties:

$$\frac{1}{R} = \frac{1}{2}$$

$$k = 0.85$$

$$r_p\% = 0.154$$

In all cases, 6, 8, and 10 pad geometries were analysed. The results are given in Tables 1 through 8 and plotted in Figures 7 through 46.

 The shead and astern bearings of the USS Barry (DD933) and the shead bearing of the USS Norfolk (DL1) were studied at their full speed condition. These are:

	SIZE (O. D. " x L. D. ")	NUMBER OF PADS	(RPM)
Astern Bearing USS Barry®	26 x 17-1/2	8	160
Ahead Bearing USS Barry	$31 \times 16 - 1/2$	8	320
Ahead Bearing USS Norfolk	35 x 18-1/2	8	170

The results are given in Tables 9 through 11 and plotted in Figures 48 through 56.

^{*} In the case of the astern bearing of DD933, Figure 47 was used to determine T_{GR}. This is because the grooves between the pads of the bearing amounted to approximately 35% of the effective runner area, as compared with about 15% in the other bearings. In the absence of data for this size groove, Figure 47 was obtained from Figure 4, considering the groove temperature rise to be inversely proportional to the extent of the grooves

3. In order to estimate the effects of pad thickness, radial pivot location, groove temperature and bearing size, several additional calculations were made varying these parameters one at a time. The calculations were made for the following:

Bearing Size (O. D. x L. D.)	No. of Pads	Speeds (RPM)	R	<u>r_p%</u>	TGR
31 x 15-1/2	6, 8 and 10	180 and 320	0.130	50	Per Figure 4
$31 \times 15 - 1/2$	6, 8 and 10	180 and 320	0.193	50	Per Figure 4
$31 \times 15 - 1/2$	6, 8 and 10	180 and 320	0.154	53	Per Figure 4
$31 \times 15 - 1/2$	6, 8 and 10	180 and 320	0.154	47	Per Figure 4
$31 \times 15 - 1/2$	8	180 and 320	0.154	5-0	130°F
39 x 19-1/2	8	150 and 200	0.154	50	130°F
$19 \times 9 - 1/2$	6, 8 and 10	100	0.154	50	Per Figure 4
$75 \times 37 - 1/2$	6, 8 and 10	100	0.154	50	Per Figure 4
100 x 50	6, 8 and 10	100	0.154	50	Per Figure 4
$19 \times 9 - 1/2$	6	100	0.130	50	Per Figure 4
45 x 27-1/2	6	100	0.130	50	Per Figure 4
$75 \times 37 - 1/2$	6	100	0.130	50	Per Figure 4
100 x 50	. 6	100	0.130	50	Per Figure 4

The results are given in Tables 12 through 21 and plotted in Figures 57 through 81.

4. A 51-1/2" O.D. x 32" L.D. bearing that was analyzed under separate contract with M.S.T.G. &G. Dept. has also been included in this report. The geometry and operating conditions were:

Bearing Size (O. D. x L. D.)	No. of Pads	Speeds (RPM)	R	r _p %	TGR
51-1/2 x 32	10 and 12	200 and 400	0.117	52.6	Per Figure 4

The results are given in Table 22 and plotted in Figures 82 through 86.

IV DESIGN CHARTS

In order to facilitate design and selection of thrust bearings, where the outer diameter is roughly twice the inner diameter, the data in Tables 1 through 8 was used to arrive at a set of design charts. These are given in Figures 87 through 98. Note that in these charts (as in the other figures in this report) solid lines represent data within the range of calculations and dashed lines indicate extrapolated values.

When the oil film temperatures in Tables 1 through 8 are plotted, it is seen that both the maximum and the average temperatures are, with good accuracy, functions only of the unit load, number of shoes and pad inlet temperature. This allows the maximum and average temperature to be represented on a single chart, Figure 87. The accuracy of this chart, up to $T_{max} = 235^{\circ}F$, is $^{\frac{1}{2}}5^{\circ}F$. Above $T_{max} = 235^{\circ}F$, the accuracy is $^{\frac{1}{2}}10^{\circ}F$.

The minimum film thickness is a function of bearing size and speed as well as unit loading, number of shoes and pad inlet temperature. It is represented here as a function of these variables, in the set of nine charts, Figures 88 through 96. The accuracy of these charts is ± 0.0001" within the calculated regions. In the extrapolated regions, 'errors may be somewhat larger.

The hydrodynamic oil flow per pad is plotted in Figure 97, as a function of the dimensionless parameter $\begin{pmatrix} \mu_{avg} & U_{avg} \\ p_{avg} & B \end{pmatrix}$ As was pointed out earlier, the oil

flow calculations are subject to significant error (in some cases as high as 20%), in part because of the numerical approximation of the pressure gradient at the pad edges. It is also necessary to keep in mind that the oil flow given by Figure 97 is only that which flows through the clearance spaces between the runner and the bearing pads. The total flow furnished to the bearing should be several times this quantity.

The friction horsevower loss per pad is plotted in Figure 98, also as a function of the dimensionless parameter $\left(\frac{\mu_{avg}}{P_{avg}}\right)$ This horsepower loss

is dependent on the calculated oil flow and is thus subject to the same errors. In addition, it should be noted that Figure 98 shows only the horsepower loss due to fluid shear in the oil film. There are additional losses in the bearing, such as those due to turbulence in the oil grooves.

The example below illustrates the use of the charts.

Example: Compare the performance of 6 8 and 10 pad geometries for a 35" O. D. $\times 17-1/2$ " I. D. bearing at a speed of 280 RPM and a unit load of 650 psi. (Oil 2190T, k = 0.85 in all cases)

(0 2., (2.)			
	6 Pad	8 Pad	10 Pad
Pavg at h = 0.0010" (Per Figures 88, 91 and 94)	528	520	453
pavg at hmin = 0.0008" (Per Figures 89, 92 and 95)	623	663	620
pavg at hmin = 0.0006" (Per Figures 90, 93 and 96)	745	832	815
h _{min} at p _{avg} = 650 psi (by interpolation)	0. 0075"	0. 0082"	0. 0077"
T _{max} at 650 psi (Per Figure 87) - OF	237	215	207
Tavg at 650 psi (Per Figure 87) - OF	185	185	184
Mavg (Per Figure 5)	1.8x10-6	1.8×10-6	1.8×10-6
$U_{avg} = 2\pi (R - L/2) N - in/sec$	385	385	385
$B = (R - L/2) \theta_T = (R - L/2) \frac{2k\pi}{n}$ - in.	11.7	8. 76	7. 01
$\left(\frac{u_{avg} U_{avg}}{P_{avg} B}\right) \times 10^6$	0. 091	Q 122	0.152
$\left(\frac{Q}{B L U_{avg}}\right) \times 10^6$ (Per Figure 97)	24.9	24.7	24.6
Q GPM	0.98	0.73	0, 58
Q_{tot} GPM (= n x Q)	5.9	5.8	5.8
f x 10 ³ (Per Figure 98)	0.97	1.01	1.12
$HP = \frac{f B L p_{avg} U_{avg}}{6600}$	3.77	2. 94	2, 61
HP _{tot} (= n x HP)	22.6	23.5	26.1

DISCUSSION AND CONCLUSIONS

v

- 1. The two principal criteria of thrust bearing performance are the minimum film thickness and the maximum temperature. The present analysis, which was limited to 6, 8 and 10 pad bearings, showed that:
 - a) For each condition of operation (bearing size, load and speed), there is an optimum number of pads, from the standpoint of minimum film thickness. This can be seen by comparing the design charts, Figures 88 through 96.
 - b) The maximum temperature can be decreased by increasing the number of pads in the bearing. This gain is greatest in the critical high load regions as shown in Figure 87.

Note also from Figure 87 that the maximum temperature is a very sensitive indicator of bearing load. This is in contrast to the oil temperature which is little influenced by load changes.

2. At low loads, the minimum film thickness occurs at the inside radius of the trailing edge. However, as the bearing load (and hence the pad deformation) increases, the point of minimum film thickness moves toward the pivot, as shown in Figure 99. This figure shows that the radial location of the point of minimum film thickness moves quite rapidly towards the center region of the pad. It can be concluded from this that failures which result from small dirt particles in the oil film are most likely to occur near the pivot. This is borne out by experience.

Figure 99 also shows that the location of the point of minimum film thickness is dependent on the pad subtended angle. Thus, it moves inward from the trailing edge most rapidly in the case of the 6 pad bearing.

The marked divergence, at high loads, between the minimum film thickness and the film thickness at the inside radius of the trailing edge is also shown in Figure 100. In fact this figure shows that at high loads, the film thickness at the inside radius of the trailing edge becomes almost insensitive to load changes.

- 3. The effect of pad thickness is illustrated in Figures 101. Note that there is an optimum pad thickness at each specific load, from both the standpoints of minimum film thickness and maximum temperature. At low loads, thinner pads are preferable for the deformation there allows a more favorable film shape. At high loads, on the other hand, deformations become excessive and reduce load carrying capacity.
- 4. Since propeller shaft bearings are required to operate under either direction of rotation, the pivot location can be varied only radially. Figure 102 shows the effect of radial pivot location on minimum film thickness and maximum temperature, for several values of unit loading. Both these sets of curves indicate that there is an optimum pivot location, that varies with unit loading. The optimum locations obtained from the two sets of curves are, however, different. Thus, from the standpoint of minimum film thickness, the optimum pivot location approaches the mean radius from the outer circumference, as the unit loading increases. From the standpoint of maximum temperature on the other hand, the optimum pivot location approaches the mean radius from the inner circumference, also as the unit load increases.
- 5. The groove mixing temperature plays a very important role in bearing performance. Figure 103 shows the reduction in load carrying capacity that accompanies a rise in the groove temperature. This reduction is a major one, as indicated in the following table (obtained from Figure 103):

hmin"	GR °F	p avg psi	T oF
0.0006	130	1030	220
0.0006	158	800	235

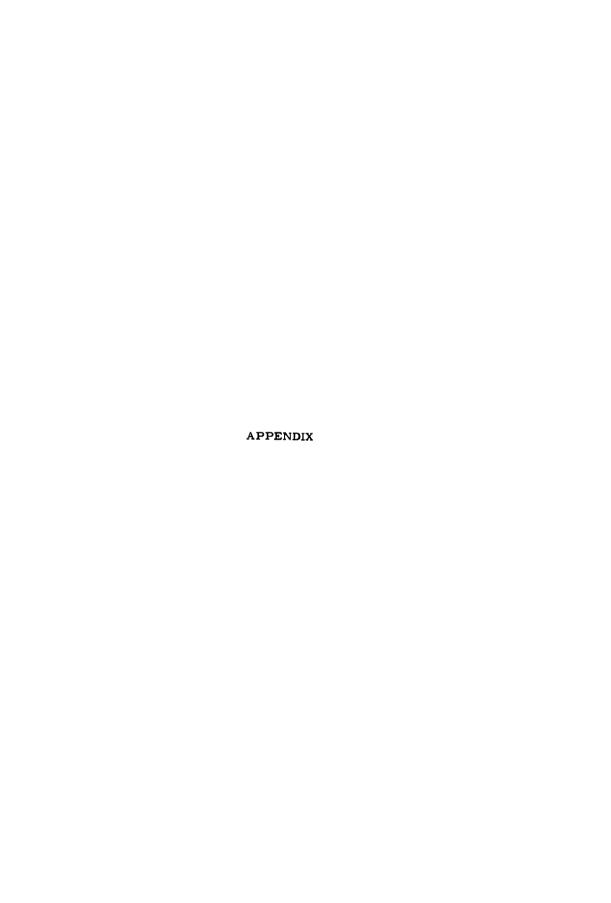
Thus, for a constant minimum film thickness, a reduction of 28°F in groove temperature achieves an increase of 28% in unit load, together with a reduction of 15°F in the maximum temperature.

- 6. For a geometrically similar series of bearings, the unit loading will increase with bearing size (at a given angular speed and minimum film thickness) as shown, for example, in Figure 81. This is of course due to the higher surface speed of the larger bearings. Note however, that the slope of the curve decreases quite rapidly due to the rise in groove mixing temperature and bending deflections. This points up again the importance of these two factors on bearing performance.
- 7. Early in this report, it was pointed out that the inclusion of thermal wedge and pad bending in the analysis explains the load carrying capacity of centrally pivoted pads. The load carrying capacities of a flat pad bearing with optimum pivot location and of a centrally pivoted pad were then compared in Figure 2, for a particular pad geometry. It should be noted, however, that the hydrodynamic pressure profiles differ markedly in the two cases, as shown in Figure 104.
- 8. In the present analysis, heat conduction was neglected. Thus, the calculated maximum film temperatures are somewhat higher than those which occur in practice. (The calculated values are therefore conservative.) Furthermore, whereas the calculated maximum temperatures are at the trailing edge, in practice they will occur at a small distance inward, also because of conduction.

V. RECOMMENDATIONS

- 1. The simplified analysis that was used here has shown that several aspects of bearing geometry, such as number of pads, pad thickness and radial pivot location, have a significant effect on load carrying capacity. The effect of number of pads was studied for a large range of bearing sizes. The effects of the other factors were studied for a 31" O. D. x 15-1/2" I. D. bearing. It is desirable to:
 - a) Verify the results using a more rigorous elasticity analysis (as is being done in Phase II).
 - b) Extend the results obtained to bearings with different L/R ratios.
 - c) Obtain experimental verification (PhaseIII and contemplated thrust bearing test machine.)
- 2. Groove mixing temperature plays a very important role in determining the load carrying capacity of thrust bearings. Gains in load capacity on the order of 25% can be achieved if mixing in the grooves can be inhibited, thus lowering the pad inlet temperature of the oil. This suggests an investigation aimed at developing suitable baffles in the oil grooves which would reduce the carry over of hot oil from the downstream pad. (A reduction in the dil temperature at housing inlets also serves to improve performance.)
- The major importance of pad geometry and grove mixing temperature on bearing performance indicate that design modifications can be made to greatly increase the load carrying capacity of tilting pad bearings. In such designs, consideration should be given to multi-point supports and to shaped pad surfaces as well as to the other aspects of bearing geometry studied in this report. Advantage should also be taken of the elasticity of the pads in optimizing the bearing design.
- 4. The present analysis was limited to steady state conditions. Analytical and experimental investigations are necessary in order to arrive at means of predicting bearing performance under transient conditions, such as acceleration, crash maneuvers, start up under load (as in a submerged submarine) and others.
- Metallurgical work is badly needed to-day to set up operating temperature limits of the various babbitts in use as well as to develop alternative materials.

- In future analytical work, the effect of thermal conduction should be studied.
- 7. The extent of misalignment present in thrust bearing installations on board ship needs to be investigated. In parallel with this, the degree of load equalization between pads and the load carrying capacity of the bearings under misalignment should be analyzed.



APPENDIX

1. Finite Difference Equations

The numerical solution of the Reynolds and Energy Equations by means of finite differences is described in Reference 11. Here a brief outline of the procedure is given.

For convenience of comparison between geometrically similar pads, the Reynolds and Energy Equations are first put in dimensionless form.

Let
$$r = R \overline{r}$$

 $h = h_a \overline{h}$ $p = 12 \pi N' \mu_{GR} \overline{p} \left[\text{where } N' = \frac{R}{h_a} \stackrel{?}{=} N \right]$
 $\theta = \overline{\theta}$
 $\mu = \mu_{GR} \overline{u}$ $T = \frac{12 \pi N' \mu_{GR}}{\rho_{g} J C_{p}} \overline{T}$ (A-1)

Introducing Equation (A-1) into Equation (1) of the text, we obtain the Reynolds Equation in dimensionless form:

$$\frac{\partial}{\partial \overline{r}} \left(\frac{\overline{r} h^3}{\overline{\mu}} \frac{\partial \overline{r}}{\partial \overline{r}} \right) + \frac{\partial}{\overline{r} \partial \overline{\theta}} \left(\frac{\overline{h}^3}{\overline{\mu}} \frac{\partial \overline{p}}{\partial \overline{\theta}} \right) - \frac{\overline{r} \partial \overline{h}}{\partial \overline{\theta}} = 0$$
 (A-2)

Referring to Figure 6, we can write

$$\frac{\partial}{\partial r} \left(\frac{\overline{rh}^{2}}{\overline{\mu}} \right) \frac{\partial \overline{p}}{\partial r} = \frac{\frac{\overline{rh}^{2}}{\overline{\mu}} \Big|_{i+1/2, j} \left(\frac{\overline{p}_{i+1, j} - \overline{p}_{i, j}}{\overline{2r}} \right) - \frac{\overline{rh}^{2}}{\overline{\mu}} \Big|_{i-1/2, j} \left(\frac{\overline{p}_{i, 1} - \overline{p}_{i-1, j}}{\overline{2r}} \right)}{\overline{\Delta r}} \\
\frac{\partial}{\partial r} \left(\frac{\overline{h}^{2}}{\overline{\mu}} \right) \frac{\partial \overline{p}}{\partial r} = \frac{\frac{\overline{h}^{2}}{\overline{\mu}} \Big|_{i, j+1/2} \left(\frac{\overline{p}_{i, j+1} - \overline{p}_{i, j}}{\overline{\Delta \theta}} \right) - \frac{\overline{h}^{2}}{\overline{\mu}} \Big|_{i, j-1/2} \left(\frac{\overline{p}_{i, j} - \overline{p}_{i, j-1, j}}{\overline{\Delta \theta}} \right)}{\overline{r}_{1, j} \overline{\Delta \theta}}$$

$$(A-3)$$

$$\frac{\overline{r}\partial \overline{h}}{\partial R} = \frac{\overline{r}_{i, j} \left(\overline{h}_{i, j+1/2} - \overline{h}_{i, j-1/2} \right)}{\overline{R}}$$

And, introducing Equation (A-3) into Equation (A-2) and solving for $\overline{P}_{i,j}$ we obtain

$$\overline{p}_{i,j} = \frac{\left(\frac{\overline{r}h^{3}}{\overline{\mu}}\Big|_{i+1/2,j} \frac{\overline{p}_{1+1,j}}{\Delta \overline{r}^{2}}\right) + \left(\frac{\overline{r}h^{3}}{\overline{\mu}}\Big|_{i-1/2,j} \frac{\overline{p}_{i-1,j}}{\Delta \overline{r}^{2}}\right) + \left(\frac{\overline{h}^{3}}{\overline{\mu}}\Big|_{i,j+1/2} \frac{\overline{p}_{1,j+1/2}}{\Delta \overline{\theta}^{2}}\right)}{\left(\frac{\overline{r}h^{3}}{\overline{\mu}}\Big|_{i+1/2,j} + \frac{\overline{r}h^{3}}{\overline{\mu}}\Big|_{i-1/2,j}\right) \frac{1}{\Delta \overline{r}^{2}} + \left(\frac{\overline{h}^{3}}{\overline{r}\mu}\Big|_{i,j+1/2} + \frac{\overline{h}^{3}}{\overline{r}\mu}\Big|_{i,j-1/2}\right) \frac{1}{\Delta \overline{\theta}^{2}}} + \frac{\left(\frac{\overline{h}^{3}}{\overline{\mu}}\Big|_{i,j-1/2} \frac{\overline{p}_{1,j-1/2}}{\Delta \overline{\theta}^{2}}\right) + r_{i,j}}{\left(\frac{\overline{r}h^{3}}{\overline{\mu}}\Big|_{i+1/2,j} + \frac{\overline{h}^{3}}{\overline{\mu}}\Big|_{i-1/2,j}\right) \frac{1}{\Delta \overline{r}^{2}} + \left(\frac{\overline{h}^{3}}{\overline{r}\mu}\Big|_{i,j+1/2} + \frac{\overline{h}^{3}}{\overline{r}\mu}\Big|_{i,j-1/2}\right) \frac{1}{\Delta \overline{\theta}^{2}}} (A-4)}$$

Similarly, from Equations (A-1) and Equation (2) of the text, we obtain the Energy Equation in dimensionless form:

$$\frac{\overline{\mu}\overline{r}^{2}}{3\overline{h}} + \frac{\overline{h}^{2}}{\overline{\mu}} \left[\left(\frac{\overline{co}}{r^{2}} \right)^{2} + \left(\frac{\overline{cp}}{\overline{o}\overline{r}} \right)^{2} \right] = \left[\overline{h} - \frac{\overline{h}^{2}}{\overline{\mu}\overline{r}^{2}} \frac{\overline{op}}{\overline{op}} \right] \frac{\overline{op}}{\overline{op}} - \left(\overline{h}^{2} \frac{\overline{op}}{\overline{op}} \right) \frac{\overline{op}}{\overline{op}}$$
(A-5)

Referring to Figure 6, the above equation can be reduced to a difference equation:

$$\frac{\overline{\mu}\overline{r}^{2}}{3\overline{h}}\Big|_{i,j} + \frac{\overline{h}^{3}}{\overline{\mu}}\Big|_{i,j} \left[\left(\frac{\overline{F}_{i,j+1} - \overline{P}_{i,j-1}}{2\overline{r}\Delta \theta} \right)^{2} + \left(\frac{\overline{P}_{i+1,1} - \overline{P}_{i-1,1}}{2\Delta \overline{r}} \right)^{2} \right]$$

$$= \left[\overline{h}\Big|_{i,j} - \frac{\overline{h}^{3}}{\overline{\mu}\overline{r}^{2}}\Big|_{i,j} \frac{\overline{P}_{i,j+1} - \overline{P}_{i,j-1}}{2\Delta \overline{\theta}} \right] \frac{\overline{T}_{i,j+1} - \overline{T}_{i,j-1}}{2\Delta \overline{\theta}}$$

$$- \frac{\overline{h}}{\overline{\mu}}\Big|_{i,j} \left(\frac{\overline{P}_{i+1,1} - \overline{P}_{i-1,j}}{2\Delta \overline{r}} \right) \left(\frac{\overline{T}_{i+1,1} - \overline{T}_{i-1,i}}{2\Delta \overline{r}} \right)$$
(A-6)

Now solving for $T_{i, i+1}$, we obtain

$$\overline{T}_{1,j+1} = \frac{2\Delta \theta \left[\frac{\overline{D}_{1}^{2}}{3h} \Big|_{1,1} + \frac{\overline{h}^{2}}{1} \Big|_{1,1} \left(\frac{\overline{P}_{1,1+1} - \overline{P}_{1,1-1}}{2\pi \Delta \theta} \right)^{2} + \left(\frac{\overline{P}_{1+1,1} - \overline{P}_{1-1,1}}{2\Delta \theta} \right)^{2} \right)}{\left[\overline{h} \Big|_{1,j} - \frac{\overline{h}^{2}}{\mu T^{2}} \Big|_{1,j} \left(\frac{\overline{P}_{1,1+1} - \overline{P}_{1,1-1}}{2\Delta \theta} \right) \right]}$$

$$+ \frac{h^{2} \Big|_{1,j} \left(\frac{\overline{P}_{1+1,1} - \overline{P}_{1-1,1}}{2\Delta \theta} \right) \left(\frac{\overline{T}_{1+1,1} - \overline{T}_{1-1,1}}{2\Delta \theta} \right) + \left\{ \overline{h} \Big|_{1,j} - \frac{\overline{h}^{2}}{\mu T^{2}} \Big|_{1,j} \left(\frac{\overline{P}_{1,1+1} - \overline{P}_{1,1-1}}{2\Delta \theta} \right) \right]} - \frac{\overline{h}^{2} \Big|_{1,j} \left(\frac{\overline{P}_{1,1+1} - \overline{P}_{1,1-1}}{2\Delta \theta} \right) \left(\frac{\overline{P}_{1,1+1} - \overline{P}_{1,1-1}}{2\Delta \theta} \right)}{\left[\overline{h} \Big|_{1,j} - \frac{\overline{h}^{2}}{\mu T^{2}} \Big|_{1,j} \left(\frac{\overline{P}_{1,1+1} - \overline{P}_{1,1-1}}{2\Delta \theta} \right) \right]} \right]}$$

The pressure and temperature profiles are obtained by the numerical solution of the two sets of E₄uations(A-4) and(A-7) using the iterative procedure described on Page 13.

The load carried by each bearing pad (Equation 5 of the text) is obtained by a numerical integration of the pressure field over the pad surface.

$$\overline{\overline{\mathbf{w}}} = \Delta \ \overline{\mathbf{0}} \ \Delta \overline{\mathbf{r}} \sum_{j=1}^{\mathbf{m}} \sum_{i=1}^{n} (\overline{\mathbf{p}}_{i,j})_{k} \overline{\mathbf{r}}_{i,j}$$
 (A-8)

The oil flow out of each pad is given in Equations 7 of the text. In order to generalize the solutions, a dimensionless factor is used;

$$\overline{Q} = \frac{231 Q}{60 \pi NRL h_a}$$
 (A-9)

Equations (A-1) and (A-9) are introduced into Equation 7 and four point approximations are used for the pressure gradients at the pad edges (Reference 12). Noting that the pressure is zero along the edges, the numerical form of the flow equations becomes:

$$Q_{2} = \frac{R}{L} \frac{\Delta \bar{\theta}}{\Delta \bar{r}} \sum_{j=1}^{m} (\frac{\bar{h}^{3}}{\bar{\mu} \bar{r}})_{1/2, j} (3.000 \, \bar{p}_{1, j} - 1.500 \, \bar{p}_{1-1/2, j} + 0.333 \, \bar{p}_{2, j})$$

$$\bar{Q}_{3} = \frac{\bar{r}}{L} \Delta \bar{r} - \sum_{i=1}^{n} (\bar{r} \, \bar{h})_{i, m+1/2}$$

$$+ \frac{R}{L} \frac{\Delta r}{\Delta \bar{\theta}} \sum_{i=1}^{n} (\frac{\bar{h}^{3}}{\bar{\mu} \bar{r}})_{i, m+1/2} (3.000 \, \bar{p}_{i, m} - 1.500 \, \bar{p}_{i, m-1/2} + 0.333 \, \bar{p}_{i, m-1})$$
(A-10)

$$\overline{Q}_{4} = \frac{R}{L} \frac{\triangle \theta}{\triangle \hat{r}} \sum_{j=1}^{m} (\frac{\overline{h^{3}}}{\sqrt{n}})_{n+1/2, j} (3.000\overline{p}_{n, j} - 1.500 \overline{p}_{n-1/2} + Q.33 \overline{p}_{n-1, j})$$

The total flow out of the bearing is given by

$$\bar{Q} = \bar{Q}_2 + \bar{Q}_3 + \bar{Q}_4 \tag{A-11}$$

The horsepower loss by fluid shear in each bearing pad was written in Equation 8 of the text in the form

$$HP = \frac{231}{60} \times \frac{C_p \rho g}{0.707} \times Q \triangle T$$
 (A-12)

In dimensionless form this is:

$$\overline{HP} = \overline{Q} \triangle \overline{\Gamma} \tag{A-13}$$

where, from Equations (A-1), (A-9) and (A-12):

$$\overline{HP} = \frac{0.707}{12 \pi^2} \frac{J h_a}{N^2 R^3 \mu_{GR}^L}$$
 (A-14)

In numerical form the horsepower loss is then given by:

$$\overline{HP}_{2} = \frac{R}{L} \frac{\triangle \overline{\theta}}{\triangle \overline{T}} \sum_{j=1}^{m} (\frac{\overline{\underline{h}}^{3}}{\angle \overline{T}})_{1/2, j} (3.000 \, \overline{p}_{1, j} - 1.500 \, \overline{p}_{1-1/2, j} + 0.333 \, \overline{p}_{2, j}) (\overline{T}_{1/2, j} - \overline{T}_{GR})$$

$$\overline{HP}_3 = \frac{R}{L} \triangle \overline{r} \sum_{i=1}^{n} (\overline{r} \, \overline{h})_{i, \, m+1/2} (\overline{T}_{i, \, m+1/2} \overline{T}_{GR})$$

$$+\frac{R}{L}\frac{\triangle \overline{r}}{\triangle \overline{0}}\sum_{i=1}^{n}(\frac{\overline{h}^{3}}{\sqrt[3]{r}}), m+1/2} (3.000\overline{p}_{i,m}-1.500\overline{p}_{i,m-1/2}+0.333\overline{p}_{i,m-1})(\overline{T}_{i,m+1/2}\overline{T}_{GR})$$

$$\overline{HP}_{4} = \frac{R}{L} \frac{\angle \overline{\theta}}{\angle \overline{r}} \sum_{j=1}^{m} (\frac{\overline{h}^{3}}{\sqrt{r}})_{n+1/2, j} (3.000\overline{p}_{n, j} - 1.500\overline{p}_{n-1/2} + 0.333\overline{p}_{n-1, j}) (\overline{T}_{n+1/2, j} - \overline{T}_{GR})$$

and the total horsepower loss in each bearing pad is:

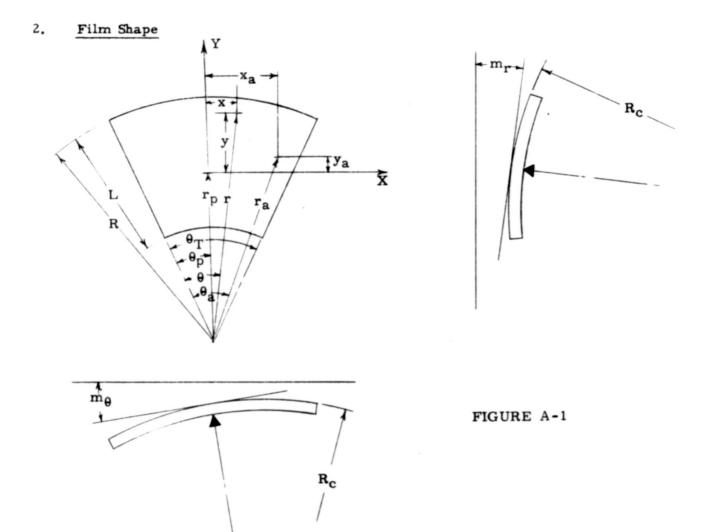
The equations for the center of pressure (Equations 10 of the text) are in numerical form:

$$\frac{\Delta \boldsymbol{\theta} \, \Delta \hat{\mathbf{r}} \, \sum_{j=1}^{m} \sum_{i=1}^{n} \hat{\mathbf{r}}^{2} \, \sin \boldsymbol{\theta}_{i,j} \, (\overline{\mathbf{p}}_{i,j})_{k}}{\mathbf{w}}$$

(A-16)

$$\overline{v} = \frac{\Delta \theta \Delta \overline{r} \sum \overline{r}_{i,j}^2 \cos \overline{\theta}_{i,j} \overline{p}_{i,j})_k}{\sqrt{\overline{r}}}$$

to note:
$$\mathbf{r_p\%} = 10 \cdot \left[1 - \frac{R}{L} \cdot \frac{1}{(\mathbf{x}^2 + \mathbf{y}^2)}\right]^{\frac{1}{2}}$$
 and $\theta_p\% = \frac{100 \tan^{-1} (\mathbf{x}/\mathbf{y})}{\theta_T}$ (A-17)



We consider that the convex shape to which the pad bends under load may be represented by part of a spherical surface whose radius of curvature is R_c , as shown in Figure A-1. In all cases considered here, R_c is very large, greater than 10^4 inches. In addition, the pad inclines, so that its tangent plane directly above the pivot point has slopes m_θ (circumferentially) and m_r (radially), with respect to the plane of the runner, as shown in Figure A-1. The pad inclinations are small so that

$$\sin m_{\theta} = \tan m_{\theta} = m_{\theta}$$

$$\cos m_{\theta} = 1$$

$$\sin m_{\mathbf{r}} = \tan m_{\mathbf{r}} = m_{\mathbf{r}}$$

$$\cos m_{\mathbf{r}} = 1$$
(A-18)

Let the film thickness at a reference point (x_a, y_a) on the pad surface be h_a . The film thickness at any other point (x, y) can ther be written:

$$h = h_a - m_\theta (x - x_a) + m_r (y - y_a) + R_c \left[\left(1 - \frac{x_a^2 + y_a^2}{R_c^2} \right)^{\frac{1}{2}} - \left(1 - \frac{x_a^2 + y_a^2}{R_c^2} \right)^{\frac{1}{2}} \right]$$
(A-19)

Since R_c is very large, powers of the ratio $\left(\frac{r^2}{R_c^2}\right)$ are neglected. Equation (A-19) then becomes:

$$h = h_a - m_\theta (x - x_a) + m_r (y - y_a) + \frac{(x^2 + y^2) - (x_a^2 + y_a^2)}{2 R_c}$$
 (A-20)

This equation can be converted from the x, y co-ordinate system to the r, θ coordinate system of Figure A-1 by means of the relations:

$$x = r \sin \left(\theta - \frac{\theta}{2} \frac{\Gamma}{2}\right) - r_{p} \sin \left(\theta_{p} - \frac{\theta}{2} \frac{\Gamma}{2}\right)$$

$$y = r \cos \left(\theta - \frac{\theta}{2} \frac{\Gamma}{2}\right) - r_{p} \cos \left(\theta_{p} - \frac{\theta}{2} \frac{\Gamma}{2}\right)$$
(A-21)

The general equation for the film shape in polar coordinates is then:

$$h = h_{a} + m_{\theta} \left[r_{a} \sin \left(\theta_{a} - \frac{\theta_{T}}{2} \right) - r \sin \left(\theta_{a} - \frac{\theta_{T}}{2} \right) \right] - m_{r} \left[r_{a} \cos \left(\theta_{a} - \frac{\theta_{T}}{2} \right) \right]$$

$$- r \cos \left(\theta_{a} - \frac{\theta_{T}}{2} \right) + \frac{1}{2R_{c}} \left[r^{2} - r_{a}^{2} - 2rr_{p} \cos \left(\theta_{a} - \theta_{p} \right) + 2r_{a}r_{p} \cos \left(\theta_{a} - \theta_{p} \right) \right]$$

$$(A-2a)$$

(note that Equation A-22 can also be used to describe the film shape for flat pads. In such cases, R is infinite, thus eliminating the fourth term on the right hand side of the equation,)

3. Bending Coefficient

Equation A-20 and Figure A-1 show that (with the simplified elasticity approach used here), the bending deflection along a point on the pad surface is proportional to the square of its distance from the pivot, i.e.

$$\delta = K(x^2 + y^2) \tag{A-23}$$

where
$$K = 1/(2R_c)$$
 (A-24)

The value of the bending coefficient K was obtained by calculating the deflection at the rim of an equivalent circular plate point supported at the center of its lower face and carrying a conically distributed load on its upper face. A circular plate was used because a closed solution for its bending deflections is available (Reference 11). A conical load distribution was selected because the ratio of peak to average pressure (3:1) is similar to that in an actual bearing pad.

Integrating Equation 57 of Reference 11, for a steel circular plate (radius "a" and thickness "tavg") under the loading and support described above, the deflection at the rim is found to be:

$$\delta = 0.75 \times 10^{-8} \frac{\text{W a}^2}{t_{\text{avg}}}$$
 (A-25)

From equations A-23 and A-25, the relation between the bending coefficient and the pad load is:

$$K = 0.75 \times 10^{-8} \frac{W}{t_{avg}}$$
 (A-26)

This relation was used in all the Phase I solutions.

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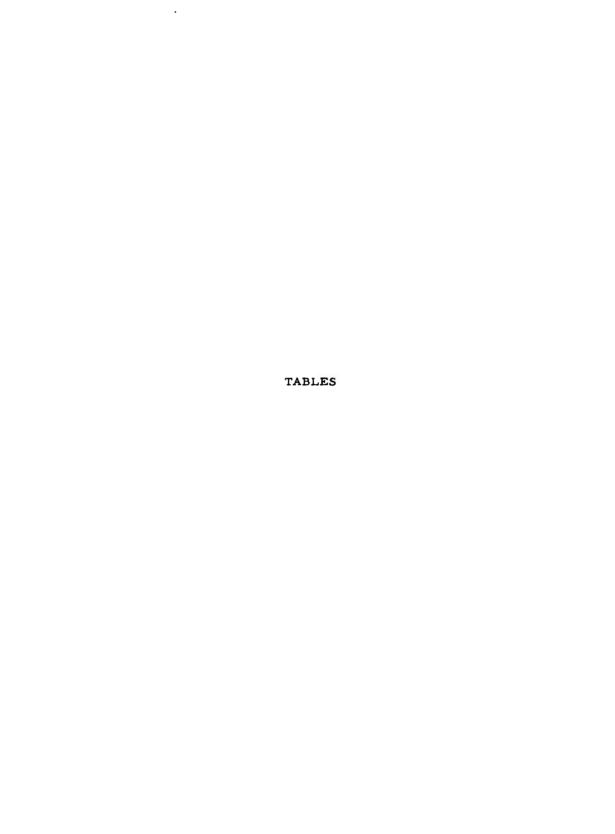


TABLE NO. 1

19" 0.D. x 9 1/2" 1.D. THRUST BEARING $\left(\frac{L}{R}$ = 0.5 $\right)$

Effective Bearing Area - 181 Sq. In. (k = 0.85) Average Pad Thickness - 1.462 In. $\frac{t_{avg.}}{R}$ = 0.154 Pivot Pitch Diameter - 14.25 In. $(r_{p} \% = 50; \theta_{p} \% = 50)$

011 - 2190

2	
Inlet	
115°F	
Ħ	
1 061	

		1							
H.P. 701		1.34 1.56 1.46	3.83	1.76	4.7	1.76	5.09 4.39		
P E	Ę,	0.816 0.575 0.510	1.78	0.60	1.27	0.769 0.517 0.43	1.55		
"TOT *10-3	108	12 64.7 93.3	30.3 93.5 123.0	54.4 95.5 123.0	36.3 86.9 134.0	25.3 82.6 120.7	61.6 124.0 169.7		
P X	8	271 899 1529	370 1372 2099	685 1355 1920	435 1142 1944	301 1073 1686	747 1672 2448		
PAVG	%	67 353 517	168 518 682	305 528 682	75 75 75 75 75 75 75	029 758 670	3771		
T, tx	oF.	150 184 209	165 207 239	22822	195 226 226	155 188 211	176 215 242		
TAVG	oF.	136 155 171	12 18 18 18	154 175 190	172	171	159 193 212		_
Ę	oF.	125 132 142	126	122	127 120 154	126	133		
4	in	0.00135	0.00136	0.000667	0.00102 0.00071 0.00058	0.00049	0.00069		
*		100 95 85.2	100 91.4 83.8	100 96.7	100 100 94.8	988	100	And the second s	
H.		50 52 52	64.3 52	35.7 44 46	14.3 42.8 45	35.7 28.6 42.8	14.3 42.8 44		
e e	uţ	0.00032	0.00124	0.0004	0.00101	0.000744	0.0006E 0.000204 0.0003		
- 8	10-6 in-	33.25.5	12%	288	788	23.28 28	31 40		
B, x10 ⁶	in/in	27 19 19	328	356	84 <i>%</i>	883	823		
**************************************	in/in	75 143 170	130 190 210	98 122 129	113 135 155	69 95 103	115 126 140		
Z	RPM	36 160 160	310 310 310	35 36 36 36 36	310	36 168 168	310 310 310		
No. of	Pads	999	999	60 60 EO	ഗ റേ പ	200	000		
•	Deg.	222	222	33.25 38.25	38.25	30.6 30.6 30.6	30.6 30.6 30.6		
- Sec	NO.	- 00	759	r- w o	212	275	16 17 18		

TABLE NO. 2

In. $(\mathbf{r_p \%} = 0.154)$ In. $(\mathbf{r_p \%} = 50 \ \mathbf{i} \ \mathbf{0_p \%} = 50)$ Sq. In. (k = 0.25)25" C.D. x 12.5" I.D. THRUST BEARING ($\frac{L}{R}$ = 0.5) Average Fad Thickness - 1.025 Effective Searing Area - 312

Pivot Pitch Diameter - 18.75 011 - 2190 T at 115°F Inlet

2	E		2.16	2.12	702	5.0	6.33	2.33	2.30	6.9	6.9	67.6		2.39	7.57	72.7	6.07						
o		ad6	1.12	0.528	2.50	1.94	70-1	0.86	69.0	3.04	1.86	à	27.2	0.62	2.95	2.03	3		-1-1		 		
Px 10-3	<u>.</u>	sqt	37.5	127.8	7.0	175.2	, ,	9.611	187.4	52.3	180.0	5	174.8	235.2	52.8	156.1						-	
	Š	2	77	1777	563	1622		923	1636	798	288	9	1391	7057	363	2070							
9	2	i	011	558	577	262		250	3	16.0	24 202 203	Ŕ	264	652	170	5 8 8		•					
, and	É		155	212	173	216	, ,	32.5	5	160	38	9	8.6	777	160	23.15	_				 		
TANG	ц		130	127	176	176	: 5	150	G2 1		201	155	2	<u>}</u>	177	201					 		
_6	i <u>u</u>		125	14		<u> </u>		137		126	351	130	77.	007	126	15.					 		
Ę			0.00130	0.00074	0.00133	0.000369	9,00005	0.000705	2	0.00134	69000.0	0.00065	0.00051	0.000	0.00106	0.00057							
3°			100	32.5	100	30.4	001	001		608	67.7	100	130	``	85	125					 	-	
, E			51.8	. S	57.1	22	14.3	6.7		21.4	34	21.7	35.7	}	20 %	8.27			-		 		
e cii	-I		0.90126	7000-0	0.00121	7000	0.00000	9000.0		0.00132	7000.0	6,00063	0.003	}	0.00106	7000.0		•	-				
<u>₩</u>	10-6 in-		۰ ۲	23	717	107		77		2, 2	3.	77		-	16.7	%					 		
" ×10	in/in		ន្តន	22	58	1%	75	33.	42	3 3	34	3:	32.7		p. 4.	37			-		 		-
8 9×106	in/in		e 3	161	173	201	0.0	137	501	134	153	8. %	127		ខ្លួ	125		North street					-
2	RPM		129	120	270	2	120	120	070	32	077	120	120		33	677				F 100 MIN M			
No. of	Pads	,	ا مه د	œ.	φ¢	9	C i. 1	lai (1)	n	u.	tı)	010	2 2		20	<u></u>							••
٠	Deg.		7.57	52	22	15	38.25	38.25	36.25	38.25	38.25	30.6	30.6	,	30.6	30.6		+			 -		
Case.	No.		2, 2, 3	7	ដន	お	33	2.8	35	8	8	33	(2)		45	*					 		

31" 0.D. x 15.5" 1.D. THRUST BEARING $\left(\frac{1}{R} = 0.5\right)$ TABLE NO. 3

Effective Bearing Area - 480 Sq. In. (k = 0.85) Average Pad Thickness - 2.385 In. $\frac{t_{BVQ_{\perp}}}{R}$ 0.154 Pivot Pitch Dismeter - 23.25 In. $t_{P}^{M}_{p}$ = 50; $\theta_{P}^{M}_{p}$ = 50)

Pivot Pitch Dismeter - 23.25 Oil - 2190 I at 115°F Inlet

<u>10</u>										
H.P. 101		8.18 7.48 7.44	19.6 18.0 20.2	8.34 8.22 7.53	21.8 18.5 18.9	9.00	20.5	<u></u>		
P _{TOT}	anci 6	3.02 2.48 2.45	6.2 5.05 4.85	3.48 2.34 1.98	6.5 4.47 3.94	3.88	2.0v 3.86			
"TOT*10"	106	154.2 284.5 346.0	213.1 350.4 425.0	99.5 289.0 382.0	166.8 324.0 503.0	73.5 269.8 411.8	100.2 370.5 546.3			
MAX.	psi	779 1802 2520	1046 2304 3492	456 1618 2440	783 2172 3323	3278 1344 2295	453 1899 3153			
AVG	psi	321 593 721	25.5 7.88 7.89	207 619 811	345 900 1058	153 562 858	213 772 1138			
THAX	Ą	180 219 25°	195 249 294	162 209 244	181 235 273	156 198 234	164 222 264			
TAVG	Ä	153 176 194	162 193 211	147 181 202	161 200 221	173 205	200 200 227			
_6	P.	130 146 154	136 154 163	127 143 158	132 158 165	125 142 160	127 156 165			
۲,	in	0.00133 0.00104 0.00098	0.00153 0.00118 0.00114	0.00129 0.00838 0.00076	0.00132 0.00094 0.00087	0.00115 0.0072 0.00065	0.00132 0.00079 0.00076			
×.		% 84.4 79.5	97.2 82.7 77.6	100 95.5 86.3	100	100 100 95.5	100 100 92.7			
NE NE		52 52 50	888	7.17	35.7 26 27	34.5	0.22.8			
d G	ui in	0.00111	0.0012	0.00127 0.0006 0.0004	0.00124 0.0006 0.0004	0.000115 0.00061 0.0004	0.00132			
규 나 %	10-6 in-	14 25 32	33.33	20 27	282	5 22	% R &			
*x106	in/in	22.2	ងងង	3,3,3	38 88	375	33.55		National distribution of the	
**************************************	In/in	139 177 193	176 216 222	95 134 147	122 161 173	72 107 115	95 126 143			
=	RPM	180 180 180	330	180 180	320	180 150 130	323			
No. of	Pads	999	·3 • • •	ta) ta) tag	to to to	0100	000			
•	Deg.	51 51	ផ្ដូ	38.25 38.25 33.25	38.25 38.25 38.25	30.6 30.6 30.6	30.6 30.6 30.6			
3	No.	£88	344	242	57 67 97	\$ 55 E	252			

37" 0.D. x 18.5 " I.D. THRUST BEARING $\left(\frac{1}{8} = 0.5\right)$

Effective Bearing Area - 685 Sq. In. (k = 0.85) Average Pad Thickness - 2.85 In. $\begin{pmatrix} t \\ avg. = 0.154 \end{pmatrix}$

Pivot Pitch Dismeter - 27.75 In. ($r_p\%$ = 50 ; $\theta_p\%$ = 50) Oil - 2190 I at 115°F Inlet

	1							
H.P. 101		13.4 13.4 14.6	33.5	24.9 0.53 0.53	23.5.7 7.05 7.05	7.77	39.6	
P _{TOT}	adb	4.92	97.8 8.46 8.47	3.29	10.02 7.15 6.77	6.83 3.7 3.11	7.09	
W101×10-3	1bs	252.2 439.7 529.8	347.4	195.5 485.6 623.2	324.6 628.5 786.5	51.5 474.9 655.4	195.3 627.5 884.5	
NAX.	78	934 2101 3135	1342 2767 4241	636 1995 2930	2634 2634 4115	160 1748 2709	617 2384 3907	
AVG	psi	3,56	798	285 910 910	474 918 1148	55 693 957	285 916 1291	
THAT	4	185 234 275	317	2563 263 263	191 254 303	153 214 254	175 242 288	
TAVG		157	171 201 218	154 192 210	227	1912	158 213 234	
. 6	4	133	157	153	137	125 152 164	130 163 165	
<u>.</u>	- t	0.00152	0.00163	0.00131 0.00098 0.00092	0.00138	0.00156	0.00137 0.000929 0.000931	
**		94 81.5 77.3	91.5	100 86 87.78	88.3 82.5	100	100 97.5 88	
* E		282	50.5	28.6	35.7 49.7	0 42.8 45	0 3 3	
P din	- ut	0.0012	0.0012	0.00126	0.00121	0.00156	0.00137	
⊣ ≋	10-6 in-	77.78	18 30 35	19	333	25.53	28 28 28	
*x106	11/11	25.55	253	282	25,62	66 78	263	
**************************************	in/in	150 185 194	220 230 230	25 134 156	135 175 190	110	90 134 153	
2	RPM	130 180 180	350 35	180	320 320 320	180 130 130	350	
No. of	Pads	999	999	∞ ∞ ω	യയയ	999	10	
•	Ď.	222	**	38.25 38.25 38.25	38.25 38.25 38.25	30.6	30.6 30.6 30.6	
	No.	282	888	63 65	799	538	222	

Š

					1	ļ							
				H.P. TOI		11.8 10.0 11.7	21.5 22.7 26.8	9.96 10.2	25.8 21.2 22.9	12.4 10.9 10.3	23.3 23.3 22.8		
				P _{TOT}	adb	3.96 3.62 3.52	7.49 6.91	2.98	7.9 5.76 5.33	3.09	7.32 5.73 4.94		
				"TOT × 10-3	1bs	337.6 562.1 692.4	455.1 711.6 825.4	238.8 654.4 815.7	430.7 797.1 990.9	232.7 621.8 875.4	539.0 810.9 1082.2		
				P. W.	19	842 1911 2895	1205 2494 3774	517 1837 2687	1000 2305 3533	297 1616 2542	1243 2140 3337		
			50)	Avg	pe 1	334 555 684	750 703 816	236 638 806	927 979	230 614 865	533 801 1069		
			H	THAX	οF	179 223 260	197 252 295	164 214 250	184 239 284	162 207 242	192 226 272		
	0.5	= 0.85)	50 3 9 %	TAVG	oF	152 177 191	162	147 183 201	161 198 217	148 184 207	172 201 222	 	
]	In. $(k = 0.85)$ $\binom{t}{8 \times 9} = 0.154$	# # €	E	oF.	130 126 151	136 152 158	126 148 156	134 157 163	126 149 160	140 158 165		
	Thrust bearing $\left(\frac{L}{R}\right)$	S. in	Ė	4	în	0.00153	0.00169 0.00142 0.0014	0.00132	0.0014	0.0011	0.00106		
4	THRUST	3.46	33.75 Inlet	y₹ •		93.8 80.3 76.9	89.95 76.95	100 88.2 83	100 87.4 81.8	100 97 89.3	100 96.1 87.5		
TABLE NO.	22.5" I.D.	Ares -	rter - it 1150F	N.		282	ដូ៥៥ ភូ	21.4 46 47	87 72.8 74 78	0 45 45	35.7 43		
•-•	×	Effective Bearing Area Average Pad Thickness	Pivot Pitch Diameter - 33.7 Oil - 2190 I at 115°F Inlet	d nia	ů	0.0012	0.0012	0.0013	0.00121	0.0011	0.00093		
	45" 0.b.	Effect	Pivot 1	- 8, #	10-6 in-	9 18 21	322	7781	9 22	22 25	20 20		
				"x106	in/in	170 19 20	322	98 54 54	385	33.22	3,32		
				*01x6	In/In	118 162 168	156 185 200	23 136 139	114 143 155	63 95 102	104 118 131		
				z	Æ	990	178 178	888	128 178 178	888	138	 	
				No. of	Pads	999	999	tw to to	to to to	222	222	 	
				6	Deg.	222	444	38.25 38.25 38.25	38.25 38.25 38.25	30.6 30.6 30.6	30.6 30.6 30.6		
				***	No.	901	112	115	118 119 120	122	125		

							J						
					H.P.		13.2	29.2 32.1 41.3	16.0 13.5 14.1	32.5 32.6 32.4	16.3 15.0 14.0	8118 8118 8199	
					Pag.	86	5.38 4.89 4.73	10.01 9.2 9.75	5.57 4.05 3.74	10.0	3.39 3.39	9.21 7.32 6.42	
					"JOT *10"	1 bs	8°206 6°072 605°8	611.9 909.9 1048.5	426.9 847.5 1044.3	601.5 1050.1 1316.6	389.6 874.3 1133.2	760.6 1103.2 1468.7	
					X¥	psi	990 2137 3244	1370 2730 4189	787 2036 295 1	1166 2577 3951	1262 1863 2827	3787 3787 3787	_
				50)	AWG	pei	374 593	728 839	342 678 835	8701 870 187	666 646 646 646 646 646 646 646 646 646	608 883 1175	
				ij	THAX	o.F	184 231 272	30 0	173 223 263	26 26 26 26 26 26 26 26 26 26 26 26 26 2	190 214 254	239	
		(5.0	(* * #.85)	**	TAVG	4	155 180 196	167 196 211	20,53	168 204 223	172	180 208 229	
⊣ (,,	4 4		_E	ñ	133 147 153	139 154 160	130	138	127 151 162	165	
- PHASE		25" I.D. THRUST BEARING $\left(\frac{L}{R}\right)$	ġ ś	ġ	ď	f,	0.00166	0.00181 0.00158 0.00156	0.00136 0.00111 0.00105	0.00142	0.00098	0.0010	
PROCESS	8	THRUST	- 1250 - 3.85	- 37.5 F Inlet	8	_	90.6 73.8 76.7	27.7 78.2	100 86.6 81.5	100 85.5 81	100 96.5 86.4	100 93.2 86.2	
SEARING	TABLE NO.	5" I.D.		rter it 1150F	¥.		25 58 5.58	50.5	35.7	87 87 87 87	35.7 43	43.5	
MARINE INCOSI BEANING PROGRAM - PHASE I	• •	*	Effective Bearing Area Average Pad Thickness	Pivot Pitch Diameter - 37.5 Oil - 2190 I at 1150F Inlet	e in	ä	700000 71100000 711000000	2000'0 2000'0	#10000 0,0000 0,0000	000	0.000 0.000 0.000 0.000	000	
		50" 0.D.	Effect. Averag	Pivot 1	구 1 1 1 1 1	10-6 in-	10 17 19	ជនន	6 17	9 17 20	111	6 71 81	
					_r×106	tn/1n	16 19 18	20 20 20	253	36%	322	23.7.4	-
					•0x10*	1n/in	136 163 169	186 20 20	91 125 131	114 148 152	97 106	115	-
					×	RPE	100	128	999	128	888	170	
					No. of	Pads	999	999	60 60 60	6 7 6 0 6 0	000	200	-
					•	99	51 51 51	222	38.25	33.25 38.25 38.25	30.6 30.6 30.6	30.6	
					3	No.	128	132	135	136	171	334	***************************************

TABLE NO. 9

26" 0.D. x 17 1/2" 1.D. THRUST BEARING ($\frac{1}{6}$ = 0.327)

Effective Bearing Area - 184, Sq. In. (k =0.631)
Average Pad Thickness - 1.47 In. (tag. = 0.113)

Pivot Pitch Diameter - 21.75 011 - 2190 I at 115°F Inlet

In. $\left(\frac{\log_4}{R} = 0.113\right)$ In. $(r_p\% = 50 + 9p\% = 50)$ H.P. TOT 3.35 0.92 mdb PMAX "TOTX10"3 QTOT 63.8 103.7 157.7 lbs psi 788 1394 2535 TMAX PAVG psi 350 40 2002 TAVG 166 하 F 128 JO. 0.00065 4 in 8.8 100 85.9 r m % 53.7 0.00072 h min ţ 583 in/in 15 in/in 135 RPW 991 No. of Pads 00 00 00 28.4 28.4 28.4 Case 0, Deg. No. 145 PREDICTOR ST. BEARING PROGRAM - THERE I

TABLE NO. 10

 $31" 0.0. \times 16 \, y/2" 1.0.$ THRUST BEARING ($\frac{1}{8} = 0.468$)

Sq. In. (k = 0.85)In. $(\frac{t_{max}}{R} = 0.142)$ In. $(r_{p} = 91.71 \ p_{p} = 50)$

Average Pad Thickness - 2.20

Effective Bearing Area - 459

Pivot Pitch Dismeter - 24 Oil - 2190 T at 1150F Injet

H.P. TOT	2. 2. 2. 2. 2. 2. 2. 2. 2. 2. 2. 2. 2. 2
Þ	# 324 32×
THAX PANG PANK TOTALO"	11.12.13.13.13.13.13.13.13.13.13.13.13.13.13.
A M	1 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2
ANG	i key
	F 538
TANG	197 216
,5	r Kyy
, ; *	0.00149 0.001111 0.00102
*	33.58
yk h	2.23 2.
•	0.00121
48,2	211.64
\$0.00 \$1000 \$0.00 \$10.00	727
10/10	20.00
* §	320
No. of	6 0 6 0 6 0
٠ <u>\$</u>	38.25
Case	176

						•
				H.P. 701	_	7. cc 5. cc 7. cc
				þ	I &	44.6
				3101 10-3	1	27.7.5 457.7.
				3	ĩ	2731 2731
			•	ARG	ĩ	78°E
			8	Ä	4	2215 2215 236 236
	اع	0.85)	(rp# =51.5; 0 %	ANG		222
	7.0 = 1	In. $(k = 0.25)$ $\left(\frac{t_{\text{grib}}}{4} = 0.133\right)$. ¥.	,5	•	156
	x 18 $1/2$ " I.D. THUST BEARING ($\frac{1}{16} = 0.471$	Sq. In. (k = 0.25) In. (1996 = 0.133	.ei	4	in	0.0010 0.0010 0.0010
月	THECES	591 2.33	23 Inlet	**	_	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2
IAME NO.	i.b.	Area -	ter .	y.		55.2 5.3 3.3
A	D. x 18 1/2	Effective Bearing Area Average Pad Thickness	Pivot Pitch Diameter - 27 Oil - 2190 I at 1150F Inlet	d c	đ	0.00120
	35" 0.D.	Effects Average	Pivot P	- x10 = 1	10-6 in-	26%
				x10	tn/in	25.52
				-x10	in/in	132,
				E	N. P.	170
				No. of	Pade	¢, m ¢.
				,	Deg.	67 67 67 67 67 67 67 67 67 67 67 67 67 6
				8	No.	22.2

31" 0.D. x 151/2" 1.D. THRUST BEARING ($\frac{1}{k}$ = 0.5

TABLE NO. 12

		1.9.	2	2.5	17.7	92	27.7	3,1,5	2.27			
		į		7.00	6.21	33,4	8.4.6	* * * * * * * * * * * * * * * * * * *	7.97 5.13 4.55			******
		" "TOT #10"		158.9 245.8 295.0	317.8	274.3	390.0	7.52	138.7 365.5 477.4		•	
			Ĭ	£ 5.8	3523	535 1674 2475	3222	2335	2062			
	^	280		223	288	\$28	848	325	8.4.8		**********	
	N 20	7	*	223	23%	383	388	23.85	253			
0.25)		ANG	<u>u</u> .	325	355	3E %	8.6.5	318	3 <u>2</u> 2			
In. (R = 200	# 20 #	.5	4	833	233	551	232	951 571 772	833	* ** ****		
Sq. In. (k = 0.25) In. (two. = 0.130	In. (Tp.	£	<u> </u>	0.00151	0.00173	0.00103	0.00141	0.00035	0.00131 0.00095 0.70101			
- 480	- 23.25 F Inlet	¥.	_	93.0	8.5.5 5.5.5	283	8 % 5	8 8 8	37.5			-
Area	tor t 1159	**		52.0 50.0	ខ្លួន	35.7	3,5,5	-33	242			
Effective Bearing Area - 480 Average Pad Thickness - 2.0	Pivot Pitch Diameter - 23.25 Oil - 2190 I at 1150F Inlet	e e	ın	0,000.0	0.00120	0.00124	0.00121	0,000.0	0.00128 0.0065 0.00045			
Effect	Pivot 1	⊣ ≈	10-6 in-	453	25	12 32 41	828	782	284			
		•x106	1n/1n	2%2	222	828	*35	328	828			
		01x9	in/in	250	238 300	120 182 202	22,22,22	30 152 153	52.23		•	~
		=	E S	180 180 180	320	180 180	222	180 180	222			
		. of	Pads	999	999	n ဃ လ	60 80 80	222	0010			
		•-	Deg.	222	222	38.25 38.25 38.25	38.25 38.25 38.25	30.6 30.6 30.6	30.6 30.6 30.6			
		3	8	152 155 156	157 158 159	160 161 162	163 164 165	166 167 163	156 171 173			

TABLE 10. 13

31" 0.D. x 151/2" 1.D. THRUST BEARING $(\underline{L} = 0.5)$

9

In. (rpg = 50 ; 0gs =

. 23.33

Pivot Pitch Disseter

In. (taste = 0.193

In. (k = 0.85)

İ

Inverse Pad Thickness - 2.99

Effective Searing Area - 480

							8.25	7.01	2.0 2.0 2.0 2.0 5.0 5.0 5.0 5.0 5.0 5.0 5.0 5.0 5.0 5	18.5. 18.2.	15.99 19.99 19.99	200 s			
					۵	1	2.2.2 2.3.4	NA S	# # # # E	5.4	3.17	2. 4.4. 2. 48.6. 3.6.6.	** ** **		• • • • • • • • • • • • • • • • • • • •
					1.01	1	22.0	87.5 8.7.5 8.7.5	287.0	175.3	226.5	237.5			<u> </u>
					J	li	727	32.5	388	28.5	1 <u>E</u> 3	323			
				<u> </u>		i	, 25°	7.72	355	88	288	201 202 767			
				8	į		* % %	8,8,8	822	2538	£83	232			
		0.5	0.85)	53 t e	7.		25.6	153	23.55	301	32.55	222			
71		1			_6	*	223	222	555	28.3	136 161 161	150 158 165			····
THE S		BEARING (L =	8 41	ė ė	æ	đ	0.00171	0.00143	0.00152 0.00104 0.0095	0.00157	0.00109 0.00088	0.00095 0.00095			
PROGRA	77	THRUST	- 2.385	- 23.72 F Inlet	*		94.4 82.5 77.8	3.5	100 91 85.6	100 13.5	91.9	8.80			
	TABLE NO.	x 151/2" I.D.		7	H.		84 63.5 59.5	282	1.88 4.48	71.78	57. 53.51	kki.			
MALON INNIST BRADEL PROGUE - THANK I		.D. x 151/	Effective Bearing Area Average Pad Thickness	Pivot Pitch Diemeter - 23.72 Oil - 2190 T at 115°F Inlet	q	ę,	0.00060	0.00140	0.00125	0.00122	0.00097	07000°0 0.00000 0.00000			
		31" 0.D.	Effect	Pivet 0	-1s	10-6 In-	382	388	# 22 E	22%	23.6° æ	322			
					•x10	In/In	-37	£	huw	vo v	115	12 22	·	•	ten men i i
					-0x10-	in/in	152 188 195	3,828 33,03,03	155 139	137 193 193	% 177 173	138 138 138			
					-	Ē	180 180 180	222	8 8 8	388	180 180 180	222			
					No. of	Pede	999	999	ထားသေး	യയ	222	555			
					•	Ġ	222	2222	38.25 38.25 38.25	38.25 38.25 39.25	30.6 30.6 30.6	30.6 30.6 30.6			
					3	Š	190	193 194 195	196 198	2002	202	205 207 207			

TABLE NO. 15

31" 0.0. x 151/2" 1.0. THRUST BEARING ($\frac{L}{R}$ = 0.5

Sq. In. (k = 0.05)In. $\begin{pmatrix} t_{max} \\ k \end{pmatrix}$ In. $(r_{p}k = 4.7 + p_{p}k = 50)$ Average Pad Ihickness - 2.385 Effective Bearing Area - 480

Pivot Pitch Dismeter - 22.78 Oil - 2190 I at 115F Inlet

		ı							
H.P. 101		0.7.7. 0.7.7.7.	19.5	7.5.2	22.8 12.6 15.3		75.55 12.55 12.55		
5	\$	3.00 2.45 2.32	5.25 5.25 5.25 5.25 5.25 5.25 5.25 5.25	3.3	9.4 8.63	3.15 2.65 2.01	25 de 18		
2 Lora 10-3	4	138.2 268.0 343.5	183.5 339.0 416.0	122.7 272.6 379.0	97.9 363.0 453.0	147.8 219.0 391.6	173.1 325.6 520.6		
3	ž	252	28£	576 1490 2371	2030 3107	710 1103 2160	1660		
ANG	ĩ	263 716	382	32%	52,88	322	25.2		 -
1	*	288	% 7.2% % 7.2%	388	385	25.23	2217		-
TANG	.	355	32.02	222	152	171	163		 -
,5		55 55 153 153	2223	123	22,23	138	223		
4	ţu	0.00118 0.00086 0.00081	0.00131 0.00100 0.0095	0.00000	0.00120	0.000% 0.000% 0.00052	0.00078 0.00068 0.00061	-	
*	_	100 85.7 80	100 84.5 78.6	100 87.2	8,50	100 100 98.6	853%		
N. III		3.8.3	35.7	30.5	35.7	14.3	21.7		
Ę	l th	0.00111	0.00120	0.00090	0.00120	0.00076	0.00078 0.00061 0.00040		
- x10°	10-6-1n-	25 31	328	. 679. 26.	3%%	\$22	18		 -
x10	in/in	87 22 21	ጽሄድ	130 69 55	85 85 85 85 85 85 85 85 85 85 85 85 85 8	100 85 62	120 83 63		
-0x10*	tn/sn	55 88 188	164 213 218	80 124 137	72 155 169	88 80 20 20 20	83 120 139		
B	RPM	130 130	3333	91 98 180 180	888	180 180	282		
No. of	Pads	999	999	60 10 60	80 80 80	222	100		
• I	Deg.	222	222	38.25 38.25 38.25	38.25	30.6 30.6 33.6	30.6		
3	No.	203 209 210	211 212 213	214 215 216	217 213 219	220 221 222	52 53 53 53 53 53 53		

THE COURT PARTIES TROOM - PROST

 31° 0.0. x 15 $V2^{\circ}$ 1.0. THRUST BEARING $\left(\frac{L}{R} = 0.5\right)$ TABLE NO. 16

		a 3	Ē	3.43	9.5.6 3.6.8	7.72	
		0	<u> </u>	3.55	5.35	R.	
		4-01x-E	5	#3.5. %2.0	203.0 2.5.5.5 2.5.5.0	645.0	
		ì		8.6	25,7	403	
-	-	S A		28.2	¥ 50	3	
	2			325	£2.	Ř	
0.85)	a. }	ANG		87.1	2.3	₹	
Sq. In. (k = 0.85) In. (t = 0.154) In. (r = 0.154)		<u>,</u> 6		555	25	2	
8 5 5	!	<u>.</u> -	ë	0.00131	0.00136	6000	
- 2.385	Inlet	¥.		93.1 8.6.			
.	t 1150F	N.		14.3	35.7		
Effective Bearing Ares - 430 Average Pad Thickness - 2,35 Plvot Pitch Diameter -	041 - 2190 T at 1150F Inlet	d cje	1n	0.00130	0.00126	;	
Effect: Average Pivot F	8	-d≈'	10-6 In-	242	222		
		-x10	in/in	2%%	835		
		*01x0#	in/in	155 182	135 236 236		
		x	2	180 180	888		
		No. of	Pade	to to to	ഗോഗ ഗ		
		o ^L	Deg.	38.25 38.25 38.25	38.25 38.25 38.25		
		Š	2	22 22 23 24	និនិនី		

						K.P. JOI		t- 10-0	44 L/	
						=		13.7	KKK	
						þ	Ł	3.63	6.83 5.08	
						"101"10"	1	266.7 644.0 814.0	286.5 236.0	
						×	ž	£3% %82 %82	2811	
				_		AKG	ž	95.35 100 100	8 E 3	
				8		T M	•F	23.0	¥22.3	
		اٽ	In. (k = 0.25)	05 = 50		TANG	•	153 175 189	181	
-		= 0.5	In. $(k = 0.85)$			<u>,</u> 6	₽.	85 85 85 85 85 85 85 85 85 85 85 85 85 8	888	
	,	THRUST BEARING (L =	Sq. In.	- S		<u></u>	In	0.00133	0.00137	
PACRA	7	THRUST	- 760	- 29.25	Inlet	¥.	_	100 89.7 83.4	100 88.5 84.2	
12	TABLE NO. 17		A546		2	*		35.7 47.2 48.5	35.7 47.5 49.1	
MATER THEIRS TRANSPORM - PRINT	н	0.D. x 191/2" I.D.	Effective Bearing Area Average Pad Thickness	Pivot Pitch Dismeter	- 2190 T at 115°F Inlet	rt a	th	0.00124	0.00123	
200		\$ h	Effect	Pivot 5	911	내	10-6 in-	% ₹%	388	
						"x10	in/in	328	3 K &	
						**************************************	in/in	102 158 186	1183	
						=	RPM	888	888	
						No. of	Pads	€ 0 €0 €0	80 BO BO	
						٠	Deg.	38.25 38.25 38.25	38.25 38.25 38.25	
						***	Š.	333	3333	

						H.P.	i	5.0 57.0 57.0	2000 2000 2000 2000	0.88 80 80 80 80 80 80 80 80 80 80 80 80 8	
						į		6.30	6.00	322	
						2 tot x 10-3	1	45.9 75.2 93.7	35.2 74.7 191.0	12.7 \$6.7 \$6.7	
							ž	1821 1631	2 525	126.25	
					•	ANG	Ĩ	X28	25.28	**	
				_	₽ #	, a	<u>پ</u>	26.5	888	352	
	-	6	0.85)	0.154	* d	TANG	.	388	325	3%2	
4		20 = 18E	In. (k = 0.85	(tage = 0.154	1 8 d	.5		283	223	22 23 23 23	
MAIN THIS RAILE PROBLE - PART		BEARING (L =	<i>\$</i>	ė	ė ė	<u>~</u>	et.	0.00072	0.00065	0.00069 0.00044 0.00337	
100		THRUST	- 181	- 1.462	- 14.25 F Inlet	6		97.2 87.4 82.2	25.1 28.1	888	
	TABLE NO. 18	1/2" I.D.			eter et 1150	**	_	52.1 52.1 50.2	8.2.2 8.2.2 2.2.8	0 21.4 35.7	
N In St		× 9	Effective Bearing Area	Average Pad Thickness	Pivot Pitch Diameter - 14.2 Oli - 2190 T at 1150F Inlet	, s	ş	0.00060	0.00063	0.00069	
	į	19" 0.D.	Effect	Averag	Pyot Oil	46	10-6 in-	272	288	728	
						= x10*	11/10	8 8 Q	おれれ	233	
						-x10*	in/in	27.8	15 63 112 64	488	
						= 1	Ē	888	ទី នីនី	888	
						. og	8	202	ക മേ	222	
						. -	ġ	222 	38.25 38.25	33.6	
						3	3	2002	ភ ង្គ	123	

TABLE NO. 19

75" 0.D. x 371/2" 1.D. THRUST BEARING ($\frac{L}{R}$ = 0.5

Sq. In. (k = 0.85)In. $(\frac{t_{avq.}}{R} = 0.154)$ In. $(r_p\% = 50 \ \text{i} \ \rho_p\% = 50)$ Effective Bearing Area - 2810 Average Pad Thickness - 5.77

Pivot Pitch Diameter - 56.25

011 - 2190 T at 1150F Inlet

			1		
	H.P. TOI		53.1 61.8 47.3	53.6 47.3 51.4	
	Pror	adó	16.0 16.7 13.1	12.2 11.5 10.9	
	"IOT*10-3	lbs	1985.0 2200.0 2260.0	2825.0 2544.0 3180.2	
	MAX.	ps1	3203 4 390 2927	4517 2819 4311	
	PAVG	pei	706 783 802	100 4 902 1128	
	T,	o.F	272 318 263	319 254 306	
	TAVG	oF	196 210 206	225 213 232	
	F.	o.F	153 157 160	163 162 165	
Inlet	4	in	0.00205	0.00161	
	0 ⁶		76.3 74.6 81.0	78.3 86.5 82.8	
t 115°F	, a		50 49.8 47.5	46.6 46.6	
011 - 2190 T at 1150F Inlet	, ain	- ut	0,00060	0,0000.0	
011	₽ 48,	10-6 in-	222	1202	
	•x10	1n/in	888	388	
	0x10, .x10,	1n/in	170 183 137	136 106 115	
	2	RPM	888	888	
	No. of	Pads	990	8 00	
	•	Deg.	51 38.25	38.25 30.6 30.6	
	3	No.	243	250 252 252	

TABLE NO. 20

50" I.D. THRUST BEARING $\left(\frac{L}{R} = 0.5\right)$ 100" 0.D. x

In. (tave. = 0.154 Sq. In. (k = 0.85)Effective Bearing Area - 5000 Average Pad Thickness - 7.70

Pivot Pitch Diameter - 75

In. (rp% = 50; 9p% = 50)

011 - 2190 T at 115°F Inlet

H.P. 701		352	13 8 118 132				
Prot	udb	39.2 47.8 28.2	27.4 26.7 25.7				
"TOT × 10"	1bs	3730 4380 4890	5280 5151 6493				
MX.	psi	4268 6451 3995	5939 3758 5862				
PAVG	psi	745 876 977	1028 1028 1296				
TMAX	9F	305 352 301	367 289 353				
TAVG	9F	206 226 221	237 226 248				
<u>"</u> 8	ą,	156 160 163	165 165 165				
£"	i	0.00284	0.00226				
×.		74.5 72.1 79.4	76.8 83.0 81.1				
1º.		8.67 8.67	48.5 46.7 47.4				
h nin	-	0,00060	0,000,0				
Fx106 K= 1	10-6 in-	11 21 9	11,01				
P,x106	in/in	222	272			 	
mgx10 ⁶ m _r x10 ⁶	1n/1n	179 175 130	146 116 122				
z	RPM	100	868				
No. of	Pads	990	3 10				
•	Deg.	51 51 38.25	38.25 30.6 30.6				
3	No.	253 254 255	256 257 253				

MARINE THRUST BEARING - Phase I

Table No. 21

Oil - 2190 TEP at 115°F Inlet

R in.	9.5	22.5	37.5	50
L in.	4.75	11.25	18.75	25
tavg in.	1.236	2.924	4.88	6.50
θ _T - degrees	51	51	51	51
n n	6	6	6	6
r _p %	50	50	50	50
ep %	50	50	50	50
N - RPM	100	100	100	100
$m_{\Theta} \times 10^{-6} in/in$	187	228	215	211
m x 10 ⁻⁶ in/in	25	27	25	23
K x 10 ⁻⁶ in ⁻¹	47	30	21	17
h _{min} - in.	0.00040	0.00040	0.00040	0.00040
r _m %	50.2	46.5	49.2	49.0
θ _m %	81.7	75.5	70.7	68.7
T _{GR} - of	134	145	151	154
TAVG - OF	155	181	204	220
T _{MAX} - °F	188	251	286	300
PAVG - P.S.I.	377	565	666	704
P P.S.I.	1203	3004	4625	5682
W _{TOT} x 10 ⁻³ - Lbs.	68.1	572.0	1870	3520

for 9 19.0 15.3 14.4 11.1 10.5 46.8 8.85 8.65 6.65 26.2 21.4 17.2 9.3 32.1 32.9 32.1 23.6 "TOI x 10-3 916.1 1147.6 362.3 1475 215.0 346.1 296.9 469.1 557.6 330.5 264.5 529.8 969.9 1271 287.6 661.0 767.6 ğ 230 PMAX 2663 732 732 256 173 173 610 1019 1267 198 2011 35,35 2574 4005 3873 PAVG In. $\binom{t}{avq_{\pm}} = 0.117$ In. $(r_p\% = 52.61 \cdot 0_p\% = 50)$ 1 718 765 1165 233 844 334 334 198 198 319 138 **388** 281 THAX 202 2252 282 374 322 222 361 ñ TAVG 888 122 SQF 855 222 288 Sq. In. (k = 0.85) 282 333 4 32 " I.D. THRUST BEARING ($\underline{\underline{L}} = 0.379$ Œ 23.03 35,5 152 288 <u> 488</u> 128 146 153 165 165 4 <u>-</u>-5 - 42.25" Effective Bearing Area - 1,085 Oil - 2190 I at 115°F Inlet Average Pad Thickness - 3.00 0 K TABLE NO. 22 P. III Pivot Pitch Diameter e e 0.00242 0.00040 0.00120 0.00020 0.00297 0.00131 0,0000.0 Ę 51 1/2 " 0.D. x rx106 K= 1 2Rc in/in 10-6 in-625 325 385 300 348 958 333 ኯ፟፟፠፟፟፟፟፟፟፟፟፟፟፟ 222 ភូនុភ្ 244 5778 | *01x04 | in/in 322 208 185 5223 223 **3**222 3258 212 888 888 F. P. 333 988 888 888 88 No. of Pads 999 222 222 222 222 222 22 30.6 30.6 30.6 30.6 30.6 33.6 25.5 25.5 25.55 25.55 25.5 25.52 • ġ 98 ŝ **%**%% 322 272 222 22,52

H.P. TOT

47.5 48.9 46.8

12.5 17.7 145

322

152 42.6 52.0

19.2 12.3

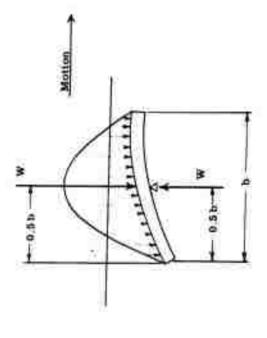
8 1 1 2 1 3 1 3 1

627

281



Figure 1 MOMENT EQUILIBRIUM



Restoring Moment: M # 0

(a)

ē

Restoring Moment: M = 0

2.385" Thick Pad (Bending Incl.) 0,51L 185°F Central Pivot Minimum Film Thickness: .001" Speed: 320 RPM T95.0 36,600 Lbs. Bearing Pad: 31" OD, $15\frac{1}{2}$ " ID, $38\frac{1}{4}$ Subtended Angle 0.51 L 204°F Flat Pad Central Pivot Oil: 2190T, 130°F at Pad Inlet 22, 200 Lbs. 0.5 8T 3 Figure 2 $T_{max} = 179^{O}F$ Flat Pad Optimum Pivot (a) 0.61 9T W = 39,600 Lbs.Location Pivot

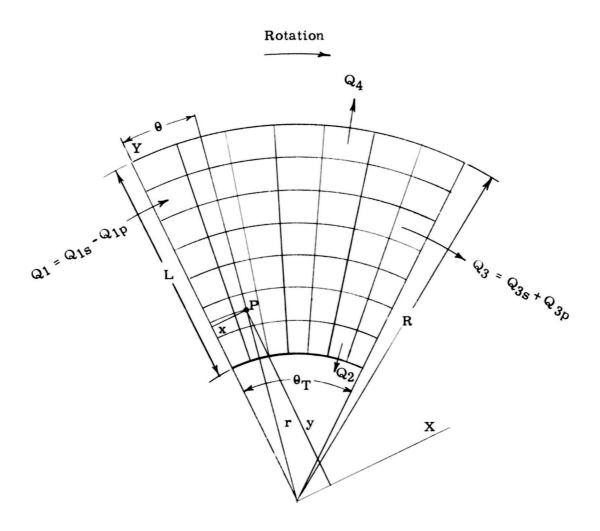
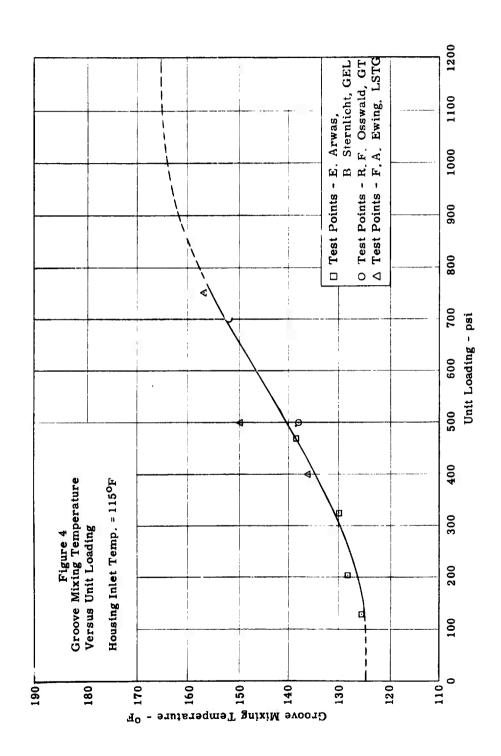


Figure 3
Co-ordinate System



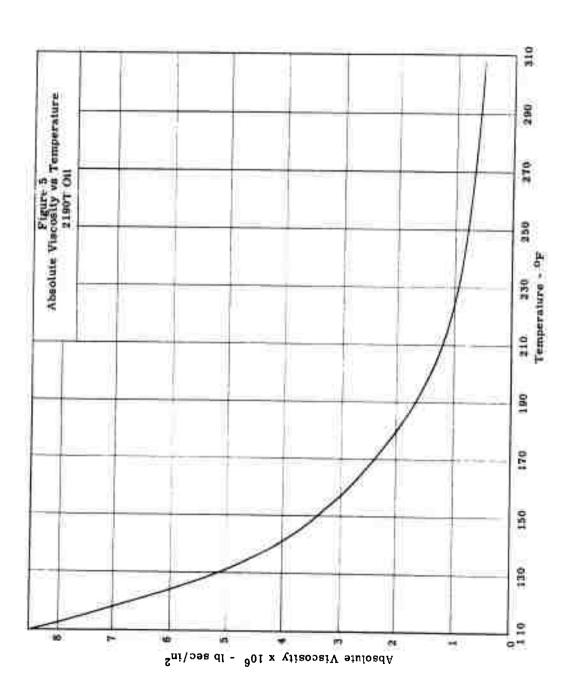


Figure 6 MESH NOTATION

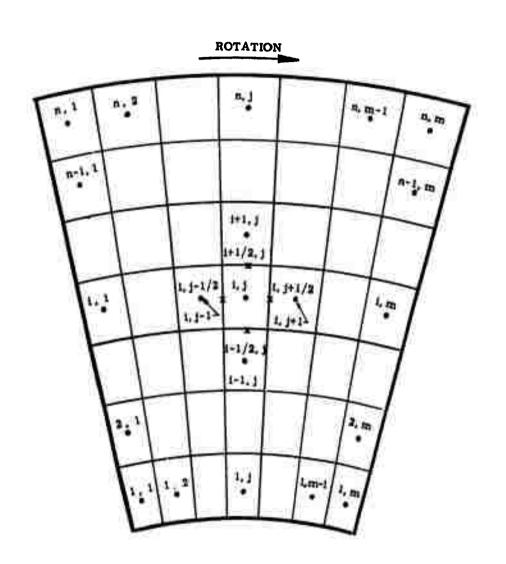
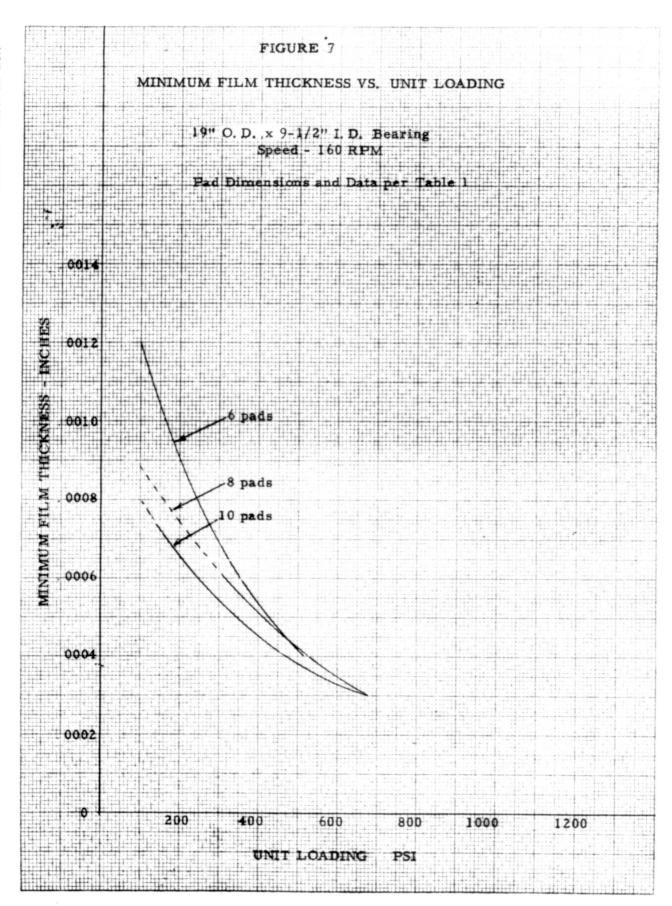
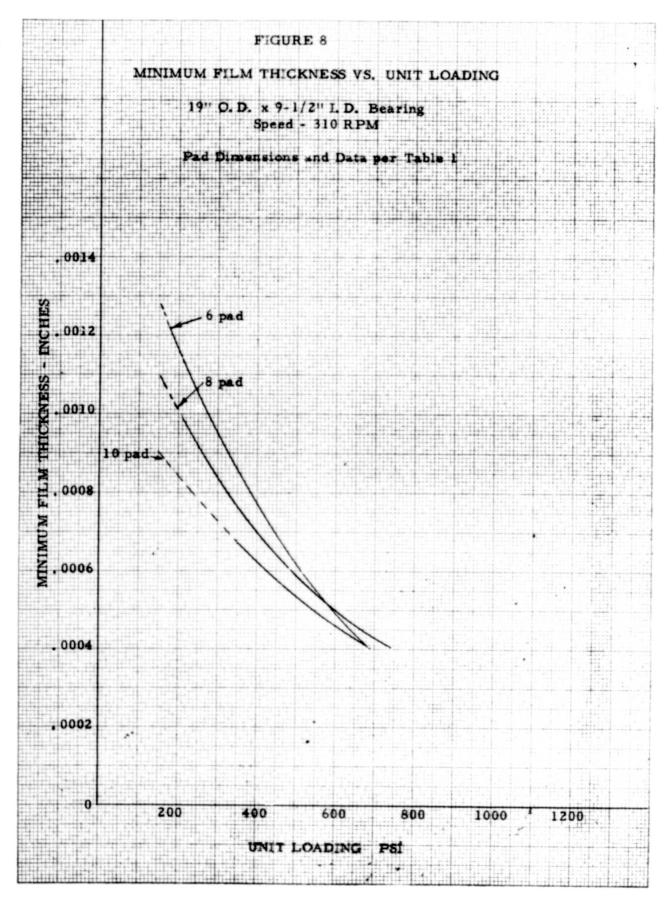
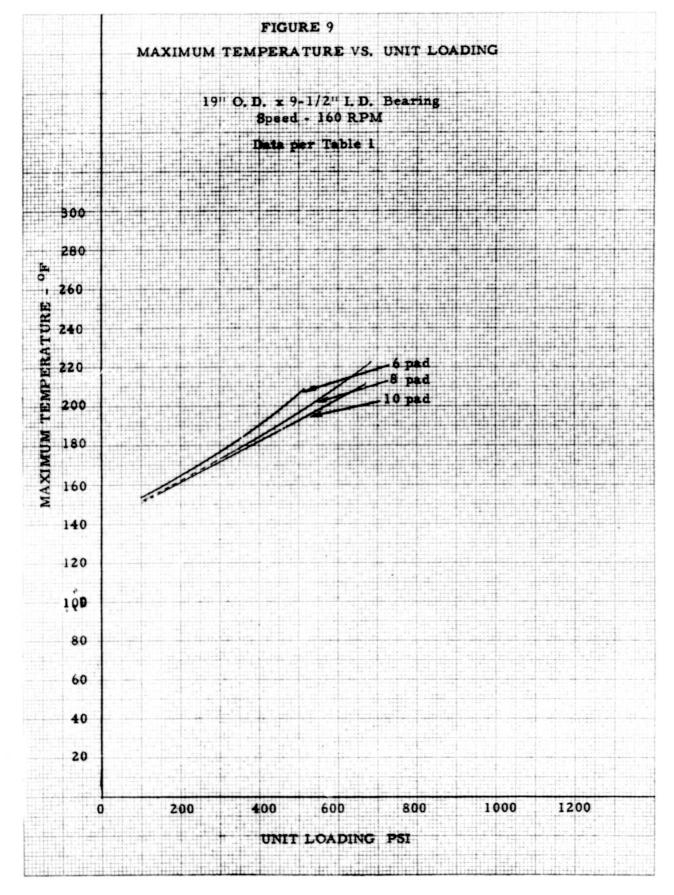


Figure 6

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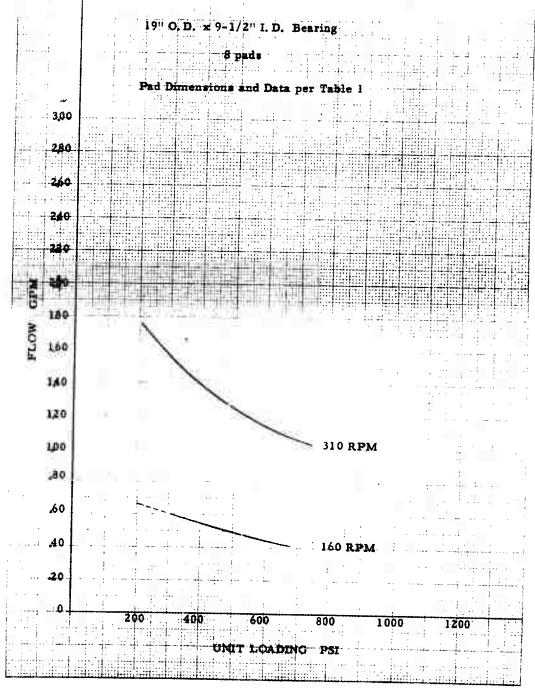


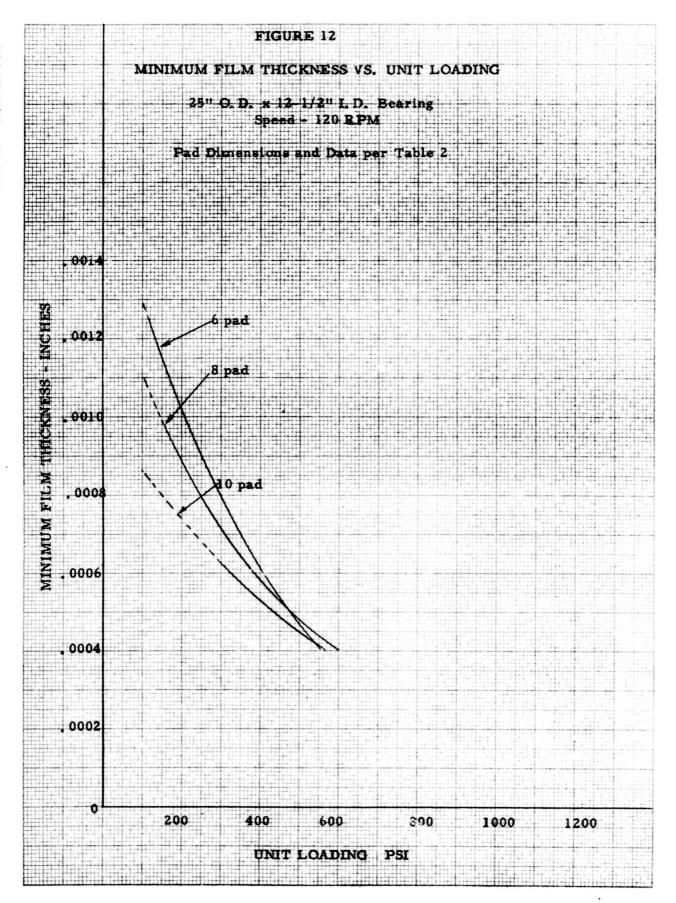
MAXIMUM TEMPERATURE VS. UNIT LOADING 19" O. D. & 9+1/2" I. D. Bearing Speed - 310 RPM

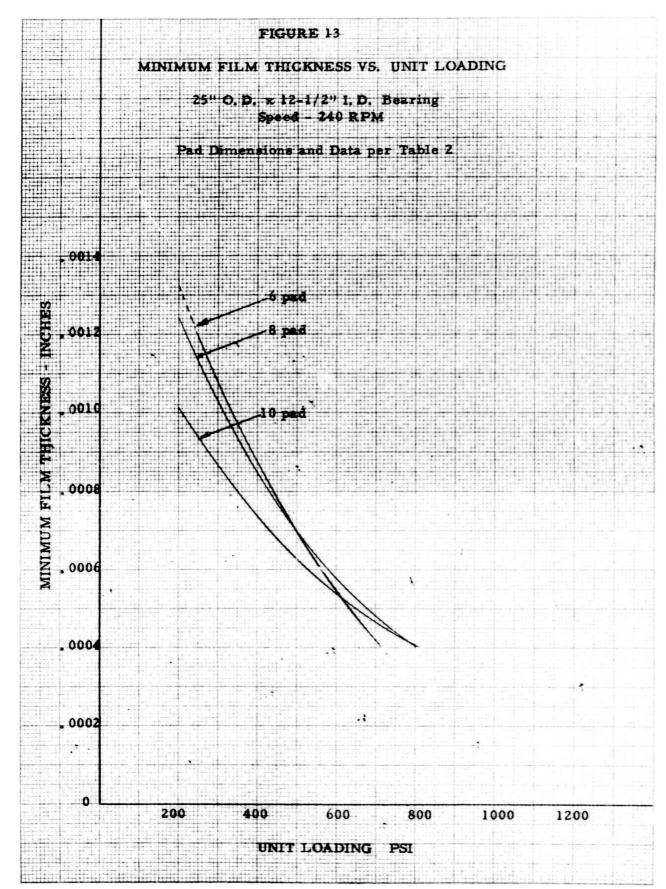
UNIT LOADING PSI

FIGURE 10

FIGURE 11
HYDRODYNAMIC OIL FLOW VERSUS UNIT LOADING







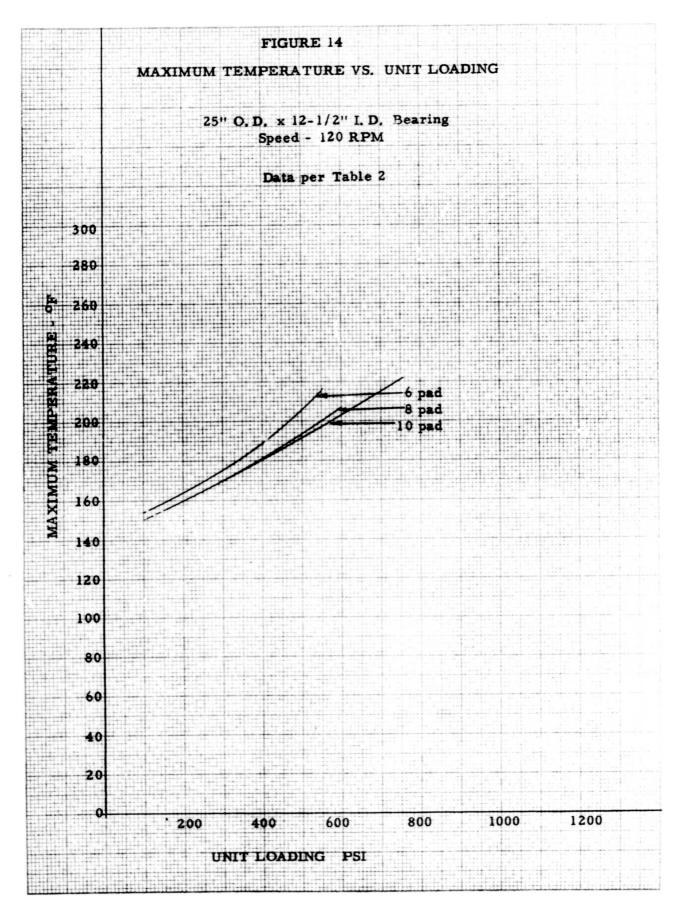
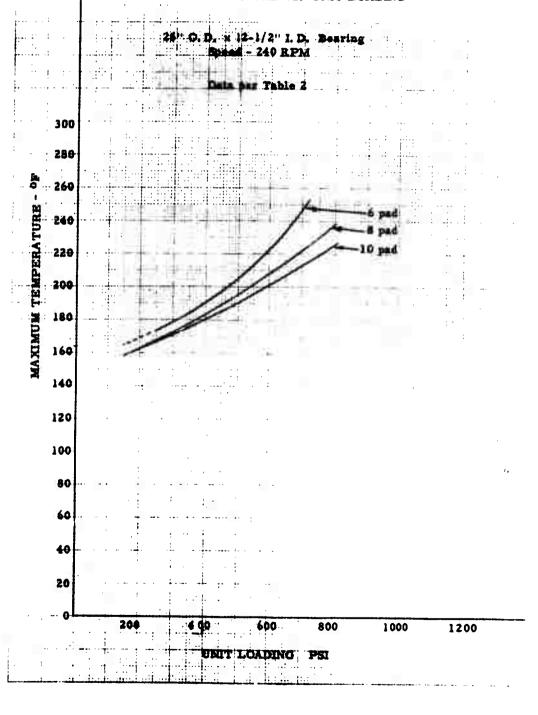


FIGURE 15
MAXIMUM TEMPERATURE VS. UNIT LOADING



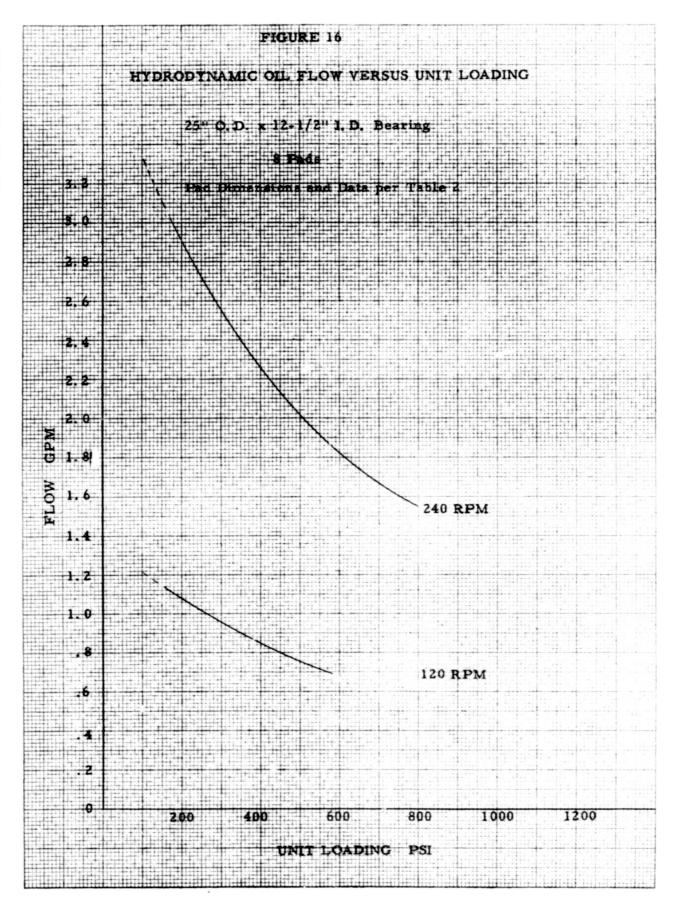
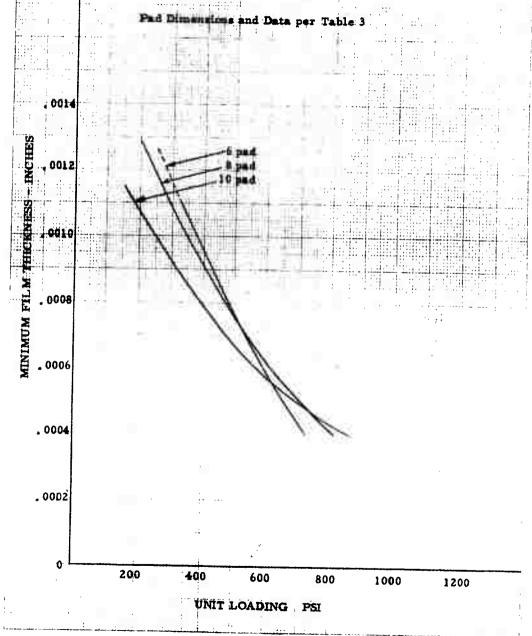


FIGURE 17
MINIMUM FILM THICKNESS VS. UNIT LOADING

31" O. D. x 15-1/2" I. D. Bearing Speed - 180 RPM





.

MINIMUM FILM THICKNESS VS. UNIT LOADING

31" O. D. x 15-1/2" I. D. Bearing Speed - 320 RPM

Pad Dimensions and Data per Table 3

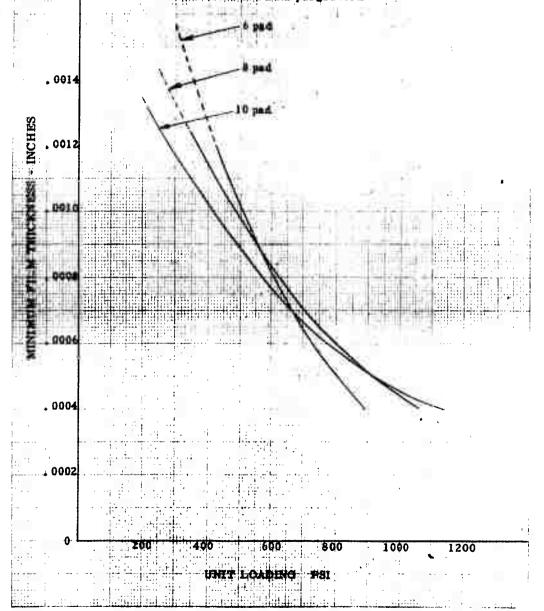


FIGURE 19 MAXIMUM TEMPERATURE VS. UNIT LOADING 31 . O. D. x 15-1/2" L.D. Bearing Speed - 180 RPM MAXIMUM TEMPERATURE --240 -220 UNIT LOADING PSI

FIGURE 20 MAXIMUM TEMPERATURE VS. UNIT LOADING

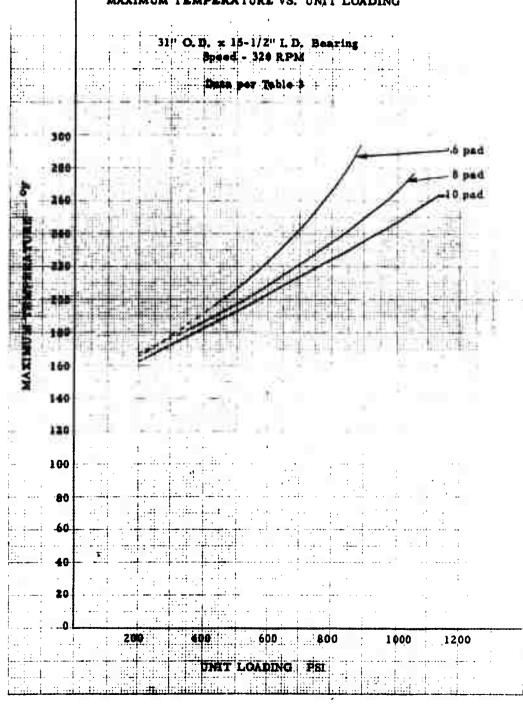


FIGURE 22 MINIMUM FILM THICKNESS VS. UNIT LOADING 37" O. D. x 18-1/2" I. D. Bearing Speed - 180 RPM 10 pad . 0004 0002 1200

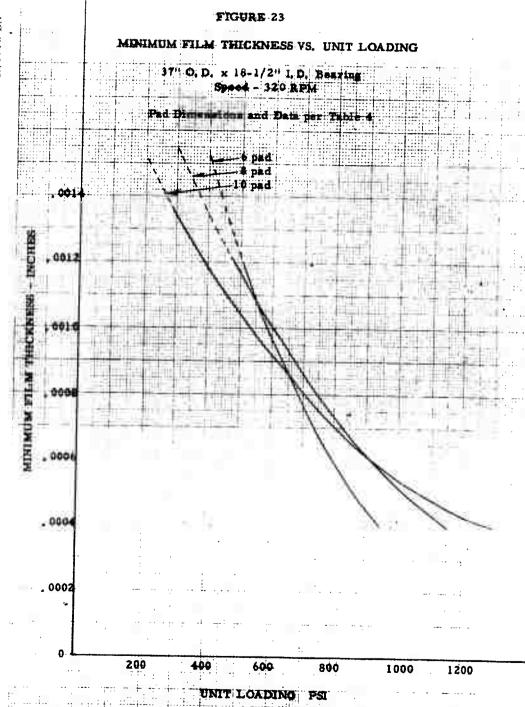


FIGURE 24
MAXIMUM TEMPERATURE VS. UNIT LOADING

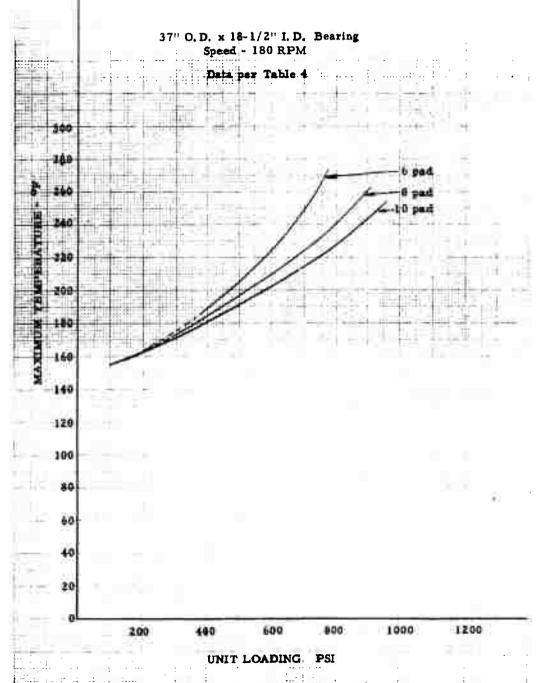


FIGURE 25
MAXIMUM TEMPERATURE VS. UNIT LOADING

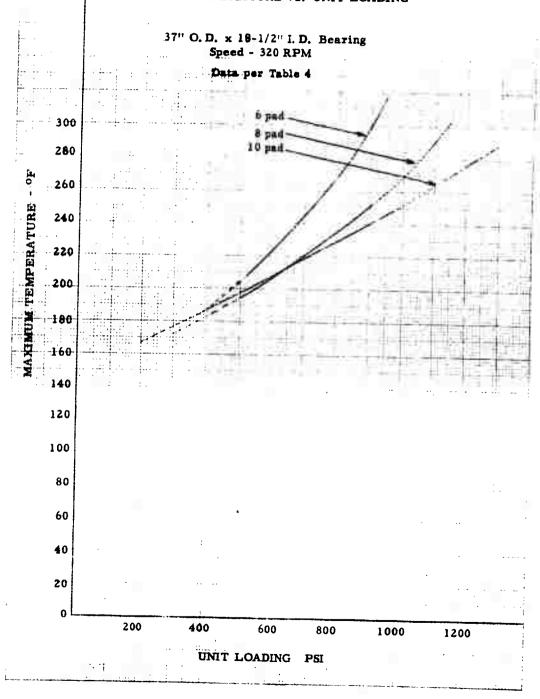


FIGURE 26 HYDRODYNAMIC OIL FLOW VERSUS UNIT LOADING 37" O. D. x 18-1/2" I. D. Bearing & pads Pad Dimensions and Data per Table 4 200 1000 1200 UNIT LOADING PSI

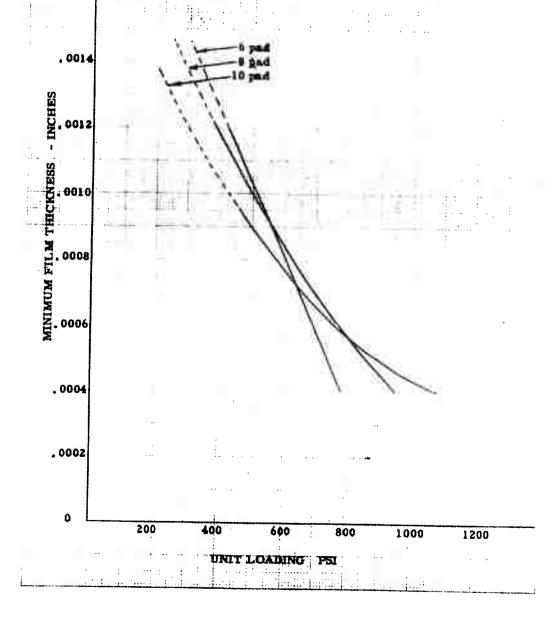
FIGURE 27 MINIMUM FILM THICKNESS VS. UNIT LOADING 39" O. D. x 19-1/2" L.D. Bearing Speed - 150 RPM . 0014 MINIMUM FILM THICKNESS - INCHES . 0012 . 0010 . 0008 . 0006 . 0004 . 0002 200 600 800 1000 1200 UNIT LOADING PSE

FIGURE 28

MINIMUM FILM THICKNESS VS. UNIT LOADING

39" O. D. x 19-1/2" L.D. Bearing Speed - 200 RPM

Pad Dimensions and Data per Table 5



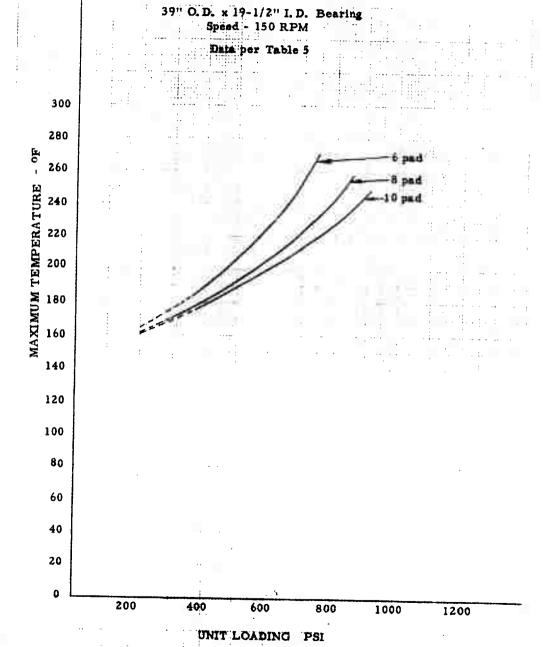


FIGURE 30 MAXIMUM TEMPERATURE VS. UNIT LOADING 39" O. D. x 19-1/2" I. D. Bearing Speed:- 200 RPM UNIT LOADING

TABLE 31 HYDRODYNAMIC OIL FLOW VERSUS UNIT LOADING The state of the s 39" O.D. x 19-1/2" I.D. Bearing Pad Dimensions and Data per Table 5 12 8 6 2 200 400 600 : 800 1000 1200 UNIT LOADING

. 0002

200

400

UNIT LOADING PSI

600

800

1000

1200

MINIMUM FILM THICKNESS VS. UNIT LOADING

41" O. D. x 20-1/2" I. D. Bearing Speed - 200 RPM

Pad Dimensions and Data per Table 6

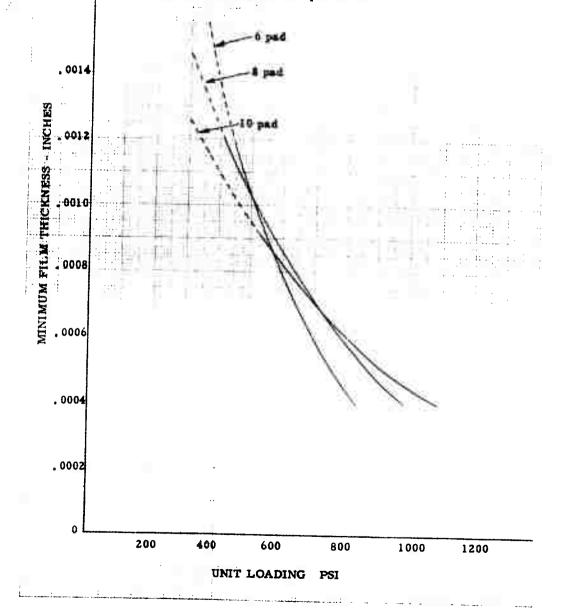


FIGURE 34 MAXIMUM TEMPERATURE VS. UNIT LOADING 41" O.D. x 20-1/2" I.D. Bearing Speed - 100 RPM 180 120 100 -60 800 1000 1200 UNIT LOADING PSI

41" O. D. x 20-1/2" I. D. Bearing Speed - 200 RPM

Data per Table 6

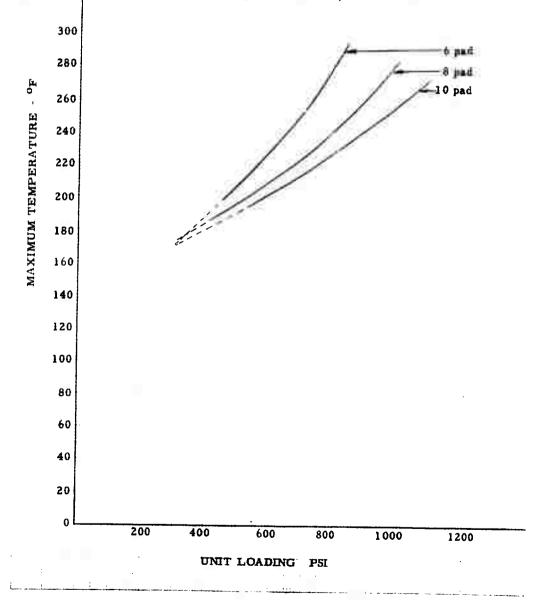


FIGURE 36 HYDRODYNAMIC OIL FLOW VERSUS UNIT LOADING 41" O. D. x 20-1/2" I. D. Bearing Pad Dimensions and Data per Table 6 200 RPM 100 RPM 800 1000 1200 UNIT LOADING PSI

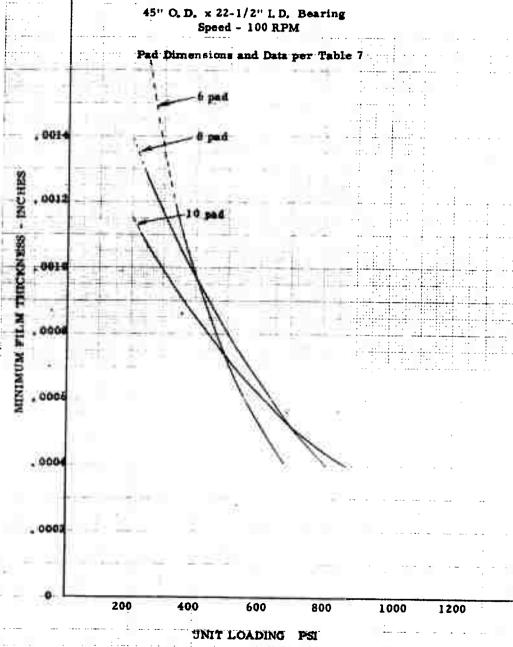
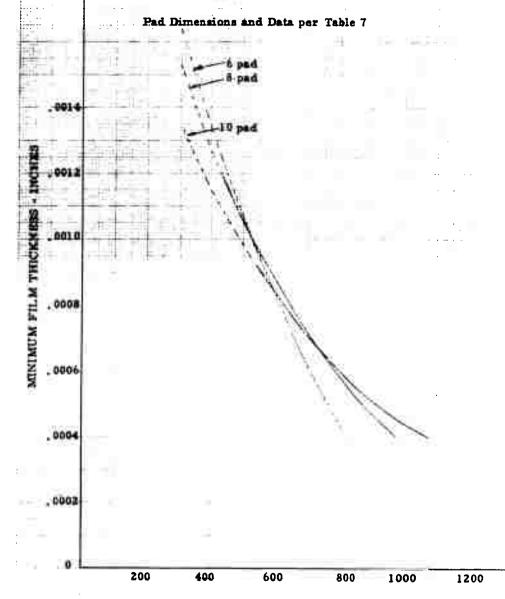


FIGURE 38

MINIMUM FILM THICKNESS VS. UNIT LOADING

45" O, D, x 22-1/2" I, D, Bearing Speed - 170 RPM



UNIT LOADING PSI

45" O, D. x 22-1/2" I. D. Bearing Speed - 100 RPM

Data per Table 7

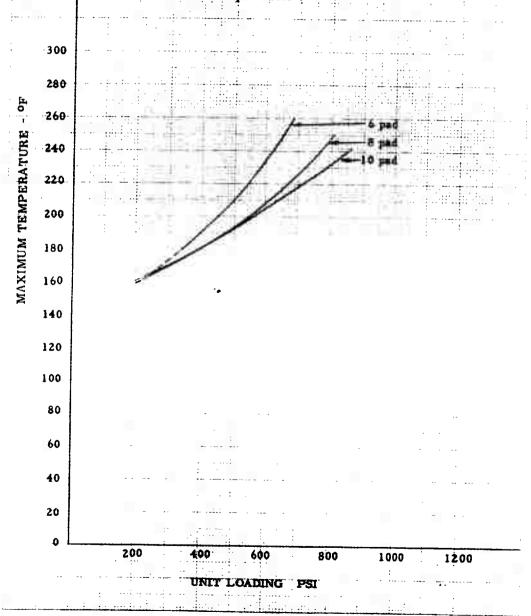
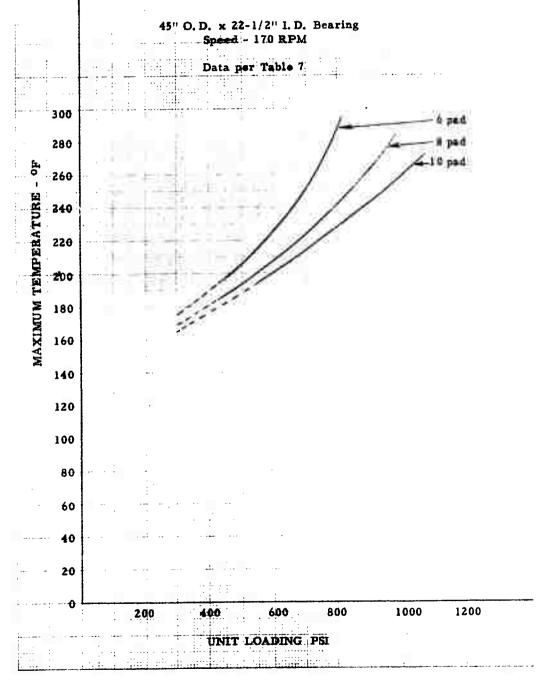
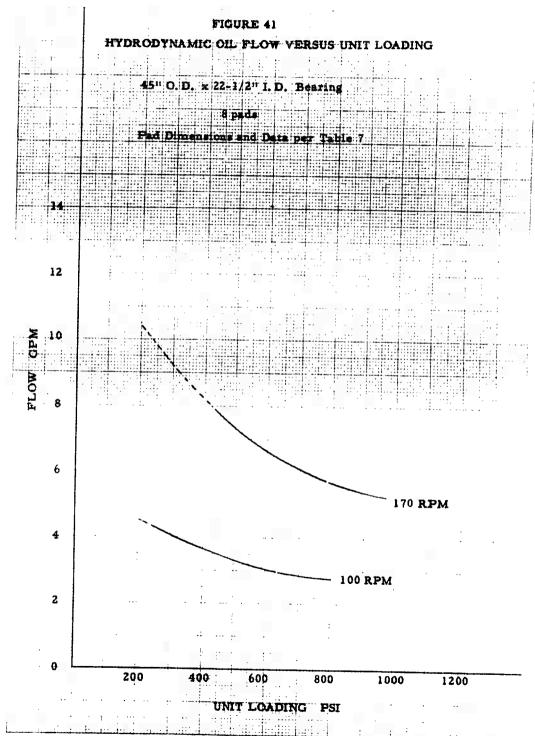


FIGURE 40 MAXIMUM TEMPERATURE VS. UNIT LOADING

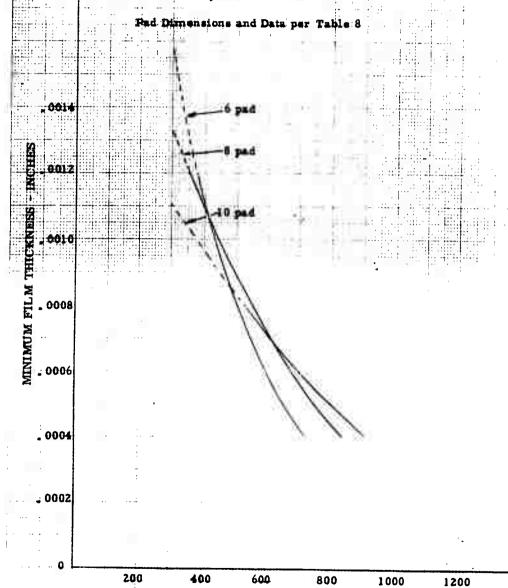




MINIMUM FILM THICKNESS VS. UNIT LOADING

50" O. D. x 25" I. D. Bearing Speed - 100 RPM

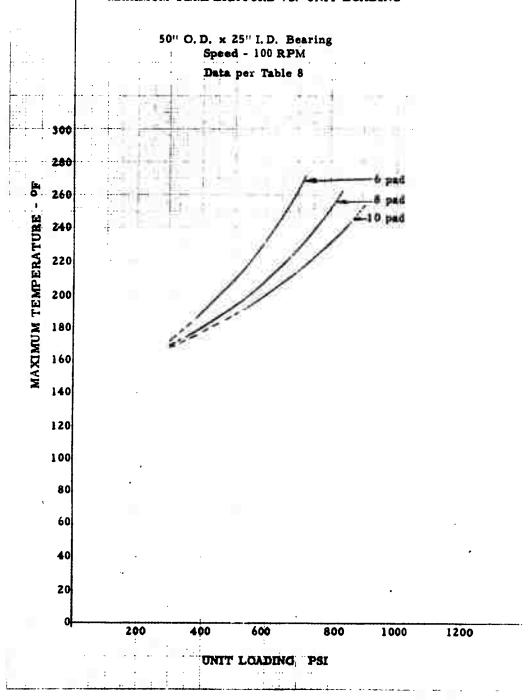
FIGURE 42



UNIT LOADING PSI

FIGURE 43 MINIMUM FILM THICKNESS VS. UNIT LOADING 50" O. D. x 25" I. D. Bearing 50444 - 170 RPM . 0014 MINIMUM FILM THICKNESS - INCHES 0012 . 0010 . 0008 . 0006 .0004 . 0002 200 400 600 800 1000 1200 UNIT LOADING PSI

FIGURE 44
MAXIMUM TEMPERATURE VS. UNIT LOADING

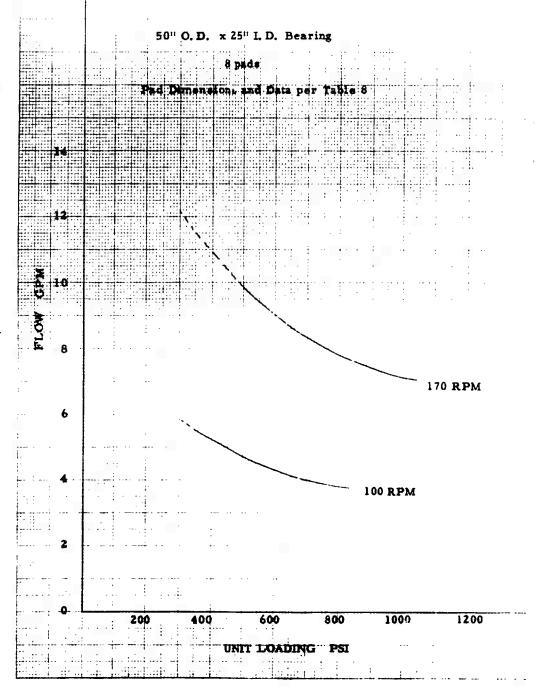


UNIT LOADING

PSI

165 x 220

FIGURE_46
HYDRODYNAMIC OIL FLOW VERSUS UNIT LOADING



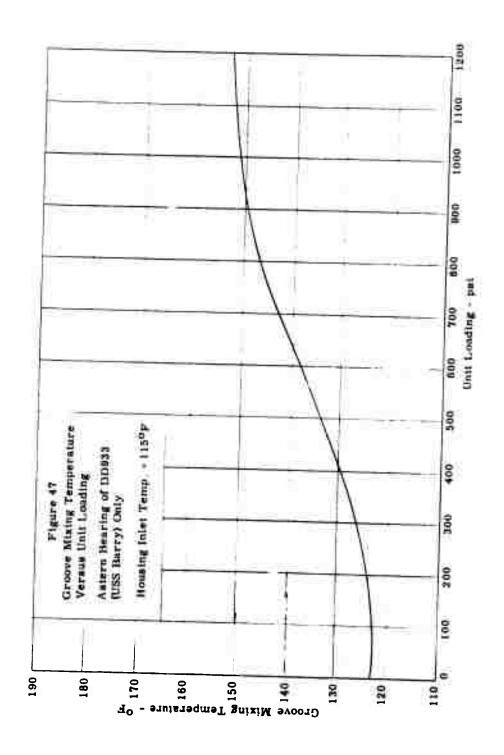
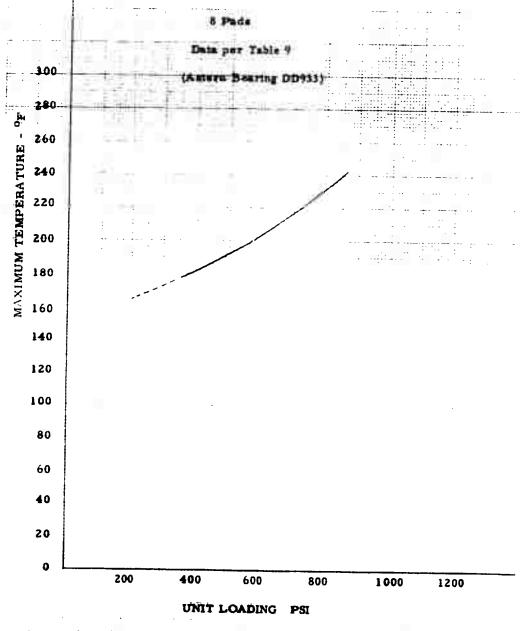


FIGURE 48 MINIMUM FILM THICKNESS VS. UNIT LOADING 26" O. D. x 17-1/2" L.D. Bearing Speed - 160 RPM MINIMUM PILL 0000 . 0004 . 0002 1000 1200 800 400 600 200 UNIT LOADING PSI



MAXIMUM TEMPERATURE VS. UNIT LOADING

26" O.D. x 17-1/2" L.D. Bearing Speed - 160 RPM



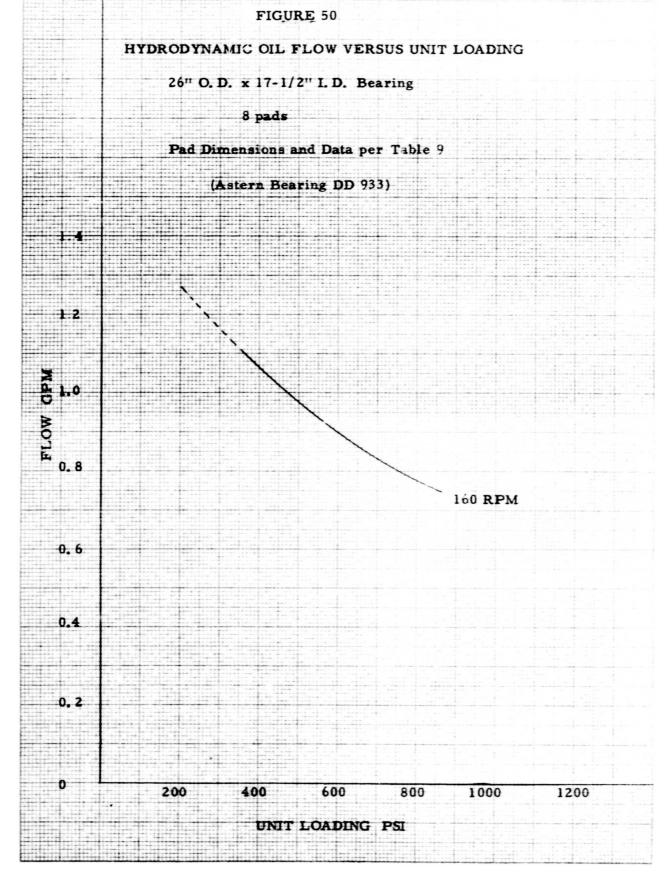
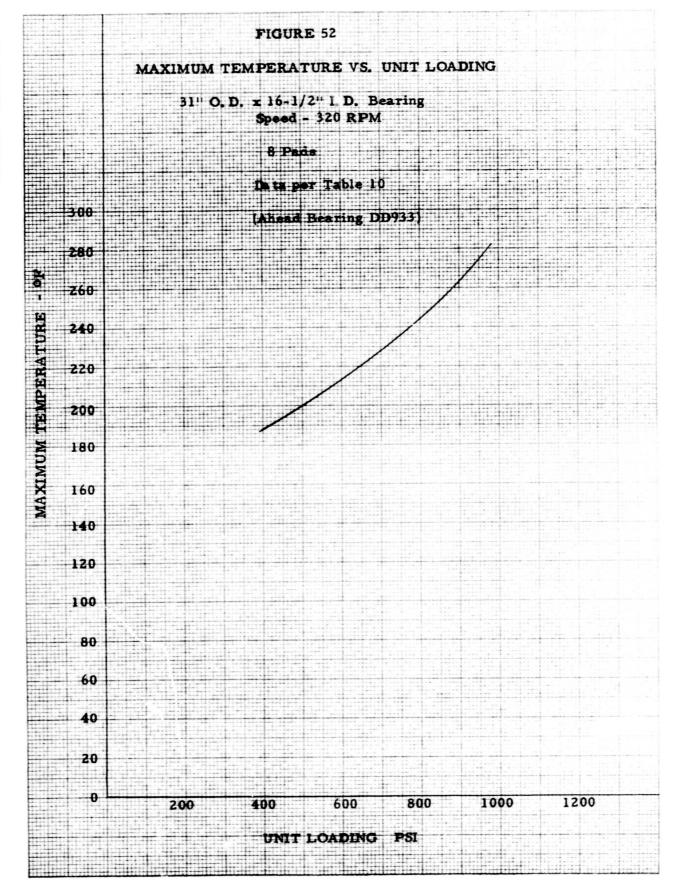


TABLE 51 MINIMUM FILM THICKNESS VS. UNIT LOADING "31" O.D. x 16-1/2! I.D. Bearing Speed - 320 RPM Pad Dimensions and Data per Table 10 .0012 MINIMUM FILM THICKNESS .0010 .0008 . 0006 .0004 . 0002 600 800 1000 1200 UNIT LOADING



3

FIGURE 53 HYDRODYNAMIC OIL FLOW VERSUS UNIT LOADING 311 O. D. x 16-172" 1. D. Bearing Pad Dimensions and Data per Table 10 (Ahead Bearing DD 933) 320 RPM 1000 1200

UNIT LOADING PSI

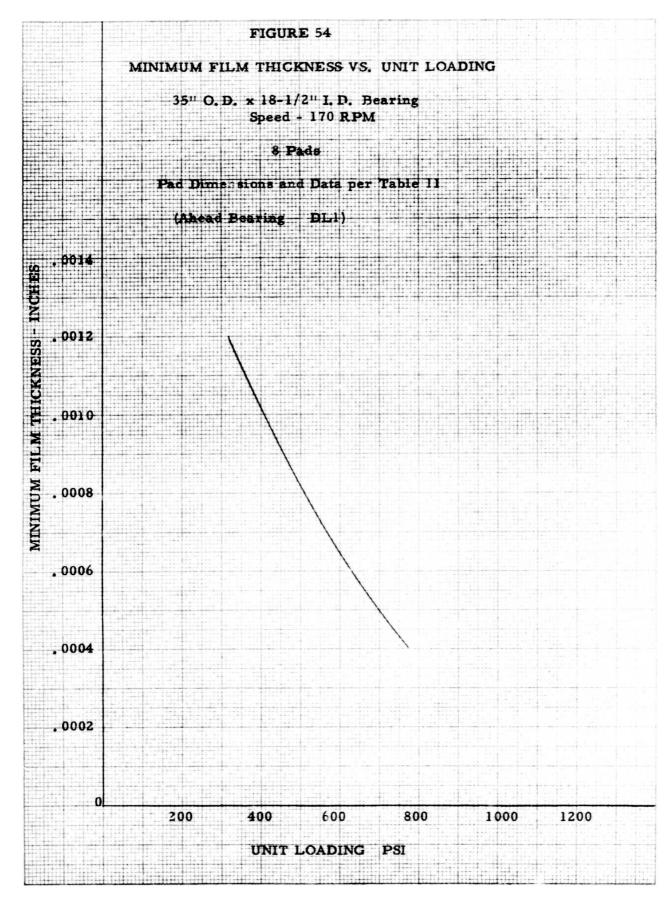
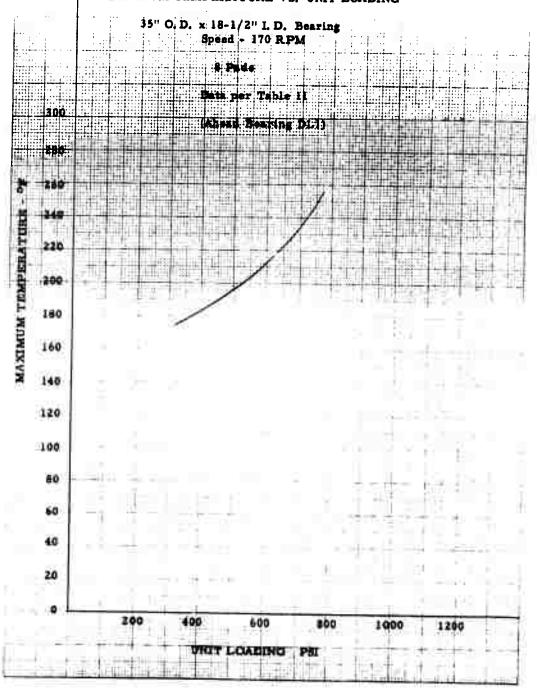


FIGURE 55
MAXIMUM TEMPERATURE VS. UNIT LOADING



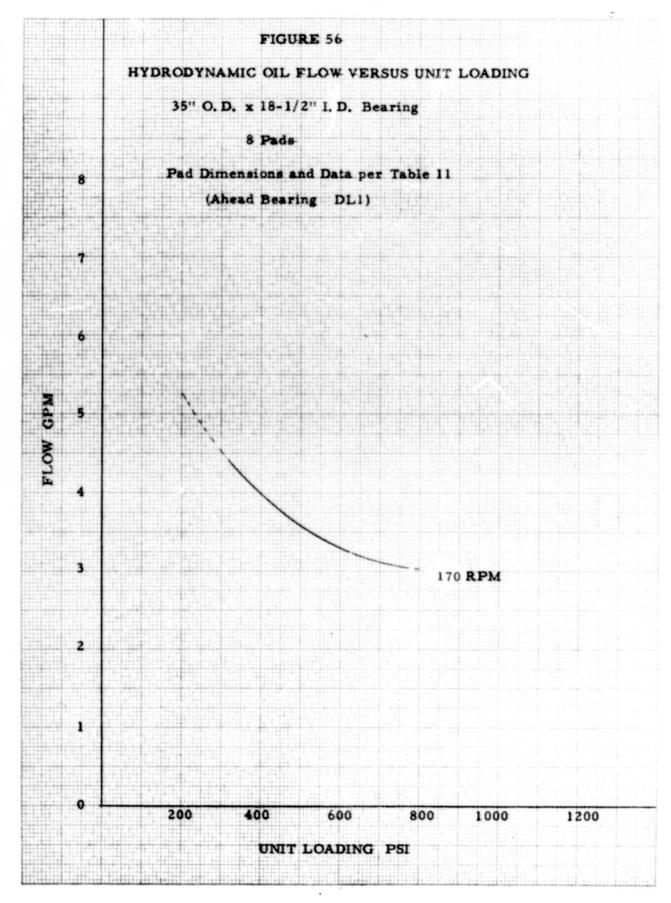
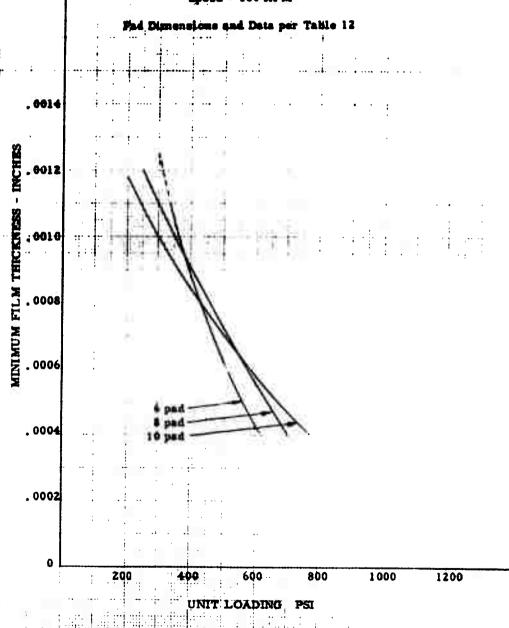
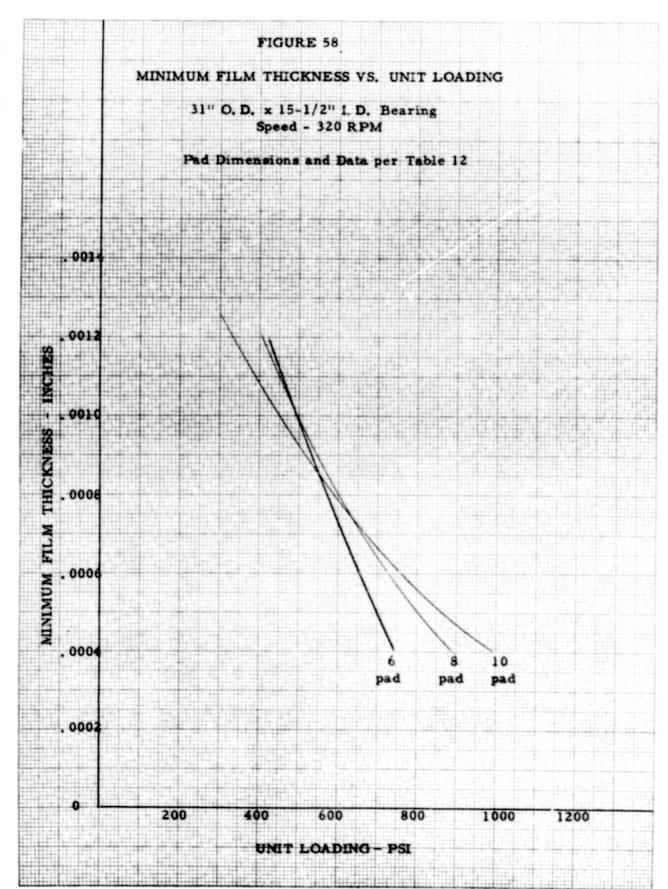


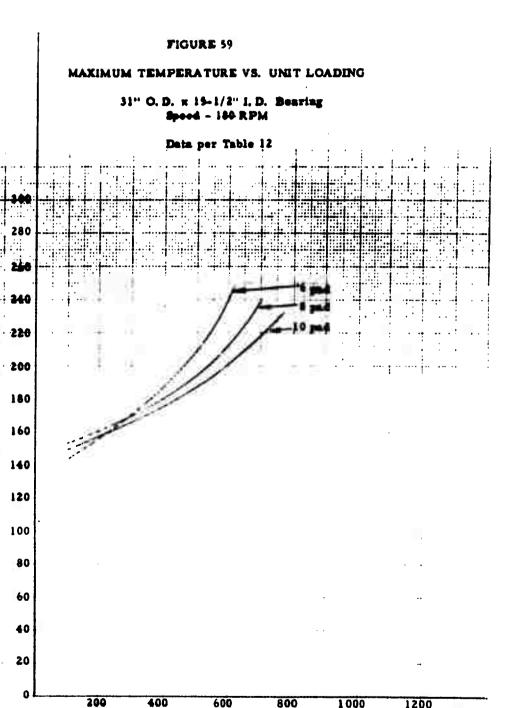
FIGURE 57
MINIMUM FILM THICKNESS VS. UNIT LOADING

31" O.D. x 15-1/2" 1.D. Bearing.

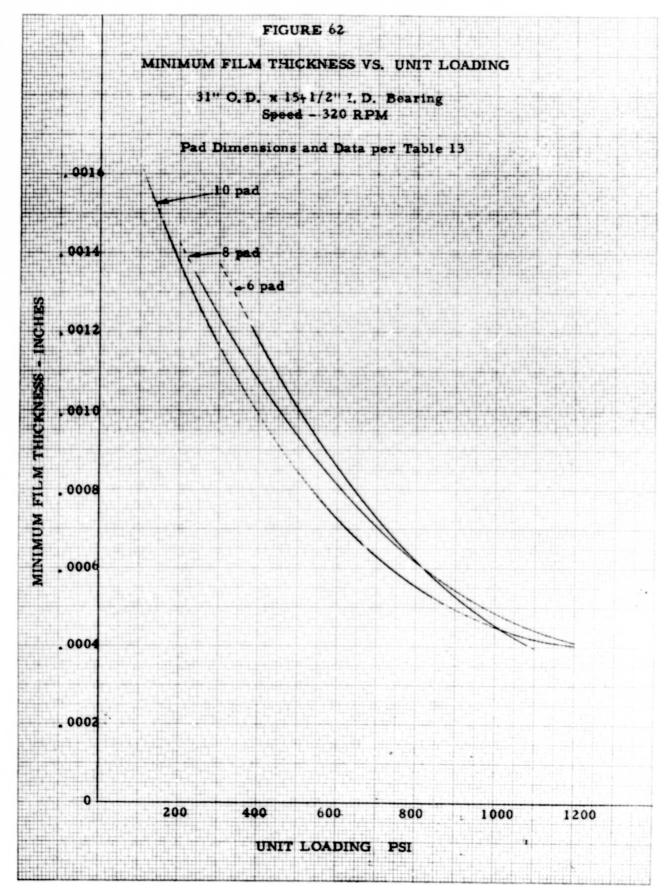




MAXIMUM TEMPERATURE



UNIT LOADING PSI



MAXIMUM TEMPERATURE VS. UNIT LOADING

FIGURE 63

31" O.D. x 15-1/2" I.D. Bearing Secod - 180 RPM

Data per Table 13

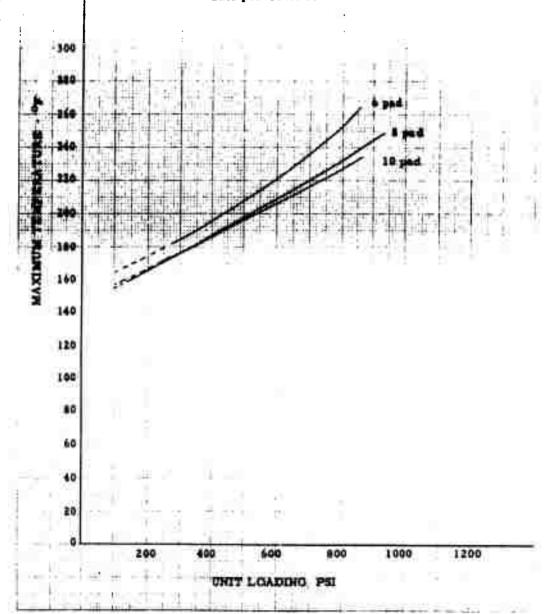
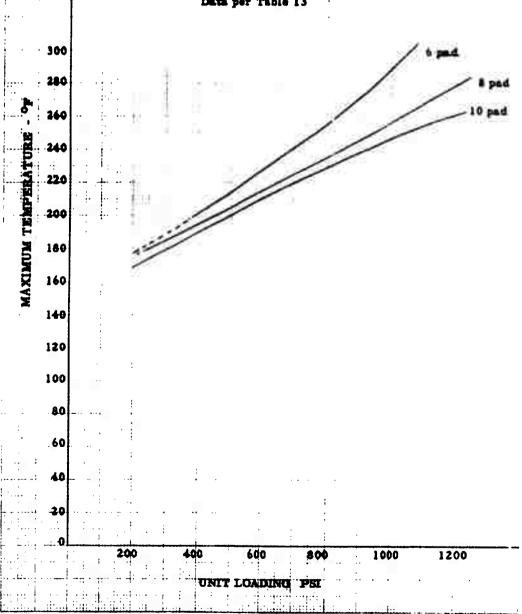
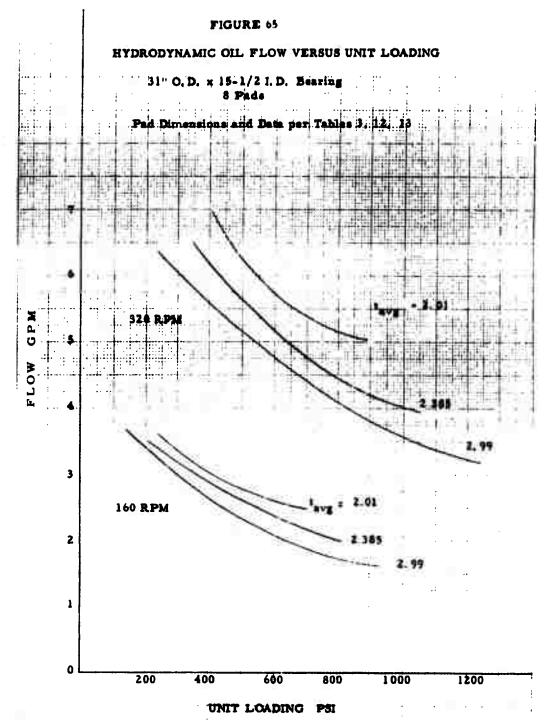


FIGURE 64
MAXIMUM TEMPERATURE VS. UNIT LOADING

31" O. D. x 15-1/2" L.D. Bearing Speed - 320 RPM

Data per Table 13





0014

0012

. 0008

. 0006

. 0004

, 0002

MINIMUM FILM THICKNESS - INCHES

FIGURE 66

MINIMUM FILM THICKNESS VS. UNIT LOADING

31" O. D. x 15-1/2" I. D. Bearing Speed - 180 RPM

Pad Dimensions and Data per Table 14

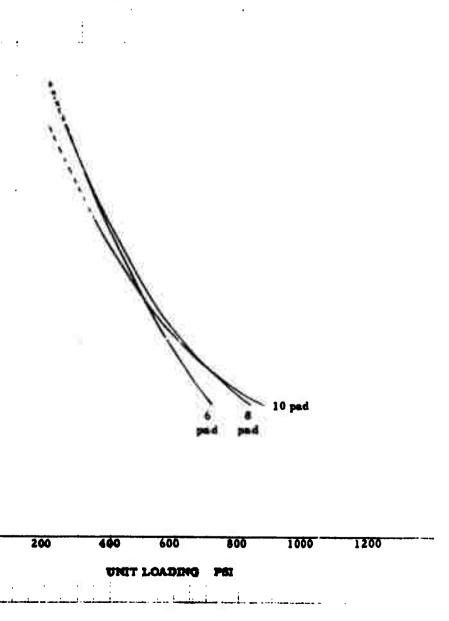
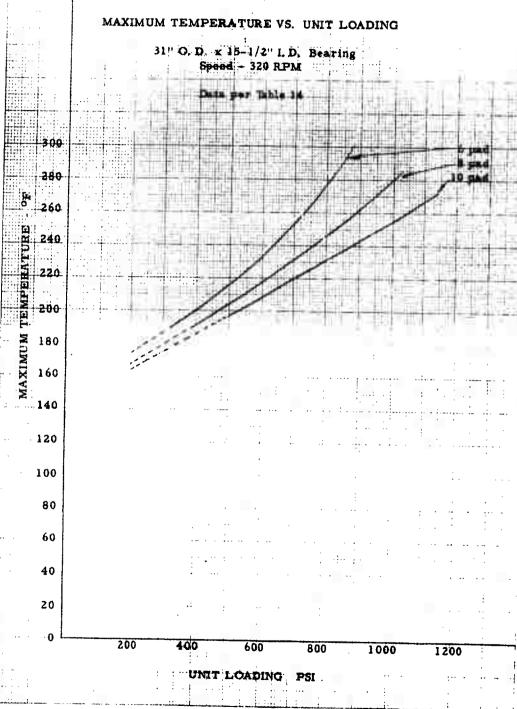
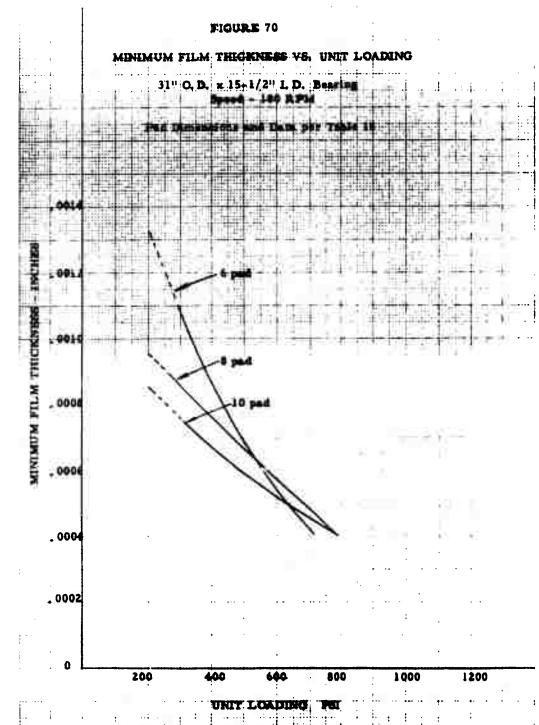


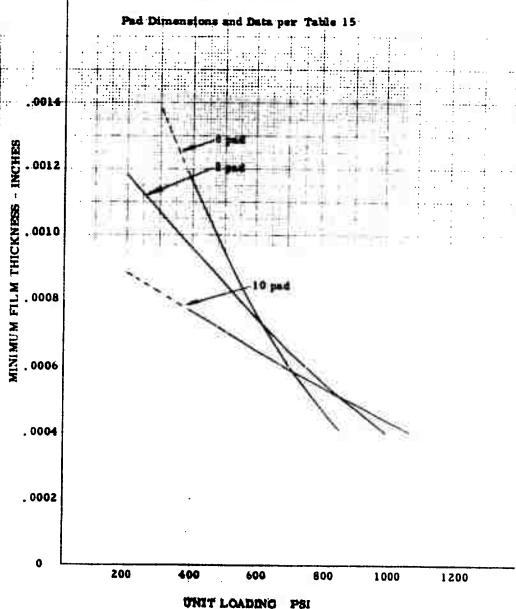
FIGURE 67 MINIMUM FILM THICKNESS VS. UNIT LOADING 31" O. D. x 15-1/2" L. D. Bearing Speed - 320 RPM 200 1200

FIGURE 69





. (9:



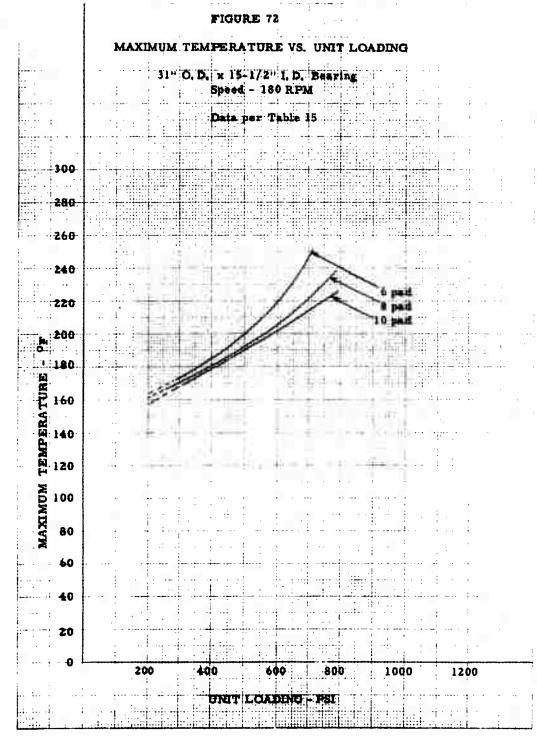


FIGURE 73

MAXIMUM TEMPERATURE VS. UNIT LOADING

31" O.D. x 15-1/2" I.D. Bearing Speed - 320 RPM

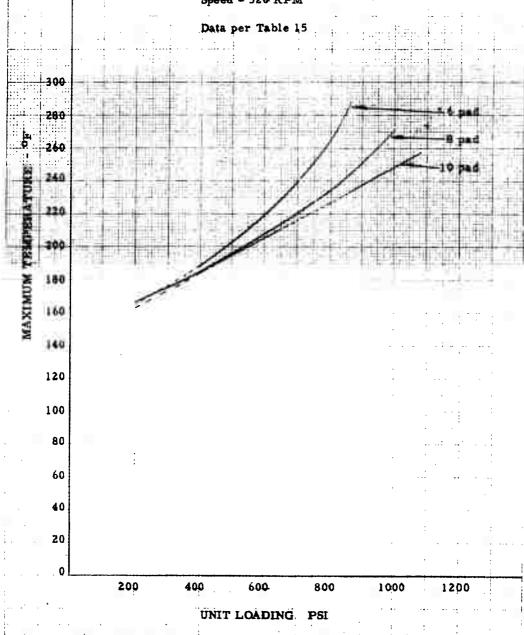


FIGURE 74

HYDRODYNAMIC OIL FLOW VERSUS UNIT LOADING

31" O. D. x 15-1/2" I. D. Bearing 8 Pads

Pad Dimensions and Data per Tables 3, 14 and 15

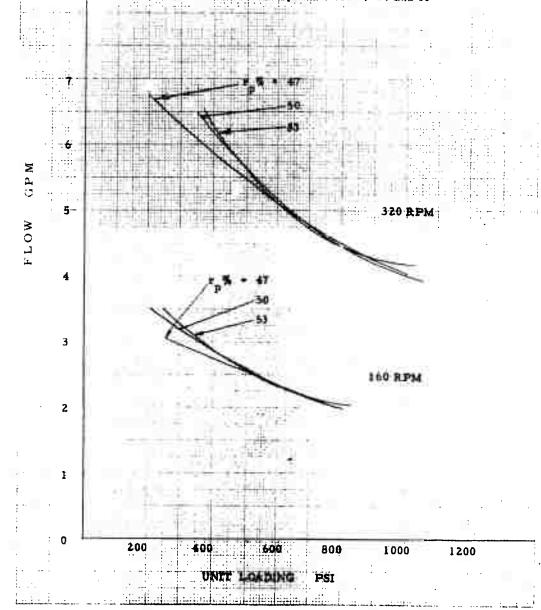


FIGURE 75

MINIMUM FILM THICKNESS-VS. UNIT LOADING

31" O. D. x 15-1/2" I. D. Bearing

350

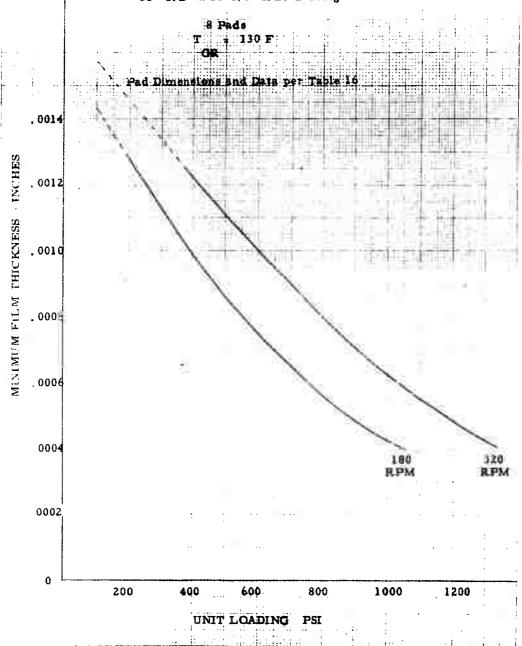
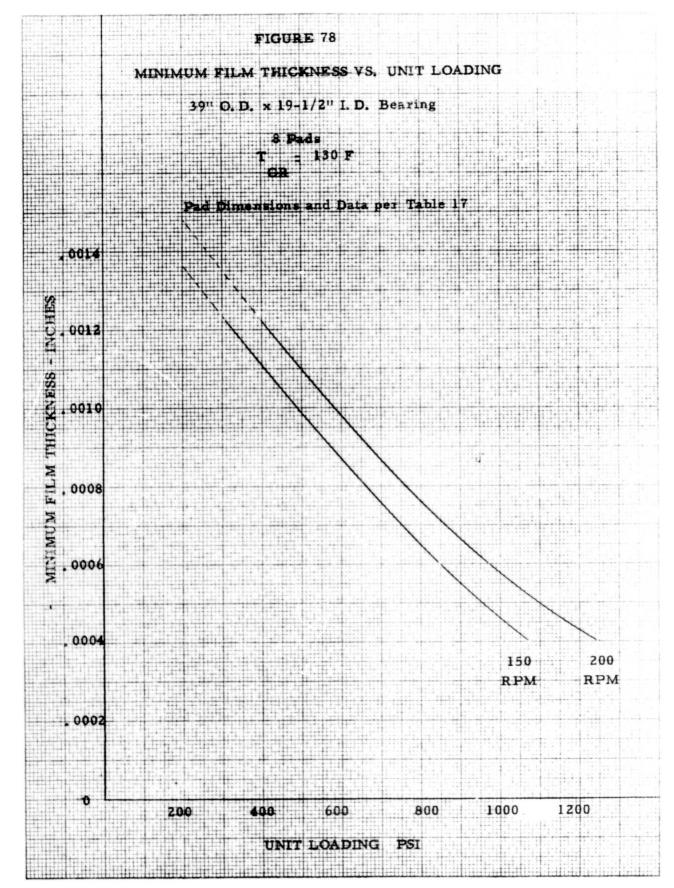
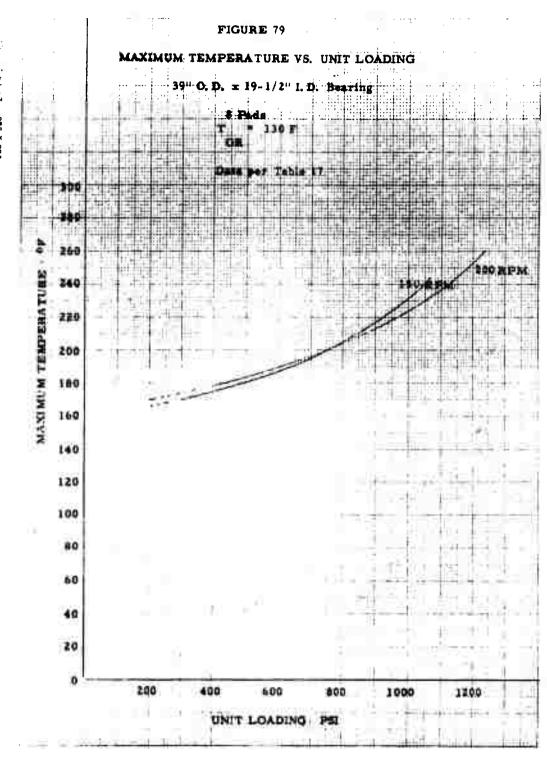
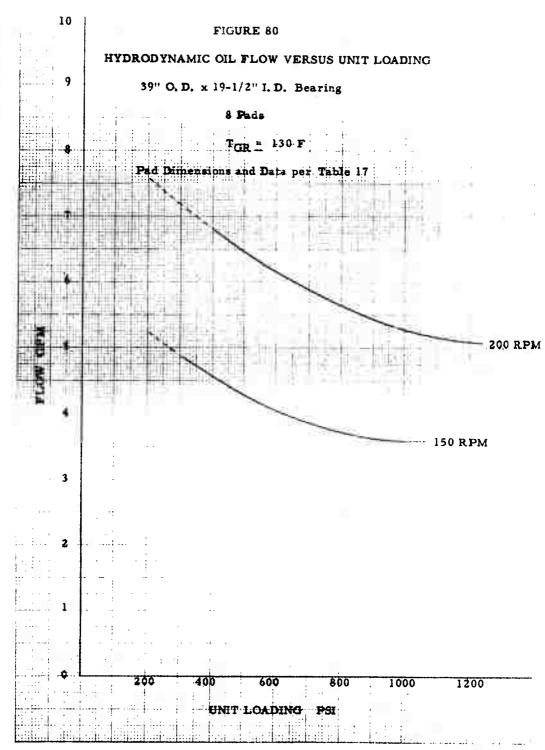
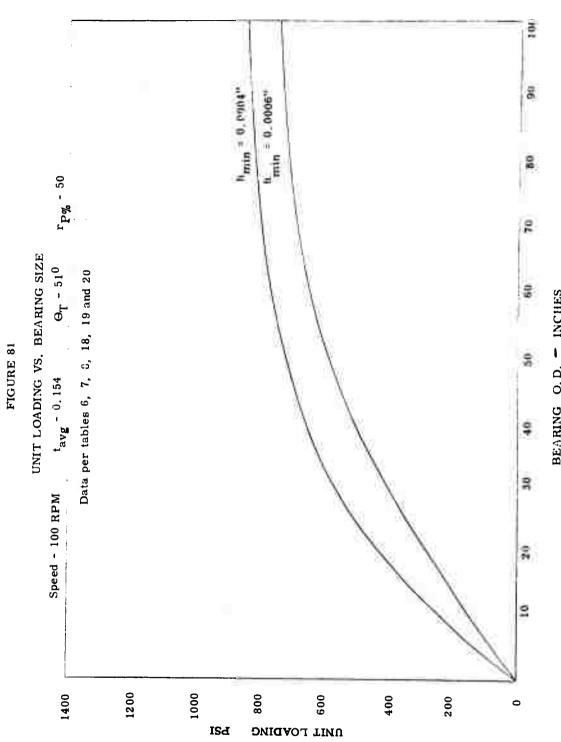


FIGURE 76 MAXIMUM TEMPERATURE VS. UNIT LOADING 31" O. D. x 15-1/2" I. D. Bearing MAXIMUM TEMPERATURE UNIT LOADING





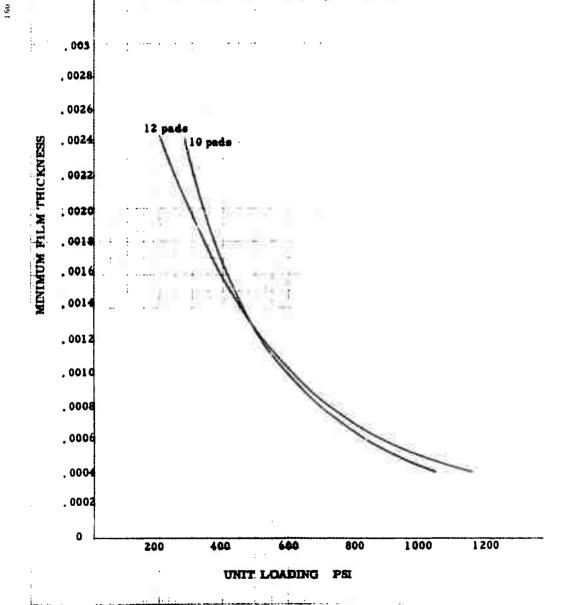




BEARING O.D. - INCHES

51-1/2" O. D x 32" I. D. Bearing Speed - 200 RPM

Pad Dimensions and Data per Table 22



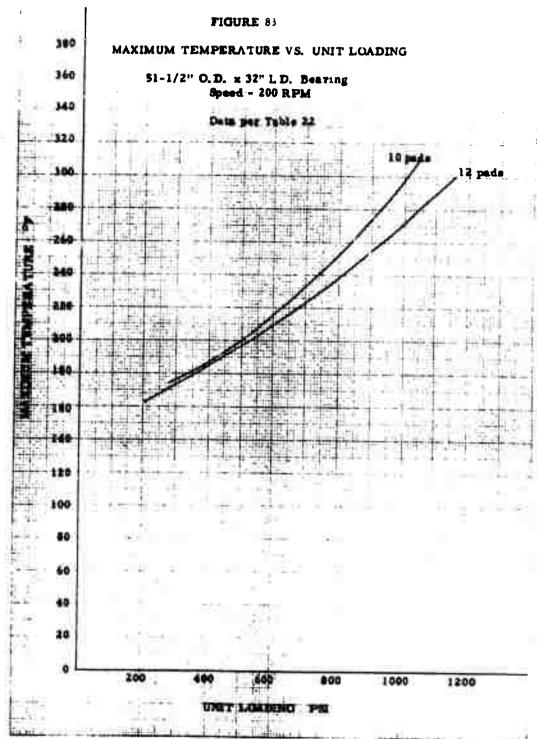
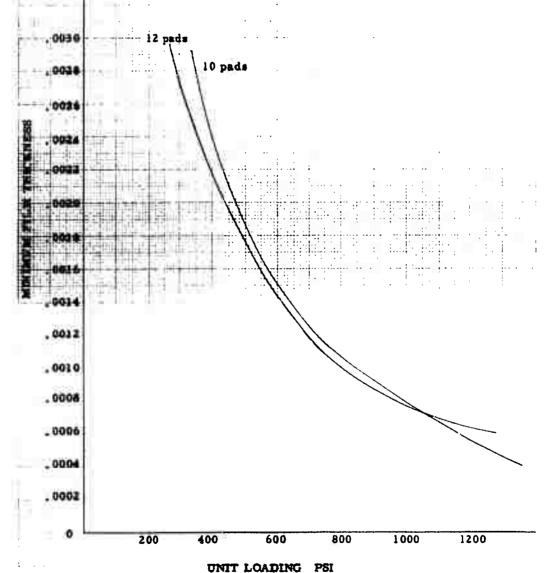


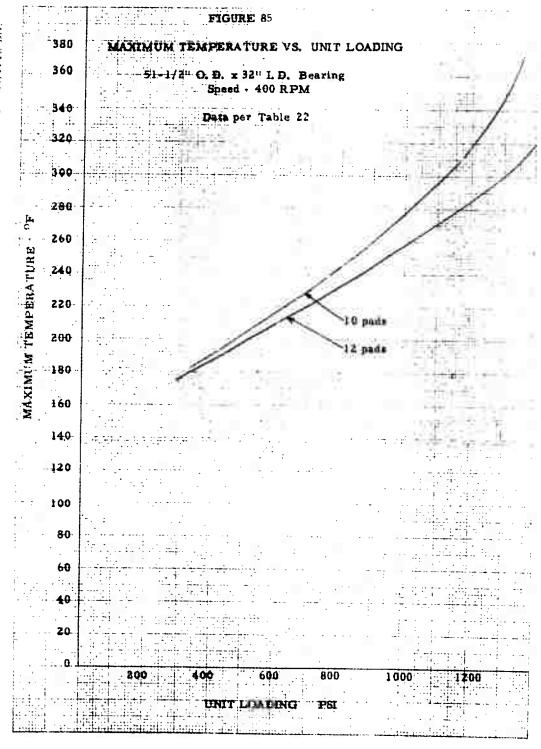
FIGURE 84

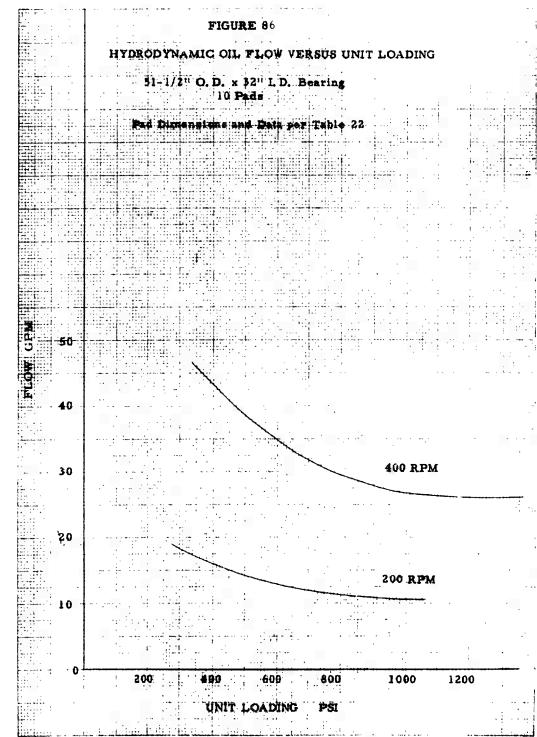
MINIMUM FILM THICKNESS VS. UNIT LOADING

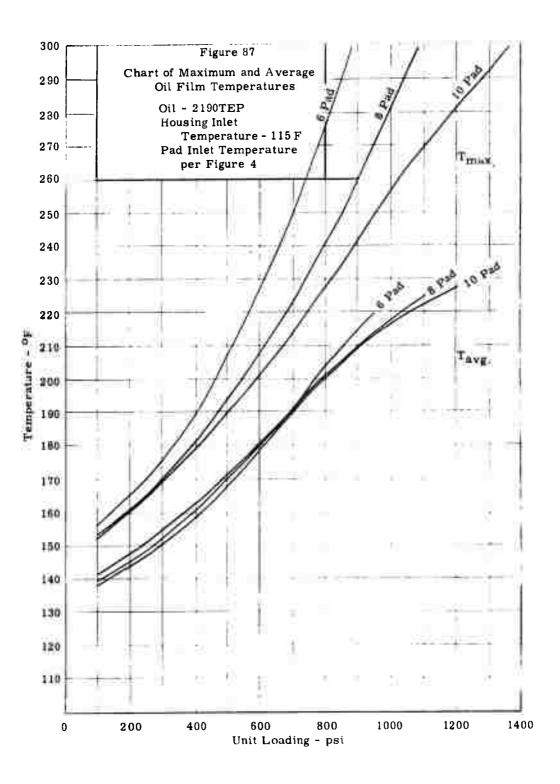
51-1/2" O.D. x 32" I.D. Bearing Speed - 400 RPM

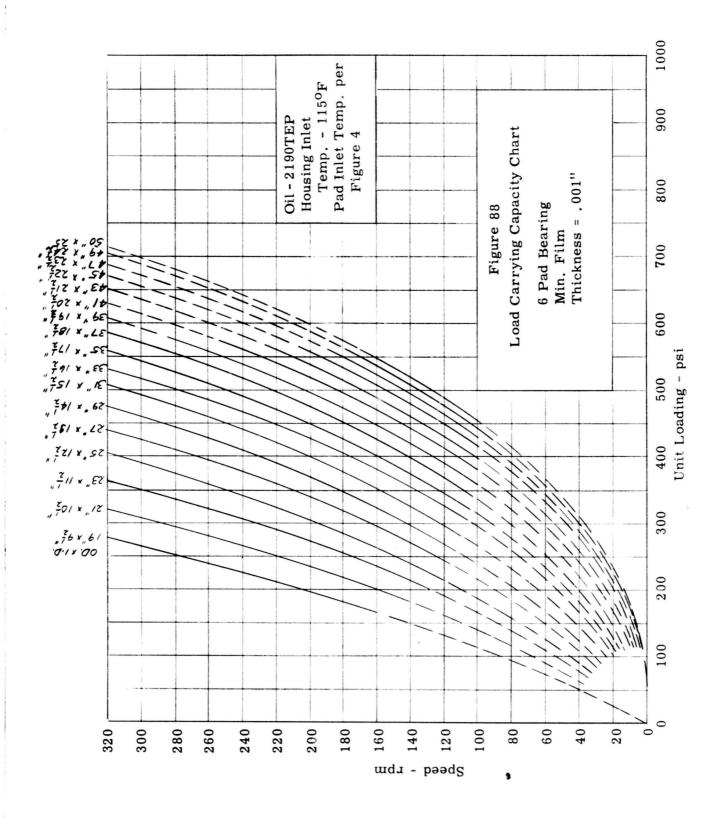
Pad Dimensions and Data per Table 22

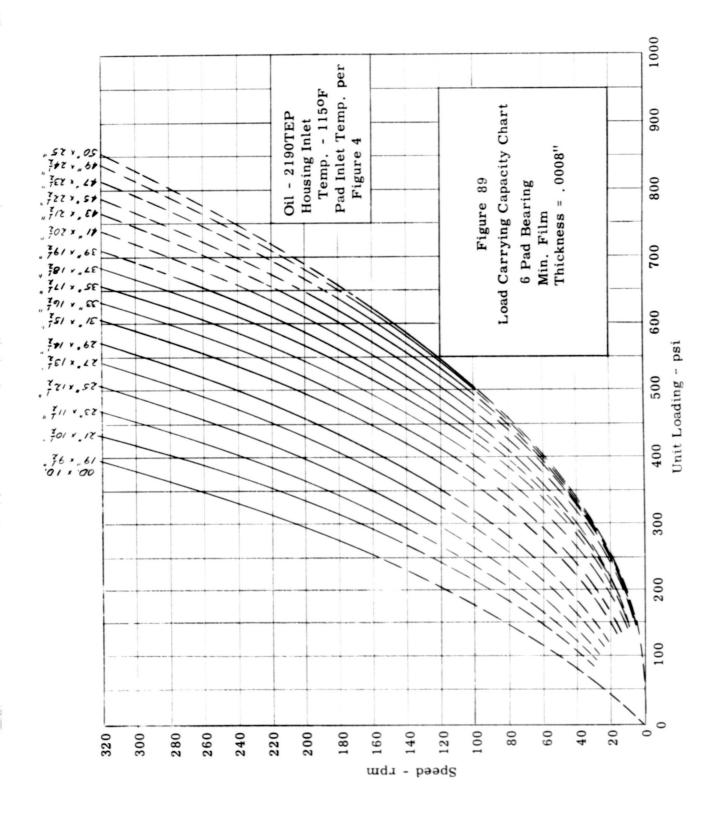


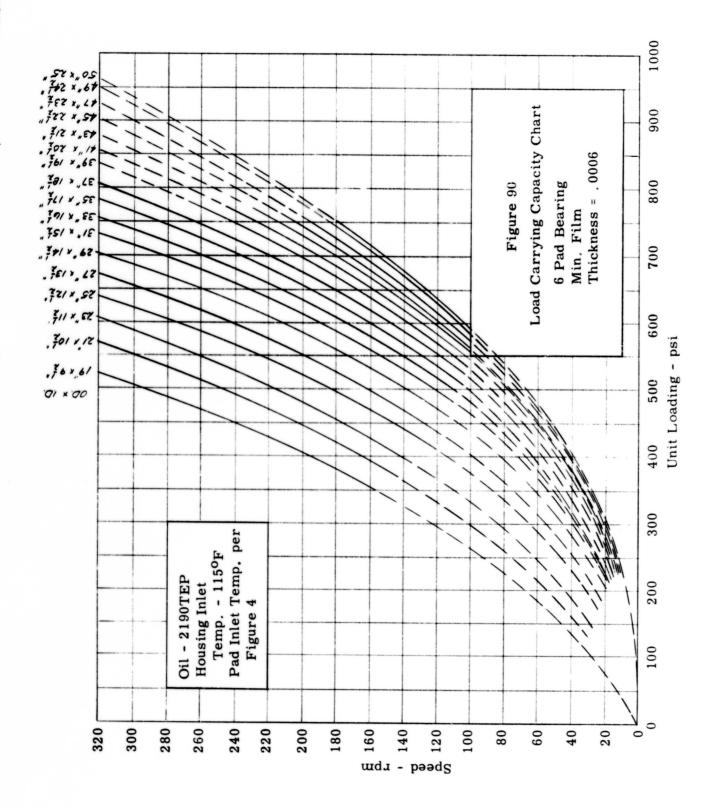


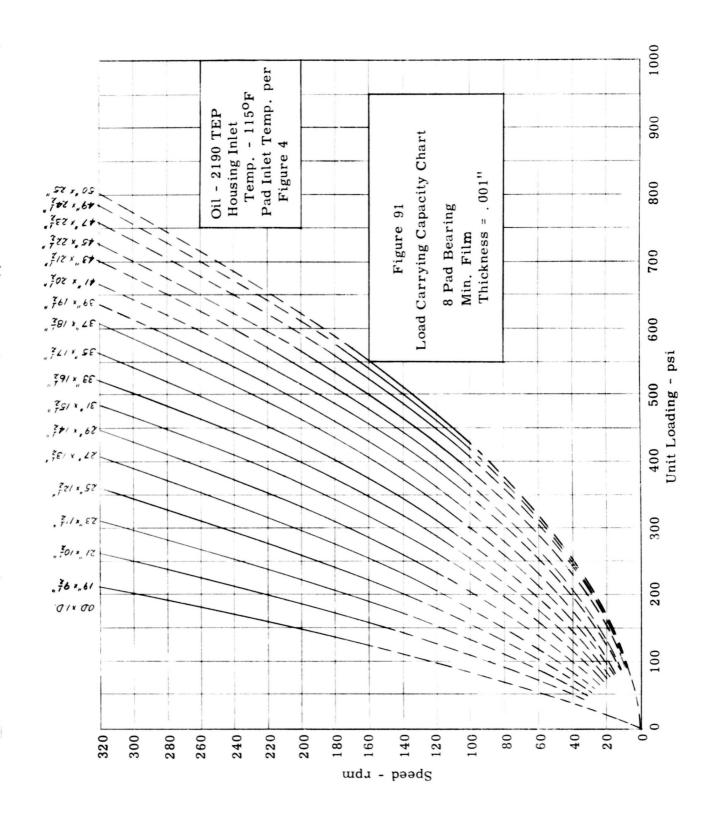


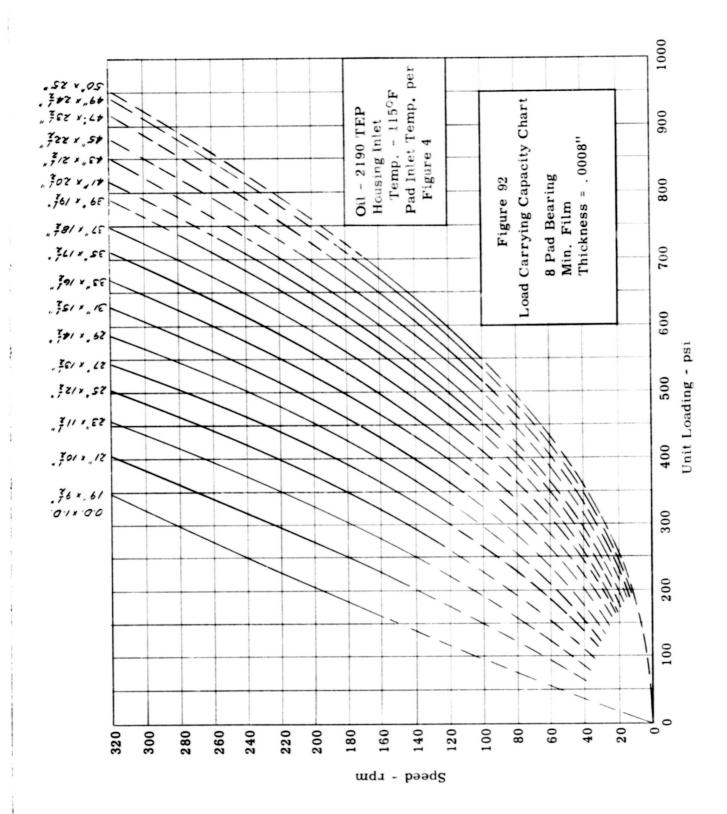


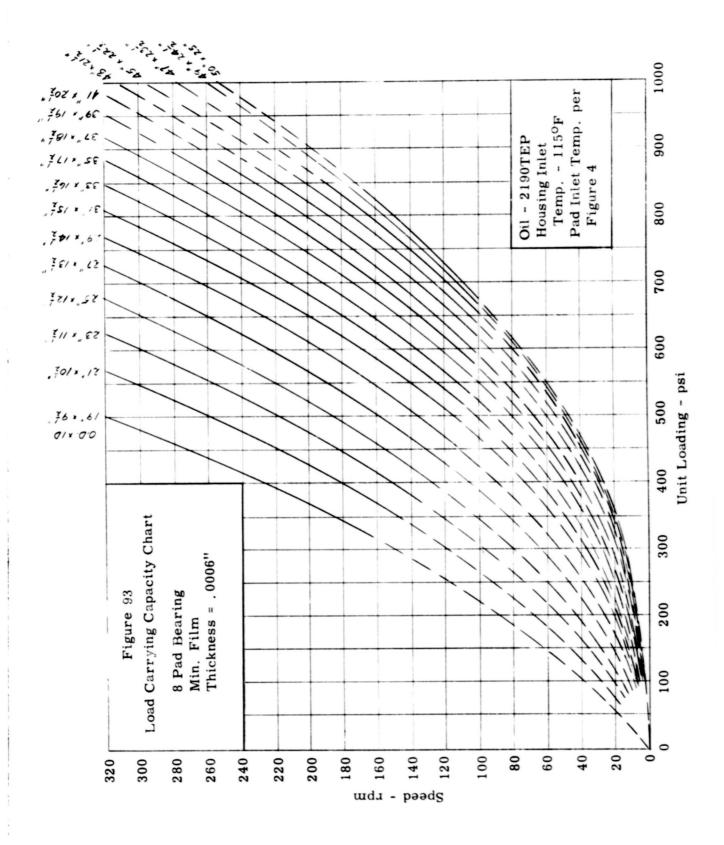


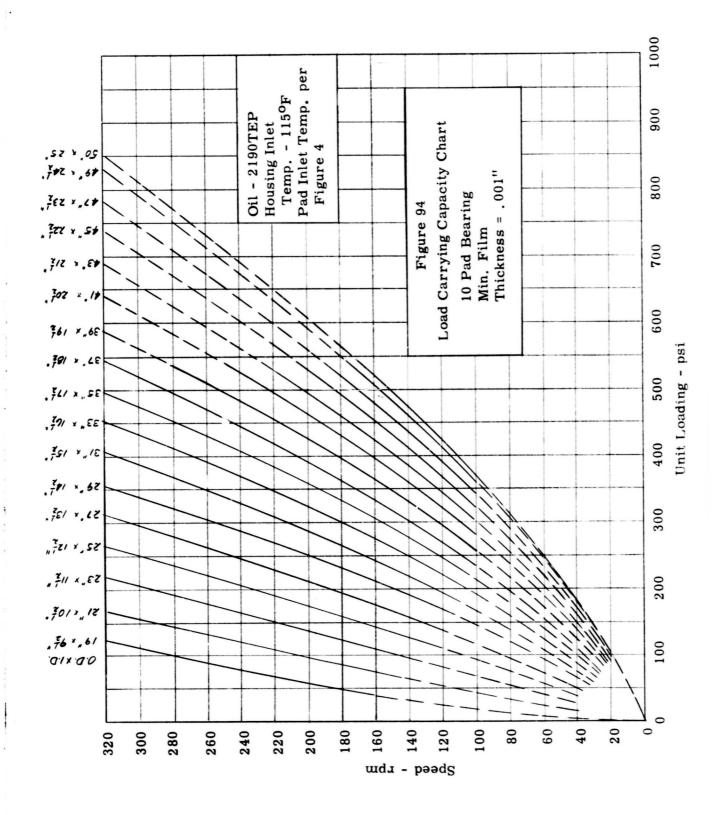


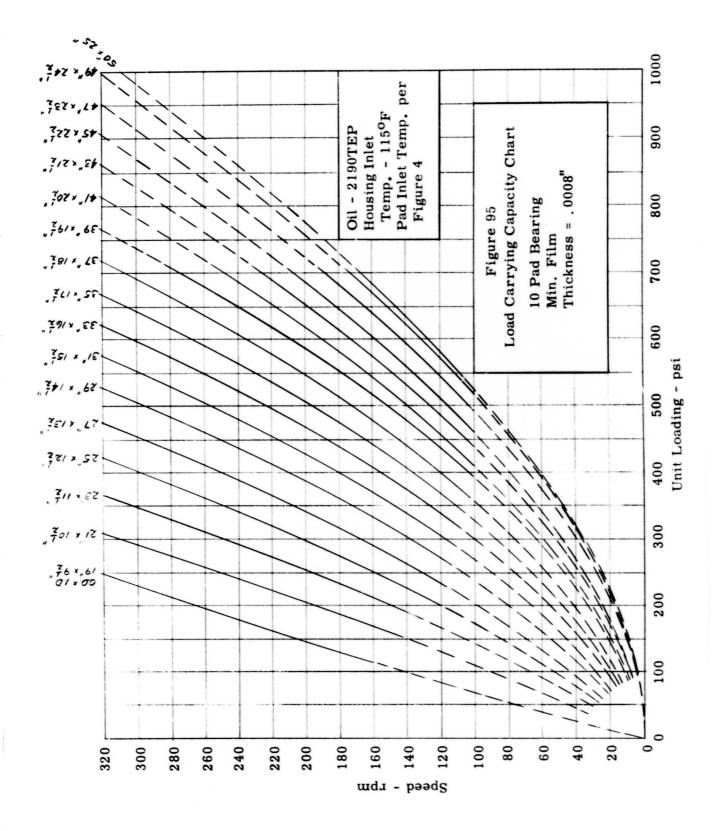


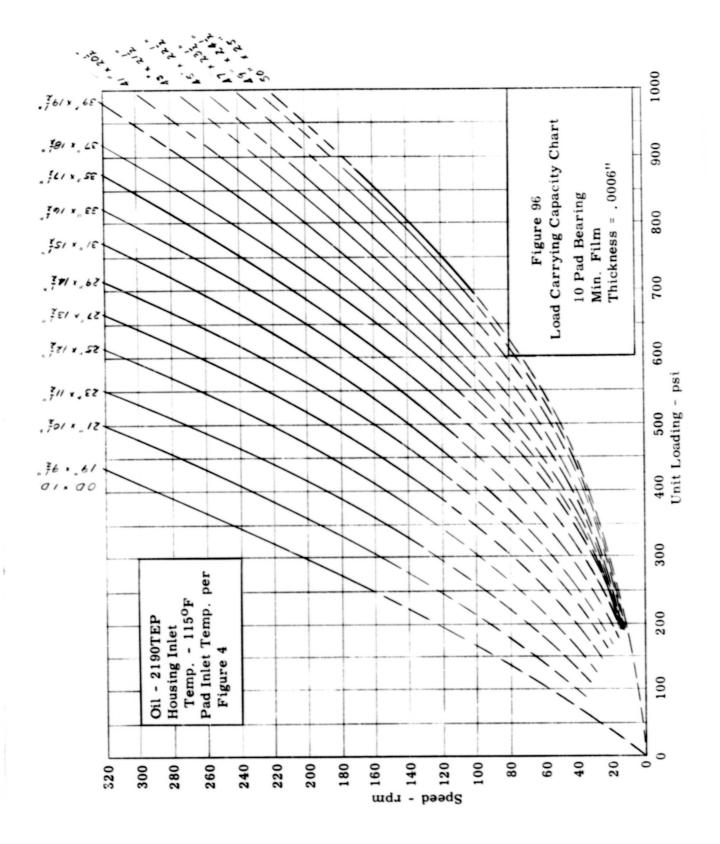












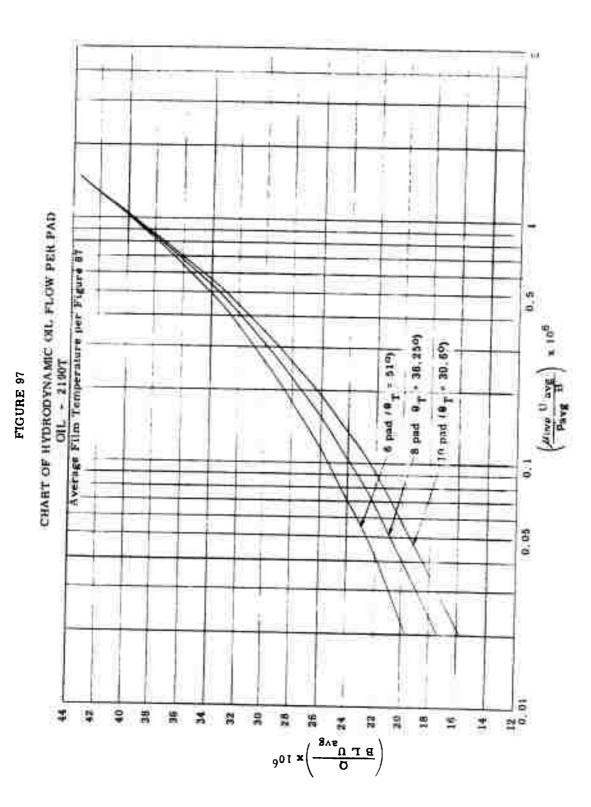


FIGURE 98
CHART OF HORSEPOWER LOSS PER PAD

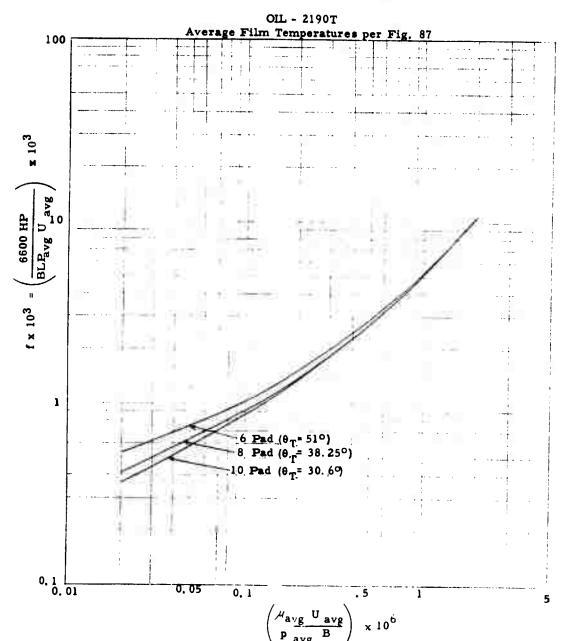


Figure 99
Location of Point of Minimum Film Thickness
31" OD x 15 1/2" ID Bearing At 320 RPM

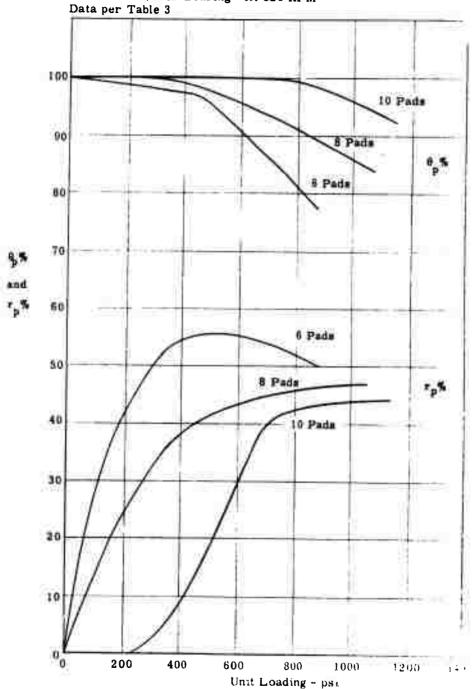
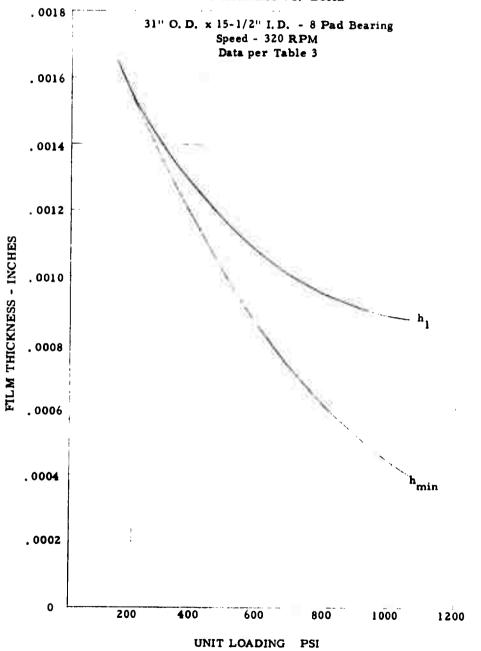
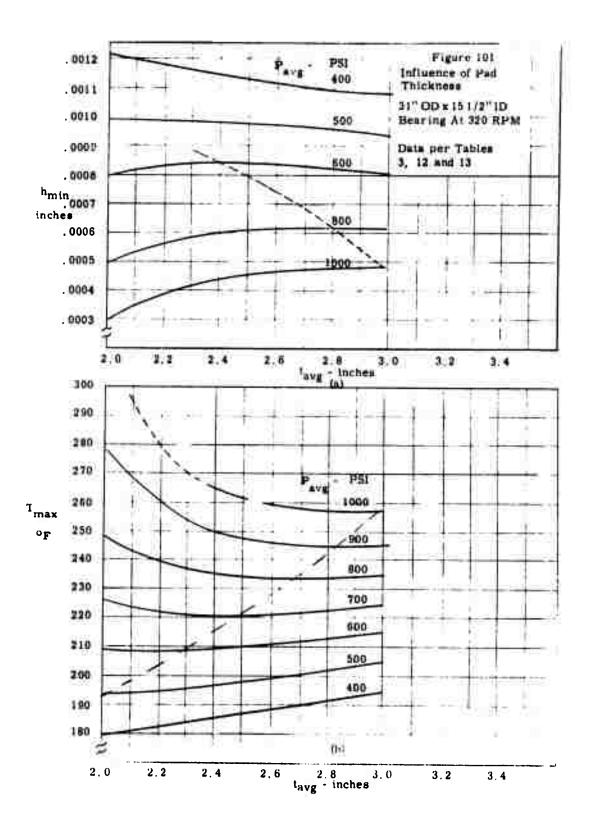


FIGURE 100

FILM THICKNESS VS. LOAD





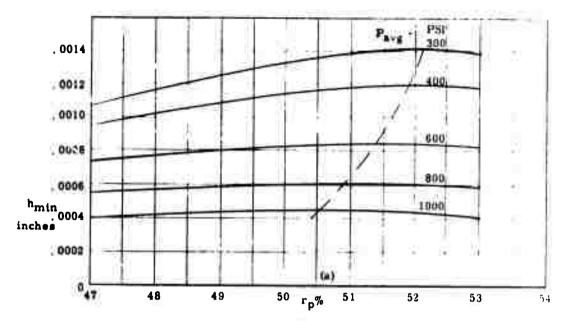
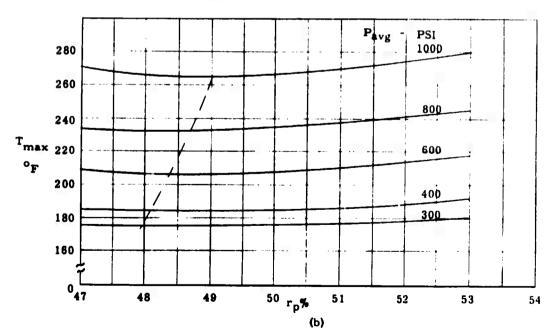
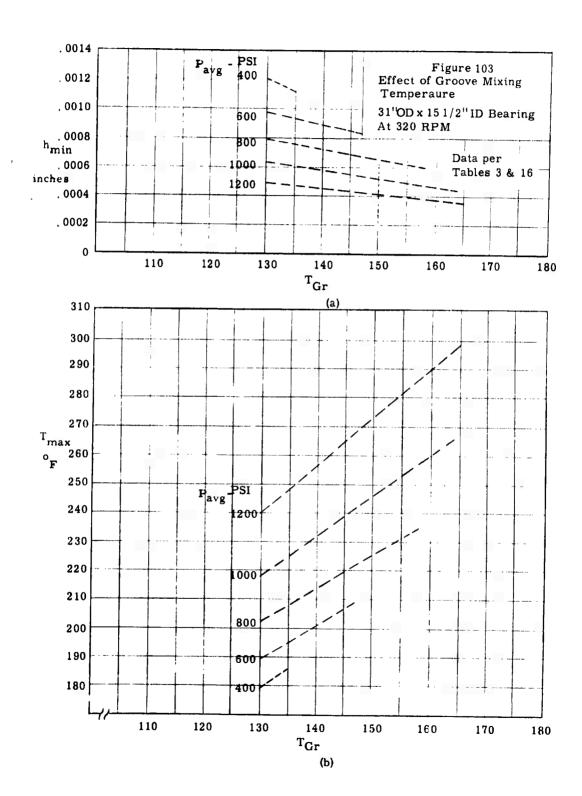


Figure 102
Influence of Radial Pivot Location
31" OD x 15 1/2" ID Bearing
At 320 RPM

Data per Tables 3, 14 and 15





-2.385 in. Thick Pad Centrally Pivoted Bending Included -Load and Max. Temp. per Fig. 2(c). -1|വ ----- Flat Pad Optimum 9 10 Pivot - Load and Max. Temp. per Fig. 2(a). Section 7-7 Section 6-6 31" OD x 15 1/2" ID Bearing ($\theta_{tot} = 38.25^{\circ}$) -1100 cole TGr = 130°F 2190T Oil 2 iaq - q - d 1200 1000 200 800 600 200 400 800 iaq hmin = 0.001" N = 320 rpm -۱۱۹ 20 e io Section 4-4 Section 5-5 7 1800 1600r 1600 1400 1200 - d 1400 1200 200 1000 1000 200 400 1000 800 909 400 9 iad - q 912-S Section 3-3 Section 2-2 Section 1-1 C1|17 0 1600 1400 1200 1000 1200 1000 - ч 400 P - pat 200 800 18q 200 400 900

COMPARISON OF PRESSURE PROFILES

FIGURE 104

SYMBOLS

```
Radius of equivalent circular plate
                                                                                                                                             inches
                  Average circumferential pad length [ • (R - L/2) 0,
                                                                                                                                             inches
  Cp
                  Specific heat of oil
                                                                                                                                             BTU/Ib. x OF
                  Coefficient of friction
 h
h<sub>1</sub>
h<sub>a</sub>
h<sub>min</sub>
                                                                                                                                             inches
                  Film thickness at inside radius of trailing edge
Film thickness at reference point (r_a, \theta_a)
Minimum film thickness
                                                                                                                                              inches
                                                                                                                                             inches
 HP Horsepower loss per pad
HPtot Total horsepower loss in bearing
HP2, 3, 4 Components of pad horsepower loss cerresponding to Q2, 3, 4
                                                                                                                                             H. P.
H. P.
H. P.
 J
                  Mechanical equivalent of thermal energy (= 9339 in. lbs./BTU)
                 Ratio of effective pad area to total available area ( - Area of pads Area of pads + Area of grooves
                  (Also used as subscript to denote number of iterations.)
                 Bending coefficient
                                                                                                                                            inches-
 L
                 Radial length of pad
                                                                                                                                             inches
                 Tangential pad inclination
Radial pad inclination
                                                                                                                                             radiane
                 Number of pads in the bearing (Also used as subscript to denote outermost mesh in radial direction.)
 N
                 Angular speed
                                                                                                                                            R. P. S.
                 Pressure
                                                                                                                                           pei
pei
pei
                 Average pressure (unit loading)
Maximum pressure
Pave
                Hydrodynamic flow per pad
Edge flow (see Figure 3)
Hydrodynamic flow per bearing
                                                                                                                                           G. P. M.
G. P. M.
G. P. M.
                                                                                                                                           inches
inches
inches
inches
inches
inches
                 radial co-ordinate
               radial co-ordinate radial co-ordinate of reference point radial co-ordinate of center of pressure radial co-ordinate of center of pressure for 100 [r<sub>cp</sub>-(R-L)]/L] radial co-ordinate of point of minimum film thickness radial co-ordinate of pivot { * 100 [r<sub>p</sub>-(R-L)]/L}
cp
cp
m
                                                                                                                                            inches
R
R
                Outer radius of pad
Radius of curvature of bent pad
                                                                                                                                           inches
avg
                Average pad thickness
                                                                                                                                            inche
                Temperature
                Average pad temperature
Groove mixing temperature
Maximum film temperature
Tave
TGR
                Average surface speed [ = 2 m (R-L/2) N]
Uave
                                                                                                                                           inches/sec.
                Load per pad
Total bearing load
                                                                                                                                           lbe.
Wtot
                                                                                                                                           inches
              co-ordinates of reference point
(xa. ya)
                                                                                                                                            inches
                Bending deflection
                                                                                                                                           inches
Δ
                Increment
                Angular co-ordinate
                                                                                                                                           radiane
                Angular co-ordinate of center of pressure
Angular co-ordinate of center of pressure = 100 (e_c/s_T)
Angular co-ordinate of point of minimum film thickness
Angular co-ordinate of pivot
                                                                                                                                            radians
                                                                                                                                            radiane
                Angular co-ordinate of pivot . 100 (8 8T)
•
                Angular extent of pad
                                                                                                                                            radiane
f
                Mass density of oil
                                                                                                                                            lb. sec2/in4
                Absolute viscosity of oil
Absolute viscosity of oil at TGR
Absolute viscosity of oil at Tavg
#GR
Have
                                                                                                                                            lbe sec. in.2
                                                                                                                                           1b. sec. /in. 2
1b. sec. /in. 2
                Angular velocity
```

SUBSCRIPTS

- Defines value of r in the thrust bearing pad mesh, running from 1 to n
- Defines value of 8 in the thrust bearing pad mesh, running from 1 to m
- k Iteration number